# Statistics Toolbox

**For Use with MATLAB®**

Computation

Visualization

Programming

The MATH WORKS Inc.

User's Guide

*Version 3*

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# Preface

# Overview

This chapter introduces the Statistics Toolbox, and explains how to use the documentation. It contains the following sections:

- "What Is the Statistics Toolbox?"
- "How to Use This Guide"
- "Related Products List"
- "Mathematical Notation"
- "Typographical Conventions"

# What Is the Statistics Toolbox?

The Statistics Toolbox is a collection of tools built on the MATLAB® numeric computing environment. The toolbox supports a wide range of common statistical tasks, from random number generation, to curve fitting, to design of experiments and statistical process control. The toolbox provides two categories of tools:

- Building-block probability and statistics functions
- Graphical, interactive tools

The first category of tools is made up of functions that you can call from the command line or from your own applications. Many of these functions are MATLAB M-files, series of MATLAB statements that implement specialized statistics algorithms. You can view the MATLAB code for these functions using the statement

```
type function_name
```

You can change the way any toolbox function works by copying and renaming the M-file, then modifying your copy. You can also extend the toolbox by adding your own M-files.

Secondly, the toolbox provides a number of interactive tools that let you access many of the functions through a graphical user interface (GUI). Together, the GUI-based tools provide an environment for polynomial fitting and prediction, as well as probability function exploration.

# How to Use This Guide

**If you are a new user** begin with Chapter 1, "Tutorial." This chapter introduces the MATLAB statistics environment through the toolbox functions. It describes the functions with regard to particular areas of interest, such as probability distributions, linear and nonlinear models, principal components analysis, design of experiments, statistical process control, and descriptive statistics.

**All toolbox users** should use Chapter 2, "Reference," for information about specific tools. For functions, reference descriptions include a synopsis of the function's syntax, as well as a complete explanation of options and operation. Many reference descriptions also include examples, a description of the function's algorithm, and references to additional reading material.

Use this guide in conjunction with the software to learn about the powerful features that MATLAB provides. Each chapter provides numerous examples that apply the toolbox to representative statistical tasks.

The random number generation functions for various probability distributions are based on all the primitive functions, randn and rand. There are many examples that start by generating data using random numbers. To duplicate the results in these examples, first execute the commands below.

```
seed = 931316785;
rand('seed', seed);
randn('seed', seed);
```

You might want to save these commands in an M-file script called init.m. Then, instead of three separate commands, you need only type init.

# Related Products List

The MathWorks provides several products that are especially relevant to the kinds of tasks you can perform with the Statistics Toolbox.

For more information about any of these products, see either:

- The online documentation for that product if it is installed or if you are reading the documentation from the CD
- The MathWorks Web site, at `http://www.mathworks.com`; see the "products" section

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**Note**  The toolboxes listed below all include functions that extend MATLAB's capabilities. The blocksets all include blocks that extend Simulink's capabilities.

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| Product | Description |
|---|---|
| Data Acquisition Toolbox | MATLAB functions for direct access to live, measured data from MATLAB |
| Database Toolbox | Tool for connecting to, and interacting with, most ODBC/JDBC databases from within MATLAB |
| Financial Time Series Toolbox | Tool for analyzing time series data in the financial markets |
| GARCH Toolbox | MATLAB functions for univariate Generalized Autoregressive Conditional Heteroskedasticity (GARCH) volatility modeling |
| Image Processing Toolbox | Complete suite of digital image processing and analysis tools for MATLAB |
| Mapping Toolbox | Tool for analyzing and displaying geographically based information from within MATLAB |

| Product | Description |
|---|---|
| Neural Network Toolbox | Comprehensive environment for neural network research, design, and simulation within MATLAB |
| Optimization Toolbox | Tool for general and large-scale optimization of nonlinear problems, as well as for linear programming, quadratic programming, nonlinear least squares, and solving nonlinear equations |
| Signal Processing Toolbox | Tool for algorithm development, signal and linear system analysis, and time-series data modeling |
| System Identification Toolbox | Tool for building accurate, simplified models of complex systems from noisy time-series data |

# Mathematical Notation

This manual and the Statistics Toolbox functions use the following mathematical notation conventions.

| | |
|---|---|
| β | Parameters in a linear model. |
| $E(x)$ | Expected value of $x$.  $E(x) = \int tf(t)\,dt$ |
| $f(x/a,b)$ | Probability density function. $x$ is the independent variable; $a$ and $b$ are fixed parameters. |
| $F(x/a,b)$ | Cumulative distribution function. |
| $I([a, b])$ or $I_{[a, b]}$ | Indicator function. In this example the function takes the value 1 on the closed interval from $a$ to $b$ and is 0 elsewhere. |
| $p$ and $q$ | $p$ is the probability of some event. <br> $q$ is the probability of $\sim p$, so $q = 1-p$. |

# Typographical Conventions

This manual uses some or all of these conventions.

| Item | Convention to Use | Example |
|------|-------------------|---------|
| Example code | Monospace font | To assign the value 5 to A, enter<br><br>`A = 5` |
| Function names/syntax | Monospace font | The `cos` function finds the cosine of each array element.<br><br>Syntax line example is<br><br>`MLGetVar ML_var_name` |
| Keys | **Boldface** with an initial capital letter | Press the **Return** key. |
| Literal strings (in syntax descriptions in reference chapters) | **Monospace bold** for literals | `f = freqspace(n, '`**`whole`**`')` |
| Mathematical expressions | *Italics* for variables<br><br>Standard text font for functions, operators, and constants | This vector represents the polynomial<br><br>$p = x^2 + 2x + 3$ |
| MATLAB output | Monospace font | MATLAB responds with<br><br>`A =`<br>`     5` |
| Menu names, menu items, and controls | **Boldface** with an initial capital letter | Choose the **File** menu. |
| New terms | *Italics* | An *array* is an ordered collection of information. |
| String variables (from a finite list) | *Monospace italics* | `sysc = d2c(sysd, '`*`method`*`')` |

**1**

# Tutorial

# Introduction

The Statistics Toolbox, for use with MATLAB, supplies basic statistics capability on the level of a first course in engineering or scientific statistics. The statistics functions it provides are building blocks suitable for use inside other analytical tools.

## Primary Topic Areas

The Statistics Toolbox has more than 200 M-files, supporting work in the topical areas below:

- Probability distributions
- Descriptive statistics
- Cluster analysis
- Linear models
- Nonlinear models
- Hypothesis tests
- Multivariate statistics
- Statistical plots
- Statistical process control
- Design of experiments

### Probability Distributions

The Statistics Toolbox supports 20 probability distributions. For each distribution there are five associated functions. They are:

- Probability density function (pdf)
- Cumulative distribution function (cdf)
- Inverse of the cumulative distribution function
- Random number generator
- Mean and variance as a function of the parameters

For data-driven distributions (beta, binomial, exponential, gamma, normal, Poisson, uniform, and Weibull), the Statistics Toolbox has functions for computing parameter estimates and confidence intervals.

### Descriptive Statistics

The Statistics Toolbox provides functions for describing the features of a data sample. These descriptive statistics include measures of location and spread, percentile estimates and functions for dealing with data having missing values.

### Cluster Analysis

The Statistics Toolbox provides functions that allow you to divide a set of objects into subgroups, each having members that are as much alike as possible. This process is called *cluster analysis*.

### Linear Models

In the area of linear models, the Statistics Toolbox supports one-way, two-way, and higher-way analysis of variance (ANOVA), analysis of covariance (ANOCOVA), multiple linear regression, stepwise regression, response surface prediction, ridge regression, and one-way multivariate analysis of variance (MANOVA). It supports nonparametric versions of one- and two-way ANOVA. It also supports multiple comparisons of the estimates produced by ANOVA and ANOCOVA functions.

### Nonlinear Models

For nonlinear models, the Statistics Toolbox provides functions for parameter estimation, interactive prediction and visualization of multidimensional nonlinear fits, and confidence intervals for parameters and predicted values.

### Hypothesis Tests

The Statistics Toolbox also provides functions that do the most common tests of hypothesis – t-tests, Z-tests, nonparametric tests, and distribution tests.

### Multivariate Statistics

The Statistics Toolbox supports methods in multivariate statistics, including principal components analysis, linear discriminant analysis, and one-way multivariate analysis of variance.

### Statistical Plots

The Statistics Toolbox adds box plots, normal probability plots, Weibull probability plots, control charts, and quantile-quantile plots to the arsenal of graphs in MATLAB. There is also extended support for polynomial curve fitting and prediction. There are functions to create scatter plots or matrices of scatter plots for grouped data, and to identify points interactively on such plots. There is a function to interactively explore a fitted regression model.

### Statistical Process Control (SPC)

For SPC, the Statistics Toolbox provides functions for plotting common control charts and performing process capability studies.

### Design of Experiments (DOE)

The Statistics Toolbox supports full and fractional factorial designs and D-optimal designs. There are functions for generating designs, augmenting designs, and optimally assigning units with fixed covariates.

# Probability Distributions

Probability distributions arise from experiments where the outcome is subject to chance. The nature of the experiment dictates which probability distributions may be appropriate for modeling the resulting random outcomes. There are two types of probability distributions – *continuous* and *discrete*.

| Continuous (data) | Continuous (statistics) | Discrete |
|---|---|---|
| Beta | Chi-square | Binomial |
| Exponential | Noncentral Chi-square | Discrete Uniform |
| Gamma | F | Geometric |
| Lognormal | Noncentral F | Hypergeometric |
| Normal | t | Negative Binomial |
| Rayleigh | Noncentral t | Poisson |
| Uniform | | |
| Weibull | | |

Suppose you are studying a machine that produces videotape. One measure of the quality of the tape is the number of visual defects per hundred feet of tape. The result of this experiment is an integer, since you cannot observe 1.5 defects. To model this experiment you should use a discrete probability distribution.

A measure affecting the cost and quality of videotape is its thickness. Thick tape is more expensive to produce, while variation in the thickness of the tape on the reel increases the likelihood of breakage. Suppose you measure the thickness of the tape every 1000 feet. The resulting numbers can take a continuum of possible values, which suggests using a continuous probability distribution to model the results.

Using a probability model does not allow you to predict the result of any individual experiment but you can determine the probability that a given outcome will fall inside a specific range of values.

This following two sections provide more information about the available distributions:

- "Overview of the Functions"
- "Overview of the Distributions"

## Overview of the Functions

MATLAB provides five functions for each distribution, which are discussed in the following sections:

- "Probability Density Function (pdf)"
- "Cumulative Distribution Function (cdf)"
- "Inverse Cumulative Distribution Function"
- "Random Number Generator"
- "Mean and Variance as a Function of Parameters"

### Probability Density Function (pdf)

The probability density function (pdf) has a different meaning depending on whether the distribution is discrete or continuous.

For discrete distributions, the pdf is the probability of observing a particular outcome. In our videotape example, the probability that there is exactly one defect in a given hundred feet of tape is the value of the pdf at 1.

Unlike discrete distributions, the pdf of a continuous distribution at a value is not the probability of observing that value. For continuous distributions the probability of observing any particular value is zero. To get probabilities you must integrate the pdf over an interval of interest. For example the probability of the thickness of a videotape being between one and two millimeters is the integral of the appropriate pdf from one to two.

A pdf has two theoretical properties:

- The pdf is zero or positive for every possible outcome.
- The integral of a pdf over its entire range of values is one.

A pdf is not a single function. Rather a pdf is a family of functions characterized by one or more parameters. Once you choose (or estimate) the parameters of a pdf, you have uniquely specified the function.

The pdf function call has the same general format for every distribution in the Statistics Toolbox. The following commands illustrate how to call the pdf for the normal distribution.

```
x = [-3:0.1:3];
f = normpdf(x,0,1);
```

The variable f contains the density of the normal pdf with parameters μ=0 and σ=1 at the values in x. The first input argument of every pdf is the set of values for which you want to evaluate the density. Other arguments contain as many parameters as are necessary to define the distribution uniquely. The normal distribution requires two parameters; a location parameter (the mean, μ) and a scale parameter (the standard deviation, σ).

### Cumulative Distribution Function (cdf)

If $f$ is a probability density function for random variable $X$, the associated cumulative distribution function (cdf) $F$ is

$$F(x) = P(X \le x) = \int_{-\infty}^{x} f(t)\,dt$$

The cdf of a value $x$, $F(x)$, is the probability of observing any outcome less than or equal to $x$.

A cdf has two theoretical properties:

- The cdf ranges from 0 to 1.
- If $y > x$, then the cdf of $y$ is greater than or equal to the cdf of $x$.

The cdf function call has the same general format for every distribution in the Statistics Toolbox. The following commands illustrate how to call the cdf for the normal distribution.

```
x = [-3:0.1:3];
p = normcdf(x,0,1);
```

The variable p contains the probabilities associated with the normal cdf with parameters μ=0 and σ=1 at the values in x. The first input argument of every cdf is the set of values for which you want to evaluate the probability. Other arguments contain as many parameters as are necessary to define the distribution uniquely.

### Inverse Cumulative Distribution Function

The inverse cumulative distribution function returns critical values for hypothesis testing given significance probabilities. To understand the relationship between a continuous cdf and its inverse function, try the following:

```
x = [-3:0.1:3];
xnew = norminv(normcdf(x,0,1),0,1);
```

How does xnew compare with x? Conversely, try this:

```
p = [0.1:0.1:0.9];
pnew = normcdf(norminv(p,0,1),0,1);
```

How does pnew compare with p?

Calculating the cdf of values in the domain of a continuous distribution returns probabilities between zero and one. Applying the inverse cdf to these probabilities yields the original values.

For discrete distributions, the relationship between a cdf and its inverse function is more complicated. It is likely that there is no $x$ value such that the cdf of $x$ yields $p$. In these cases the inverse function returns the first value $x$ such that the cdf of $x$ equals or exceeds $p$. Try this:

```
x = [0:10];
y = binoinv(binocdf(x,10,0.5),10,0.5);
```

How does x compare with y?

The commands below illustrate the problem with reconstructing the probability $p$ from the value $x$ for discrete distributions.

```
p = [0.1:0.2:0.9];
pnew = binocdf(binoinv(p,10,0.5),10,0.5)

pnew =

    0.1719    0.3770    0.6230    0.8281    0.9453
```

The inverse function is useful in hypothesis testing and production of confidence intervals. Here is the way to get a 99% confidence interval for a normally distributed sample.

```
p = [0.005 0.995];
x = norminv(p, 0, 1)

x =

    -2.5758     2.5758
```

The variable x contains the values associated with the normal inverse function with parameters μ=0 and σ=1 at the probabilities in p. The difference p(2)-p(1) is 0.99. Thus, the values in x define an interval that contains 99% of the standard normal probability.

The inverse function call has the same general format for every distribution in the Statistics Toolbox. The first input argument of every inverse function is the set of probabilities for which you want to evaluate the critical values. Other arguments contain as many parameters as are necessary to define the distribution uniquely.

### Random Number Generator

The methods for generating random numbers from any distribution all start with uniform random numbers. Once you have a uniform random number generator, you can produce random numbers from other distributions either directly or by using inversion or rejection methods, described below. See "Syntax for Random Number Functions" on page 1-10 for details on using generator functions.

**Direct.**  Direct methods flow from the definition of the distribution.

As an example, consider generating binomial random numbers. You can think of binomial random numbers as the number of heads in $n$ tosses of a coin with probability $p$ of a heads on any toss. If you generate $n$ uniform random numbers and count the number that are greater than $p$, the result is binomial with parameters $n$ and $p$.

**Inversion.**  The inversion method works due to a fundamental theorem that relates the uniform distribution to other continuous distributions.

If $F$ is a continuous distribution with inverse $F^{-1}$, and U is a uniform random number, then $F^{-1}$(U) has distribution $F$.

So, you can generate a random number from a distribution by applying the inverse function for that distribution to a uniform random number. Unfortunately, this approach is usually not the most efficient.

**Rejection**.  The functional form of some distributions makes it difficult or time consuming to generate random numbers using direct or inversion methods. Rejection methods can sometimes provide an elegant solution in these cases.

Suppose you want to generate random numbers from a distribution with pdf *f*. To use rejection methods you must first find another density, *g*, and a constant, *c*, so that the inequality below holds.

$$f(x) \le cg(x) \forall x$$

You then generate the random numbers you want using the following steps:

**1**  Generate a random number *x* from distribution *G* with density *g*.

**2**  Form the ratio $r = \dfrac{cg(x)}{f(x)}$.

**3**  Generate a uniform random number *u*.

**4**  If the product of *u* and *r* is less than one, return *x*.

**5**  Otherwise repeat steps one to three.

For efficiency you need a cheap method for generating random numbers from *G,* and the scalar *c* should be small. The expected number of iterations is *c*.

**Syntax for Random Number Functions**.  You can generate random numbers from each distribution. This function provides a single random number or a matrix of random numbers, depending on the arguments you specify in the function call.

For example, here is the way to generate random numbers from the beta distribution. Four statements obtain random numbers: the first returns a single number, the second returns a 2-by-2 matrix of random numbers, and the third and fourth return 2-by-3 matrices of random numbers.

```
a = 1;
b = 2;
c = [.1 .5; 1 2];
d = [.25 .75; 5 10];
m = [2 3];
nrow = 2;
ncol = 3;
```

```
r1 = betarnd(a, b)
r1 =

    0.4469

r2 = betarnd(c, d)
r2 =

    0.8931    0.4832
    0.1316    0.2403

r3 = betarnd(a, b, m)
r3 =

    0.4196    0.6078    0.1392
    0.0410    0.0723    0.0782

r4 = betarnd(a, b, nrow, ncol)
r4 =

    0.0520    0.3975    0.1284
    0.3891    0.1848    0.5186
```

### Mean and Variance as a Function of Parameters

The mean and variance of a probability distribution are generally simple functions of the parameters of the distribution. The Statistics Toolbox functions ending in "stat" all produce the mean and variance of the desired distribution for the given parameters.

The example below shows a contour plot of the mean of the Weibull distribution as a function of the parameters.

```
x = (0.5:0.1:5);
y = (1:0.04:2);
[X, Y] = meshgrid(x, y);
Z = weibstat(X, Y);
[c, h] = contour(x, y, Z, [0.4 0.6 1.0 1.8]);
clabel(c);
```
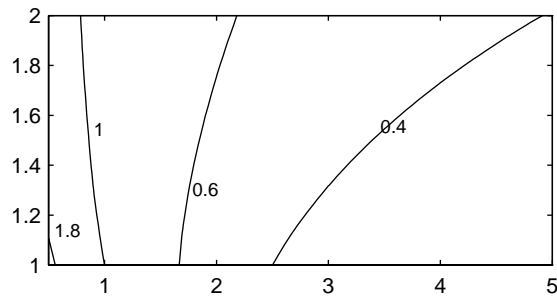
## Overview of the Distributions

The following sections describe the available probability distributions:

## Beta Distribution

The following sections provide an overview of the beta distribution.

**Background on the Beta Distribution.** The beta distribution describes a family of curves that are unique in that they are nonzero only on the interval (0 1). A more general version of the function assigns parameters to the end-points of the interval.

The beta cdf is the same as the incomplete beta function.

The beta distribution has a functional relationship with the t distribution. If $Y$ is an observation from Student's t distribution with $\nu$ degrees of freedom, then the following transformation generates $X$, which is beta distributed.

$$X = \frac{1}{2} + \frac{1}{2}\frac{Y}{\sqrt{\nu + Y^2}}$$

$$\text{if} \quad Y \sim t(\nu) \quad \text{then} \quad X \sim \beta\left(\frac{\nu}{2}, \frac{\nu}{2}\right)$$

The Statistics Toolbox uses this relationship to compute values of the t cdf and inverse function as well as generating t distributed random numbers.

**Definition of the Beta Distribution.** The beta pdf is

$$y = f(x|a, b) = \frac{1}{B(a, b)}x^{a-1}(1-x)^{b-1}I_{(0, 1)}(x)$$

where $B(\cdot)$ is the Beta function. The indicator function $I_{(0,1)}(x)$ ensures that only values of $x$ in the range (0 1) have nonzero probability.

**Parameter Estimation for the Beta Distribution.** Suppose you are collecting data that has hard lower and upper bounds of zero and one respectively. Parameter estimation is the process of determining the parameters of the beta distribution that fit this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the beta pdf. But for the pdf, the parameters are known constants and the variable is $x$. The likelihood function reverses the roles of the variables. Here, the sample values (the $x$'s) are already observed. So they are the fixed constants. The variables are the unknown parameters.

Maximum likelihood estimation (MLE) involves calculating the values of the parameters that give the highest likelihood given the particular set of data.

The function `betafit` returns the MLEs and confidence intervals for the parameters of the beta distribution. Here is an example using random numbers from the beta distribution with $a = 5$ and $b = 0.2$.

```
r = betarnd(5,0.2,100,1);
[phat, pci] = betafit(r)

phat =

    4.5330    0.2301

pci =

    2.8051    0.1771
    6.2610    0.2832
```

The MLE for parameter $a$ is 4.5330, compared to the true value of 5. The 95% confidence interval for $a$ goes from 2.8051 to 6.2610, which includes the true value.

Similarly the MLE for parameter $b$ is 0.2301, compared to the true value of 0.2. The 95% confidence interval for $b$ goes from 0.1771 to 0.2832, which also includes the true value. Of course, in this made-up example we know the "true value." In experimentation we do not.

**Example and Plot of the Beta Distribution.** The shape of the beta distribution is quite variable depending on the values of the parameters, as illustrated by the plot below.
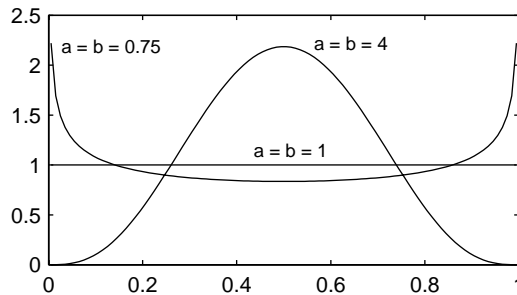
The constant pdf (the flat line) shows that the standard uniform distribution is a special case of the beta distribution.

### Binomial Distribution

The following sections provide an overview of the binomial distribution.

**Background of the Binomial Distribution.**  The binomial distribution models the total number of successes in repeated trials from an infinite population under the following conditions:

- Only two outcomes are possible on each of $n$ trials.
- The probability of success for each trial is constant.
- All trials are independent of each other.

James Bernoulli derived the binomial distribution in 1713 (*Ars Conjectandi*). Earlier, Blaise Pascal had considered the special case where $p = 1/2$.

**Definition of the Binomial Distribution.**  The binomial pdf is

$$y = f(x|n, p) = \binom{n}{x} p^x q^{(1-x)} I_{(0, 1, ..., n)}(x)$$

where $\binom{n}{x} = \dfrac{n!}{x!(n-x)!}$ and $q = 1 - p$.

The binomial distribution is discrete. For zero and for positive integers less than $n$, the pdf is nonzero.

**Parameter Estimation for the Binomial Distribution.**  Suppose you are collecting data from a widget manufacturing process, and you record the number of widgets within specification in each batch of 100. You might be interested in the probability that an individual widget is within specification. Parameter estimation is the process of determining the parameter, $p$, of the binomial distribution that fits this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the binomial pdf above. But for the pdf, the parameters ($n$ and $p$) are known constants and the variable is $x$. The likelihood function reverses the roles of the variables. Here, the sample values (the $x$'s) are already observed. So they are the fixed constants. The variables are the

unknown parameters. MLE involves calculating the value of $p$ that give the highest likelihood given the particular set of data.

The function binofit returns the MLEs and confidence intervals for the parameters of the binomial distribution. Here is an example using random numbers from the binomial distribution with $n = 100$ and $p = 0.9$.

```
r = binornd(100, 0.9)

r =

    88

[phat, pci] = binofit(r, 100)

phat =

    0.8800

pci =

    0.7998
    0.9364
```

The MLE for parameter $p$ is 0.8800, compared to the true value of 0.9. The 95% confidence interval for $p$ goes from 0.7998 to 0.9364, which includes the true value. Of course, in this made-up example we know the "true value" of $p$. In experimentation we do not.

**Example and Plot of the Binomial Distribution.** The following commands generate a plot of the binomial pdf for $n = 10$ and $p = 1/2$.

```
x = 0:10;
y = binopdf(x, 10, 0.5);
plot(x, y, '+')
```
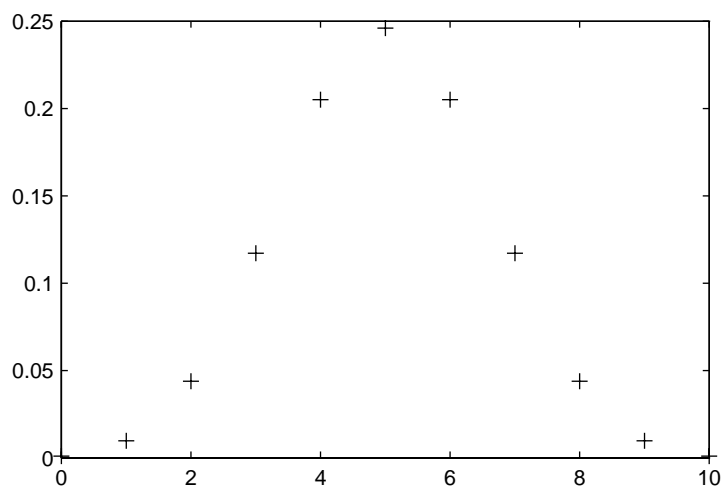
### Chi-Square Distribution

The following sections provide an overview of the $\chi^2$ distribution.

**Background of the Chi-Square Distribution.** The $\chi^2$ distribution is a special case of the gamma distribution where $b = 2$ in the equation for gamma distribution below.

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

The $\chi^2$ distribution gets special attention because of its importance in normal sampling theory. If a set of $n$ observations is normally distributed with variance $\sigma^2$, and $s^2$ is the sample standard deviation, then

$$\frac{(n-1)s^2}{\sigma^2} \sim \chi^2(n-1)$$

The Statistics Toolbox uses the above relationship to calculate confidence intervals for the estimate of the normal parameter $\sigma^2$ in the function normfit.

**Definition of the Chi-Square Distribution.** The $\chi^2$ pdf is

$$y \,=\, f(x|\nu) \,=\, \frac{x^{(\nu-2)/2}e^{-x/2}}{2^{\frac{\nu}{2}}\Gamma(\nu/2)}$$

where $\Gamma(\,\cdot\,)$ is the Gamma function, and $\nu$ is the degrees of freedom.

**Example and Plot of the Chi-Square Distribution.** The $\chi^2$ distribution is skewed to the right especially for few degrees of freedom ($\nu$). The plot shows the $\chi^2$ distribution with four degrees of freedom.

```
x = 0: 0. 2: 15;
y = chi 2pdf (x, 4) ;
pl ot (x, y)
```
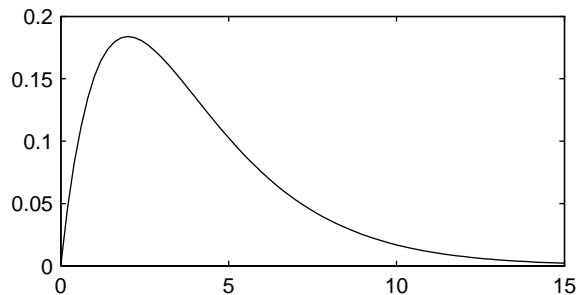


## Noncentral Chi-Square Distribution

The following sections provide an overview of the noncentral $\chi^2$ distribution.

**Background of the Noncentral Chi-Square Distribution.** The $\chi^2$ distribution is actually a simple special case of the noncentral chi-square distribution. One way to generate random numbers with a $\chi^2$ distribution (with $\nu$ degrees of freedom) is to sum the squares of $\nu$ standard normal random numbers (mean equal to zero.)

What if we allow the normally distributed quantities to have a mean other than zero? The sum of squares of these numbers yields the noncentral chi-square distribution. The noncentral chi-square distribution requires two parameters; the degrees of freedom and the noncentrality parameter. The noncentrality parameter is the sum of the squared means of the normally distributed quantities.

The noncentral chi-square has scientific application in thermodynamics and signal processing. The literature in these areas may refer to it as the Ricean or generalized Rayleigh distribution.

**Definition of the Noncentral Chi-Square Distribution.** There are many equivalent formulas for the noncentral chi-square distribution function. One formulation uses a modified Bessel function of the first kind. Another uses the generalized Laguerre polynomials. The Statistics Toolbox computes the cumulative distribution function values using a weighted sum of $\chi^2$ probabilities with the weights equal to the probabilities of a Poisson distribution. The Poisson parameter is one-half of the noncentrality parameter of the noncentral chi-square.

$$F(x|\nu, \delta) = \sum_{j=0}^{\infty} \left(\frac{\left(\frac{1}{2}\delta\right)^j}{j!} e^{-\frac{\delta}{2}}\right) Pr[\chi^2_{\nu+2j} \le x]$$

where $\delta$ is the noncentrality parameter.

**Example of the Noncentral Chi-Square Distribution.** The following commands generate a plot of the noncentral chi-square pdf.

```
x = (0:0.1:10)';
p1 = ncx2pdf(x, 4, 2);
p = chi2pdf(x, 4);
plot(x, p, '--', x, p1, '-')
```
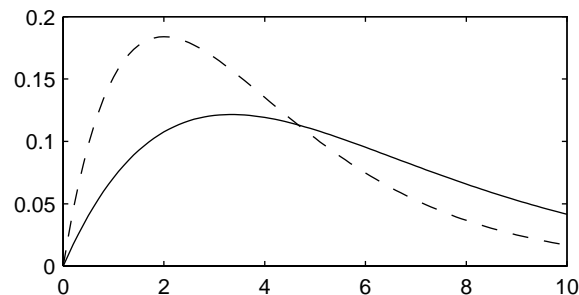
### Discrete Uniform Distribution

The following sections provide an overview of the discrete uniform distribution.

**Background of the Discrete Uniform Distribution.** The discrete uniform distribution is a simple distribution that puts equal weight on the integers from one to $N$.

**Definition of the Discrete Uniform Distribution.** The discrete uniform pdf is

$$y = f(x|N) = \frac{1}{N} I_{(1, \dots, N)}(x)$$

**Example and Plot of the Discrete Uniform Distribution.** As for all discrete distributions, the cdf is a step function. The plot shows the discrete uniform cdf for $N = 10$.

```
x = 0:10;
y = unidcdf(x, 10);
stairs(x, y)
set(gca, 'Xlim', [0 11])
```
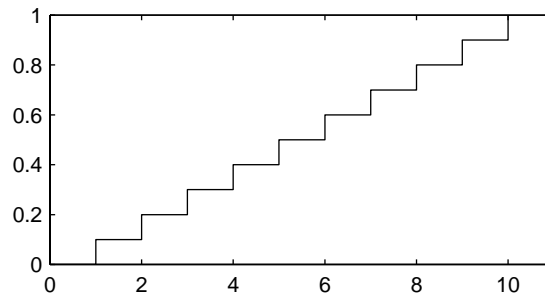


To pick a random sample of 10 from a list of 553 items:

```
numbers = unidrnd(553, 1, 10)

numbers =

    293    372      5    213     37    231    380    326    515    468
```

## Exponential Distribution

The following sections provide an overview of the exponential distribution.

**Background of the Exponential Distribution.** Like the chi-square distribution, the exponential distribution is a special case of the gamma distribution (obtained by setting $a = 1$)

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

where $\Gamma(\cdot)$ is the Gamma function.

The exponential distribution is special because of its utility in modeling events that occur randomly over time. The main application area is in studies of lifetimes.

**Definition of the Exponential Distribution.** The exponential pdf is

$$y = f(x|\mu) = \frac{1}{\mu} e^{-\frac{x}{\mu}}$$

**Parameter Estimation for the Exponential Distribution.** Suppose you are stress testing light bulbs and collecting data on their lifetimes. You assume that these lifetimes follow an exponential distribution. You want to know how long you can expect the average light bulb to last. Parameter estimation is the process of determining the parameters of the exponential distribution that fit this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the exponential pdf above. But for the pdf, the parameters are known constants and the variable is $x$. The likelihood function reverses the roles of the variables. Here, the sample values (the $x$'s) are already observed. So they are the fixed constants. The variables are the unknown parameters. MLE involves calculating the values of the parameters that give the highest likelihood given the particular set of data.

The function `expfit` returns the MLEs and confidence intervals for the parameters of the exponential distribution. Here is an example using random numbers from the exponential distribution with $\mu = 700$.

```
lifetimes = exprnd(700, 100, 1);
[muhat, muci] = expfit(lifetimes)

muhat =

   672.8207

muci =

   547.4338
   810.9437
```

The MLE for parameter $\mu$ is 672, compared to the true value of 700. The 95% confidence interval for $\mu$ goes from 547 to 811, which includes the true value.

In our life tests we do not know the true value of $\mu$ so it is nice to have a confidence interval on the parameter to give a range of likely values.

**Example and Plot of the Exponential Distribution.** For exponentially distributed lifetimes, the probability that an item will survive an extra unit of time is independent of the current age of the item. The example shows a specific case of this special property.

```
l  = 10:10:60;
lpd = l+0.1;
deltap = (expcdf(lpd, 50)-expcdf(l, 50))./(1-expcdf(l, 50))

deltap =

    0.0020    0.0020    0.0020    0.0020    0.0020    0.0020
```

The plot below shows the exponential pdf with its parameter (and mean), $\mu$, set to 2.

```
x = 0:0.1:10;
y = exppdf(x, 2);
plot(x, y)
```
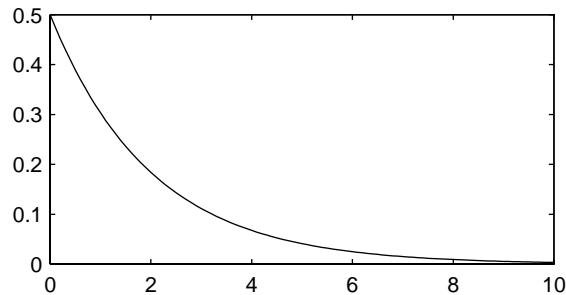
## F Distribution

The following sections provide an overview of the F distribution.

**Background of the F distribution.** The F distribution has a natural relationship with the chi-square distribution. If $\chi_1$ and $\chi_2$ are both chi-square with $\nu_1$ and $\nu_2$ degrees of freedom respectively, then the statistic $F$ below is F distributed.

$$F(\nu_1, \nu_2) = \frac{\dfrac{\chi_1}{\nu_1}}{\dfrac{\chi_2}{\nu_2}}$$

The two parameters, $\nu_1$ and $\nu_2$, are the numerator and denominator degrees of freedom. That is, $\nu_1$ and $\nu_2$ are the number of independent pieces information used to calculate $\chi_1$ and $\chi_2$ respectively.

**Definition of the F distribution.** The pdf for the F distribution is

$$y = f(x|\nu_1, \nu_2) = \frac{\Gamma\left[\dfrac{(\nu_1 + \nu_2)}{2}\right]}{\Gamma\left(\dfrac{\nu_1}{2}\right)\Gamma\left(\dfrac{\nu_2}{2}\right)}\left(\dfrac{\nu_1}{\nu_2}\right)^{\frac{\nu_1}{2}} \frac{x^{\frac{\nu_1 - 2}{2}}}{\left[1 + \left(\dfrac{\nu_1}{\nu_2}\right)x\right]^{\frac{\nu_1 + \nu_2}{2}}}$$

where $\Gamma(\cdot)$ is the Gamma function.

**Example and Plot of the F distribution.** The most common application of the F distribution is in standard tests of hypotheses in analysis of variance and regression.

The plot shows that the F distribution exists on the positive real numbers and is skewed to the right.

```
x = 0: 0. 01: 10;
y = fpdf (x, 5, 3) ;
pl ot (x, y)
```
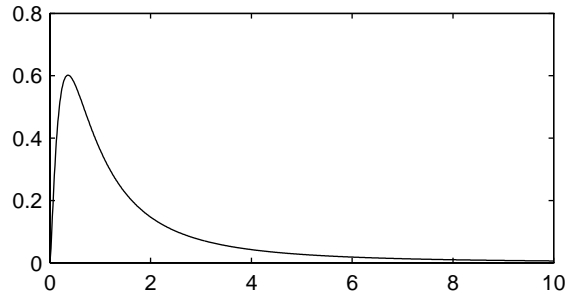


### Noncentral F Distribution

The following sections provide an overview of the noncentral F distribution.

**Background of the Noncentral F Distribution.** As with the $\chi^2$ distribution, the F distribution is a special case of the noncentral F distribution. The F distribution is the result of taking the ratio of two $\chi^2$ random variables each divided by its degrees of freedom.

If the numerator of the ratio is a noncentral chi-square random variable divided by its degrees of freedom, the resulting distribution is the noncentral F distribution.

The main application of the noncentral F distribution is to calculate the power of a hypothesis test relative to a particular alternative.

**Definition of the Noncentral F Distribution.** Similar to the noncentral $\chi^2$ distribution, the toolbox calculates noncentral F distribution probabilities as a weighted sum of incomplete beta functions using Poisson probabilities as the weights.

$$F(x|\nu_1, \nu_2, \delta) = \sum_{j=0}^{\infty} \left(\frac{1}{2}\delta\right)^j \frac{1}{j!} e^{-\frac{\delta}{2}} I\left(\frac{\nu_1 \cdot x}{\nu_2 + \nu_1 \cdot x}\bigg|\frac{\nu_1}{2}+j, \frac{\nu_2}{2}\right)$$

$I(x/a,b)$ is the incomplete beta function with parameters $a$ and $b$, and $\delta$ is the noncentrality parameter.

**Example and Plot of the Noncentral F Distribution.** The following commands generate a plot of the noncentral F pdf.

```
x = (0.01:0.1:10.01)';
p1 = ncfpdf(x, 5, 20, 10);
p  = fpdf(x, 5, 20);
plot(x, p, '--', x, p1, '-')
```
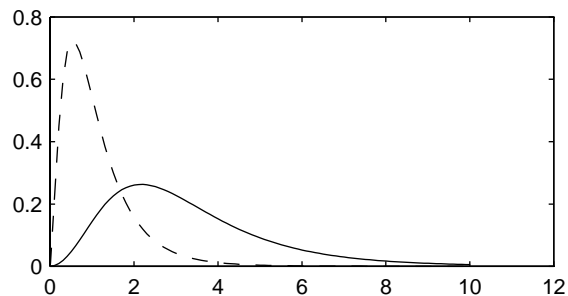


## Gamma Distribution

The following sections provide an overview of the gamma distribution.

**Background of the Gamma Distribution.** The gamma distribution is a family of curves based on two parameters. The chi-square and exponential distributions, which are children of the gamma distribution, are one-parameter distributions that fix one of the two gamma parameters.

The gamma distribution has the following relationship with the incomplete Gamma function.

$$\Gamma(x|a, b) = \text{gammainc}\left(\frac{x}{b}, a\right)$$

For $b = 1$ the functions are identical.

When $a$ is large, the gamma distribution closely approximates a normal distribution with the advantage that the gamma distribution has density only for positive real numbers.

**Definition of the Gamma Distribution.** The gamma pdf is

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

where $\Gamma(\cdot)$ is the Gamma function.

**Parameter Estimation for the Gamma Distribution.** Suppose you are stress testing computer memory chips and collecting data on their lifetimes. You assume that these lifetimes follow a gamma distribution. You want to know how long you can expect the average computer memory chip to last. Parameter estimation is the process of determining the parameters of the gamma distribution that fit this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the gamma pdf above. But for the pdf, the parameters are known constants and the variable is $x$. The likelihood function reverses the roles of the variables. Here, the sample values (the $x$'s) are already observed. So they are the fixed constants. The variables are the unknown parameters. MLE involves calculating the values of the parameters that give the highest likelihood given the particular set of data.

The function `gamfit` returns the MLEs and confidence intervals for the parameters of the gamma distribution. Here is an example using random numbers from the gamma distribution with $a = 10$ and $b = 5$.

```
lifetimes = gamrnd(10, 5, 100, 1);
[phat, pci] = gamfit(lifetimes)

phat =

    10.9821     4.7258

pci =

     7.4001     3.1543
    14.5640     6.2974
```

Note `phat(1)` $= \hat{a}$ and `phat(2)` $= \hat{b}$. The MLE for parameter $a$ is 10.98, compared to the true value of 10. The 95% confidence interval for $a$ goes from 7.4 to 14.6, which includes the true value.

Similarly the MLE for parameter $b$ is 4.7, compared to the true value of 5. The 95% confidence interval for $b$ goes from 3.2 to 6.3, which also includes the true value.

In our life tests we do not know the true value of $a$ and $b$ so it is nice to have a confidence interval on the parameters to give a range of likely values.

**Example and Plot of the Gamma Distribution.**  In the example the gamma pdf is plotted with the solid line. The normal pdf has a dashed line type.

```
x = gaminv((0.005:0.01:0.995), 100, 10);
y = gampdf(x, 100, 10);
y1 = normpdf(x, 1000, 100);
plot(x, y, '-', x, y1, '-.')
```
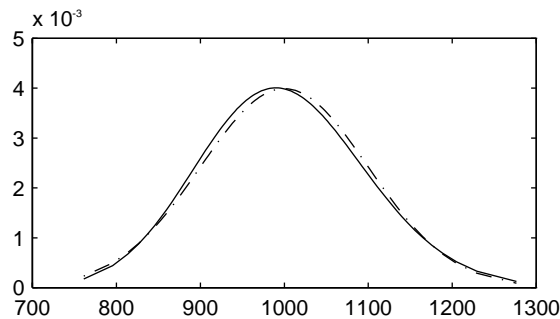


### Geometric Distribution

The following sections provide an overview of the geometric distribution.

**Background of the Geometric Distribution.**  The geometric distribution is discrete, existing only on the nonnegative integers. It is useful for modeling the runs of consecutive successes (or failures) in repeated independent trials of a system.

The geometric distribution models the number of successes before one failure in an independent succession of tests where each test results in success or failure.

**Definition of the Geometric Distribution.**  The geometric pdf is

$$y = f(x|p) = pq^x I_{(0, 1, \ldots)}(x)$$

where $q = 1 - p$.

**Example and Plot of the Geometric Distribution.**  Suppose the probability of a five-year-old battery failing in cold weather is 0.03. What is the probability of starting 25 consecutive days during a long cold snap?

```
1 - geocdf(25, 0. 03)

ans =

    0. 4530
```

The plot shows the cdf for this scenario.

```
x = 0: 25;
y = geocdf(x, 0. 03);
stairs(x, y)
```
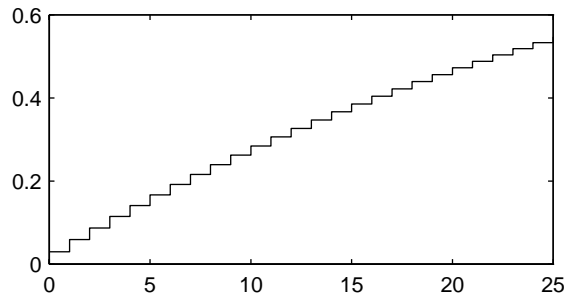


### Hypergeometric Distribution

The following sections provide an overview of the hypergeometric distribution.

**Background of the Hypergeometric Distribution.**  The hypergeometric distribution models the total number of successes in a fixed size sample drawn without replacement from a finite population.

The distribution is discrete, existing only for nonnegative integers less than the number of samples or the number of possible successes, whichever is greater.

The hypergeometric distribution differs from the binomial only in that the population is finite and the sampling from the population is without replacement.

The hypergeometric distribution has three parameters that have direct physical interpretations. *M* is the size of the population. *K* is the number of items with the desired characteristic in the population. *n* is the number of samples drawn. Sampling "without replacement" means that once a particular sample is chosen, it is removed from the relevant population for all subsequent selections.

**Definition of the Hypergeometric Distribution.**  The hypergeometric pdf is

$$y = f(x|M, K, n) = \frac{\binom{K}{x}\binom{M-K}{n-x}}{\binom{M}{n}}$$

**Example and Plot of the Hypergeometric Distribution.**  The plot shows the cdf of an experiment taking 20 samples from a group of 1000 where there are 50 items of the desired type.

```
x = 0: 10;
y = hygecdf(x, 1000, 50, 20);
stairs(x, y)
```
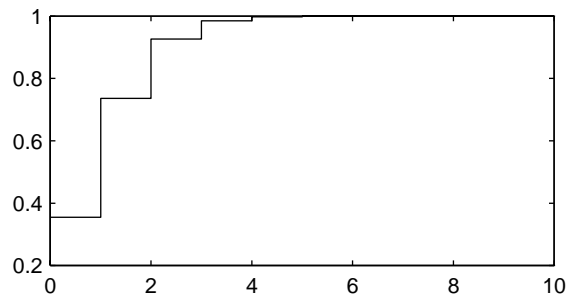
### Lognormal Distribution

The following sections provide an overview of the lognormal distribution.

**Background of the Lognormal Distribution.** The normal and lognormal distributions are closely related. If $X$ is distributed lognormal with parameters $\mu$ and $\sigma^2$, then $lnX$ is distributed normal with parameters $\mu$ and $\sigma^2$.

The lognormal distribution is applicable when the quantity of interest must be positive, since $lnX$ exists only when the random variable $X$ is positive. Economists often model the distribution of income using a lognormal distribution.

**Definition of the Lognormal Distribution.** The lognormal pdf is

$$y = f(x|\mu, \sigma) = \frac{1}{x\sigma\sqrt{2\pi}} e^{\frac{-(\ln x - \mu)^2}{2\sigma^2}}$$

**Example and Plot of the Lognormal Distribution.** Suppose the income of a family of four in the United States follows a lognormal distribution with $\mu = \log(20,000)$ and $\sigma^2 = 1.0$. Plot the income density.

```
x = (10: 1000: 125010)';
y = lognpdf(x, log(20000), 1.0);
plot(x, y)
set(gca, 'xtick', [0 30000 60000 90000 120000])
set(gca, 'xticklabel', str2mat('0', '$30,000', '$60,000', ...
                                '$90,000', '$120,000'))
```
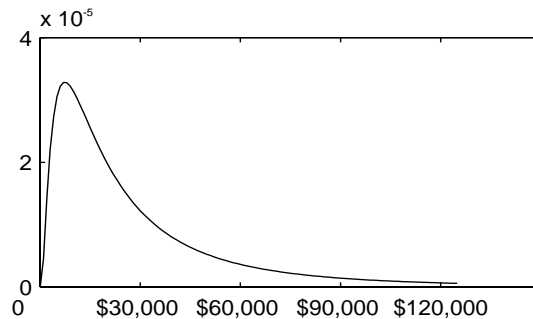
## Negative Binomial Distribution

The following sections provide an overview of the negative binomial distribution.

**Background of the Negative Binomial Distribution.** The geometric distribution is a special case of the negative binomial distribution (also called the Pascal distribution). The geometric distribution models the number of successes before one failure in an independent succession of tests where each test results in success or failure.

In the negative binomial distribution the number of failures is a parameter of the distribution. The parameters are the probability of success, $p$, and the number of failures, $r$.

**Definition of the Negative Binomial Distribution.** The negative binomial pdf is

$$y = f(x|r, p) = \binom{r + x - 1}{x} p^r q^x I_{(0, 1, \ldots)}(x)$$

where $q = 1 - p$.

**Example and Plot of the Negative Binomial Distribution.** The following commands generate a plot of the negative binomial pdf.

```
x = (0: 10);
y = nbinpdf(x, 3, 0.5);
plot(x, y, '+')
set(gca, 'XLim', [-0.5, 10.5])
```
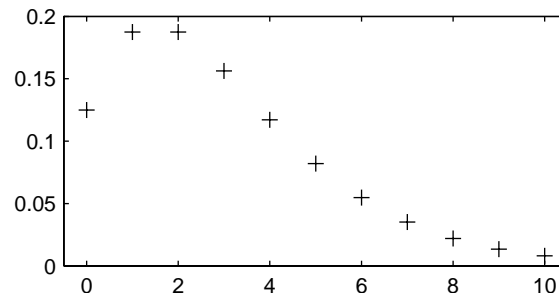
## Normal Distribution

The following sections provide an overview of the normal distribution.

**Background of the Normal Distribution.** The normal distribution is a two parameter family of curves. The first parameter, $\mu$, is the mean. The second, $\sigma$, is the standard deviation. The standard normal distribution (written $\Phi(x)$) sets $\mu$ to 0 and $\sigma$ to 1.

$\Phi(x)$ is functionally related to the error function, *erf*.

$$erf(x) = 2\Phi(x\sqrt{2}) - 1$$

The first use of the normal distribution was as a continuous approximation to the binomial.

The usual justification for using the normal distribution for modeling is the Central Limit Theorem, which states (roughly) that the sum of independent samples from any distribution with finite mean and variance converges to the normal distribution as the sample size goes to infinity.

**Definition of the Normal Distribution.** The normal pdf is

$$y = f(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}}e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

**Parameter Estimation for the Normal Distribution.** One of the first applications of the normal distribution in data analysis was modeling the height of school children. Suppose we want to estimate the mean, $\mu$, and the variance, $\sigma^2$, of all the 4th graders in the United States.

We have already introduced MLEs. Another desirable criterion in a statistical estimator is unbiasedness. A statistic is unbiased if the expected value of the statistic is equal to the parameter being estimated. MLEs are not always unbiased. For any data sample, there may be more than one unbiased estimator of the parameters of the parent distribution of the sample. For instance, every sample value is an unbiased estimate of the parameter $\mu$ of a normal distribution. The Minimum Variance Unbiased Estimator (MVUE) is the statistic that has the minimum variance of all unbiased estimators of a parameter.

The MVUEs of parameters $\mu$ and $\sigma^2$ for the normal distribution are the sample average and variance. The sample average is also the MLE for $\mu$. There are two common textbook formulas for the variance.

They are

$$1) \quad s^2 = \frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^2$$

$$2) \quad s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2$$

where

$$\bar{x} = \sum_{i=1}^{n} \frac{x_i}{n}$$

Equation 1 is the maximum likelihood estimator for $\sigma^2$, and equation 2 is the MVUE.

The function `normfit` returns the MVUEs and confidence intervals for $\mu$ and $\sigma^2$. Here is a playful example modeling the "heights" (inches) of a randomly chosen 4th grade class.

```
height = normrnd(50, 2, 30, 1);          % Simulate heights.
[mu, s, muci, sci] = normfit(height)

mu =
    50.2025

s =
     1.7946

muci =
    49.5210
    50.8841

sci =
     1.4292
     2.4125
```

**1-33**

**Example and Plot of the Normal Distribution.** The plot shows the "bell" curve of the standard normal pdf, with $\mu = 0$ and $\sigma = 1$.
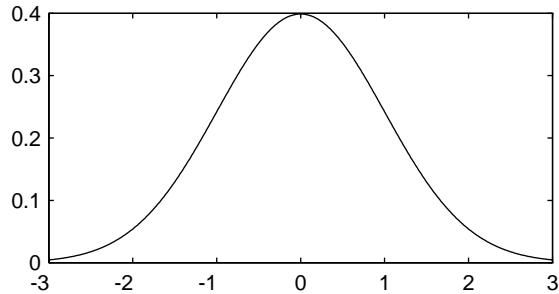


## Poisson Distribution

The following sections provide an overview of the Poisson distribution.

**Background of the Poisson Distribution.** The Poisson distribution is appropriate for applications that involve counting the number of times a random event occurs in a given amount of time, distance, area, etc. Sample applications that involve Poisson distributions include the number of Geiger counter clicks per second, the number of people walking into a store in an hour, and the number of flaws per 1000 feet of video tape.

The Poisson distribution is a one parameter discrete distribution that takes nonnegative integer values. The parameter, $\lambda$, is both the mean and the variance of the distribution. Thus, as the size of the numbers in a particular sample of Poisson random numbers gets larger, so does the variability of the numbers.

As Poisson (1837) showed, the Poisson distribution is the limiting case of a binomial distribution where $N$ approaches infinity and $p$ goes to zero while $Np = \lambda$.

The Poisson and exponential distributions are related. If the number of counts follows the Poisson distribution, then the interval between individual counts follows the exponential distribution.

**Definition of the Poisson Distribution.**  The Poisson pdf is

$$y = f(x|\lambda) = \frac{\lambda^x}{x!} e^{-\lambda} I_{(0, 1, \ldots)}(x)$$

**Parameter Estimation for the Poisson Distribution.**  The MLE and the MVUE of the Poisson parameter, $\lambda$, is the sample mean. The sum of independent Poisson random variables is also Poisson distributed with the parameter equal to the sum of the individual parameters. The Statistics Toolbox makes use of this fact to calculate confidence intervals on $\lambda$. As $\lambda$ gets large the Poisson distribution can be approximated by a normal distribution with $\mu = \lambda$ and $\sigma^2 = \lambda$. The Statistics Toolbox uses this approximation for calculating confidence intervals for values of $\lambda$ greater than 100.

**Example and Plot of the Poisson Distribution.**  The plot shows the probability for each nonnegative integer when $\lambda = 5$.

```
x = 0: 15;
y = poisspdf(x, 5);
plot(x, y, '+')
```
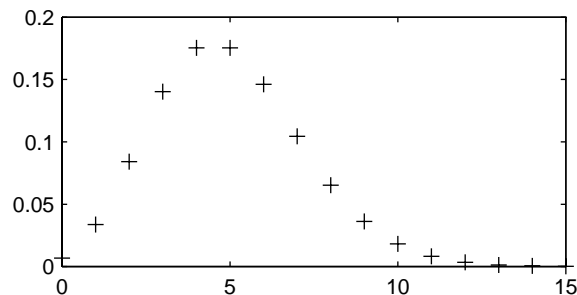


## Rayleigh Distribution

The following sections provide an overview of the Rayleigh distribution.

**Background of the Rayleigh Distribution.**  The Rayleigh distribution is a special case of the Weibull distribution. If $A$ and $B$ are the parameters of the Weibull distribution, then the Rayleigh distribution with parameter $b$ is equivalent to the Weibull distribution with parameters $A = 1/(2b^2)$ and $B = 2$.

If the component velocities of a particle in the $x$ and $y$ directions are two independent normal random variables with zero means and equal variances, then the distance the particle travels per unit time is distributed Rayleigh.

**Definition of the Rayleigh Distribution.** The Rayleigh pdf is

$$y = f(x|b) = \frac{x}{b^2} e^{\left(\frac{-x^2}{2b^2}\right)}$$

**Parameter Estimation for the Rayleigh Distribution.** The `raylfit` function returns the MLE of the Rayleigh parameter. This estimate is

$$b = \sqrt{\frac{1}{2n} \sum_{i=1}^{n} x_i^2}$$

**Example and Plot of the Rayleigh Distribution.** The following commands generate a plot of the Rayleigh pdf.

```
x = [0:0.01:2];
p = raylpdf(x,0.5);
plot(x,p)
```
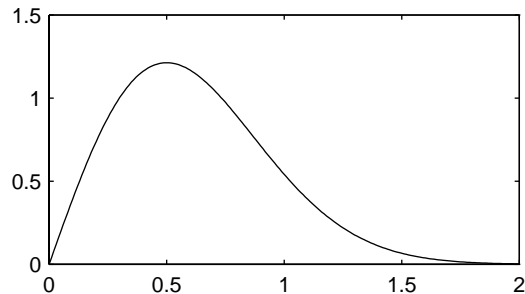
### Student's t Distribution

The following sections provide an overview of Student's t distribution.

**Background of Student's t Distribution.** The t distribution is a family of curves depending on a single parameter ν (the degrees of freedom). As ν goes to infinity, the t distribution converges to the standard normal distribution.

W. S. Gossett (1908) discovered the distribution through his work at the Guinness brewery. At that time, Guinness did not allow its staff to publish, so Gossett used the pseudonym Student.

If $x$ and $s$ are the mean and standard deviation of an independent random sample of size $n$ from a normal distribution with mean $\mu$ and $\sigma^2 = n$, then

$$t(\nu) = \frac{x - \mu}{s}$$

$$\nu = n - 1$$

**Definition of Student's t Distribution.** Student's t pdf is

$$y = f(x|\nu) = \frac{\Gamma\left(\frac{\nu + 1}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \frac{1}{\sqrt{\nu\pi}} \frac{1}{\left(1 + \frac{x^2}{\nu}\right)^{\frac{\nu + 1}{2}}}$$

where $\Gamma(\cdot)$ is the Gamma function.

**Example and Plot of Student's t Distribution.** The plot compares the t distribution with ν = 5 (solid line) to the shorter tailed, standard normal distribution (dashed line).

```
x = -5:0.1:5;
y = tpdf(x,5);
z = normpdf(x,0,1);
plot(x,y,'-',x,z,'-.')
```
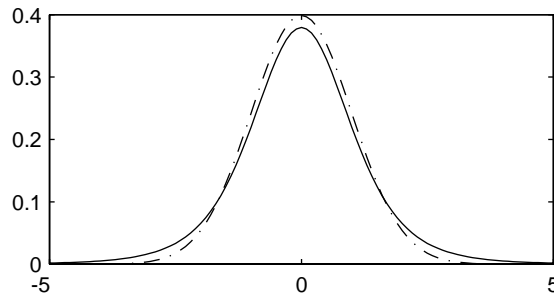
### Noncentral t Distribution

The following sections provide an overview of the noncentral t distribution.

**Background of the Noncentral t Distribution.** The noncentral t distribution is a generalization of the familiar Student's t distribution.

If $x$ and $s$ are the mean and standard deviation of an independent random sample of size $n$ from a normal distribution with mean $\mu$ and $\sigma^2 = n$, then

$$t(\nu) = \frac{x-\mu}{s}$$

$$\nu = n-1$$

Suppose that the mean of the normal distribution is not $\mu$. Then the ratio has the noncentral t distribution. The noncentrality parameter is the difference between the sample mean and $\mu$.

The noncentral t distribution allows us to determine the probability that we would detect a difference between $x$ and $\mu$ in a t test. This probability is the *power* of the test. As $x$-$\mu$ increases, the power of a test also increases.

**Definition of the Noncentral t Distribution.** The most general representation of the noncentral t distribution is quite complicated. Johnson and Kotz (1970) give a formula for the probability that a noncentral t variate falls in the range [-t, t].

$$Pr((-t) < x < t | (\nu, \delta)) = \sum_{j=0}^{\infty} \frac{\left(\frac{1}{2}\delta^2\right)^j}{j!} e^{-\frac{\delta^2}{2}} I\left(\frac{x^2}{\nu + x^2}\bigg|\frac{1}{2}+j, \frac{\nu}{2}\right)$$

$I(x/a,b)$ is the incomplete beta function with parameters $a$ and $b$, $\delta$ is the noncentrality parameter, and $\nu$ is the degrees of freedom.

**Example and Plot of the Noncentral t Distribution.** The following commands generate a plot of the noncentral t pdf.

```
x = (-5:0.1:5)';
p1 = nctcdf(x, 10, 1);
p = tcdf(x, 10);
plot(x, p, '--', x, p1, '-')
```
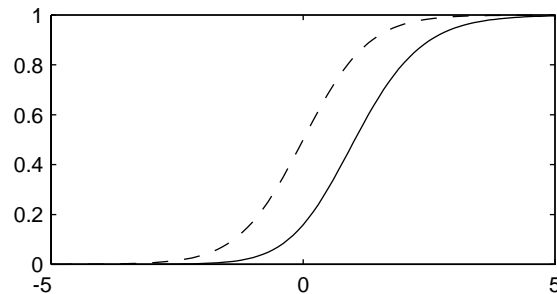


## Uniform (Continuous) Distribution

The following sections provide an overview of the uniform distribution.

**Background of the Uniform Distribution.** The uniform distribution (also called rectangular) has a constant pdf between its two parameters $a$ (the minimum) and $b$ (the maximum). The standard uniform distribution ($a = 0$ and $b = 1$) is a special case of the beta distribution, obtained by setting both of its parameters to 1.

The uniform distribution is appropriate for representing the distribution of round-off errors in values tabulated to a particular number of decimal places.

**Definition of the Uniform Distribution.** The uniform cdf is

$$p = F(x|a, b) = \frac{x - a}{b - a} I_{[a, b]}(x)$$

**Parameter Estimation for the Uniform Distribution.** The sample minimum and maximum are the MLEs of $a$ and $b$ respectively.

**Example and Plot of the Uniform Distribution.**  The example illustrates the inversion method for generating normal random numbers using `rand` and `norminv`. Note that the MATLAB function, `randn`, does not use inversion since it is not efficient for this case.

```
u = rand(1000, 1);
x = norminv(u, 0, 1);
hist(x)
```
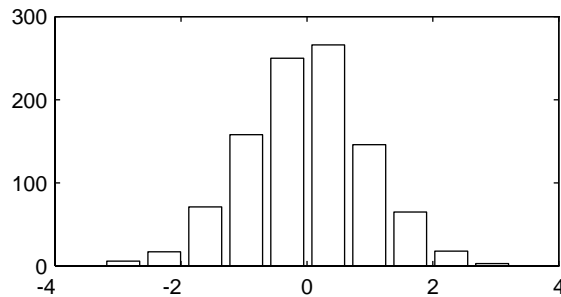


### Weibull Distribution

The following sections provide an overview of the Weibull distribution.

**Background of the Weibull Distribution.**  Waloddi Weibull (1939) offered the distribution that bears his name as an appropriate analytical tool for modeling the breaking strength of materials. Current usage also includes reliability and lifetime modeling. The Weibull distribution is more flexible than the exponential for these purposes.

To see why, consider the hazard rate function (instantaneous failure rate). If $f(t)$ and $F(t)$ are the pdf and cdf of a distribution, then the hazard rate is

$$h(t) = \frac{f(t)}{1 - F(t)}$$

Substituting the pdf and cdf of the exponential distribution for $f(t)$ and $F(t)$ above yields a constant. The example below shows that the hazard rate for the Weibull distribution can vary.

**Definition of the Weibull Distribution.** The Weibull pdf is

$$y = f(x|a, b) = abx^{b-1}e^{-ax^b}I_{(0, \infty)}(x)$$

**Parameter Estimation for the Weibull Distribution.** Suppose we want to model the tensile strength of a thin filament using the Weibull distribution. The function weibfit gives MLEs and confidence intervals for the Weibull parameters.

```
strength = weibrnd(0.5, 2, 100, 1);        % Simulated strengths.
[p, ci] = weibfit(strength)

p =
    0.4746    1.9582

ci =
    0.3851    1.6598
    0.5641    2.2565
```

The default 95% confidence interval for each parameter contains the true value.

**Example and Plot of the Weibull Distribution.** The exponential distribution has a constant hazard function, which is not generally the case for the Weibull distribution.

The plot shows the hazard functions for exponential (dashed line) and Weibull (solid line) distributions having the same mean life. The Weibull hazard rate here increases with age (a reasonable assumption).

```
t = 0:0.1:3;
h1 = exppdf(t, 0.6267) ./ (1-expcdf(t, 0.6267));
h2 = weibpdf(t, 2, 2) ./ (1-weibcdf(t, 2, 2));
plot(t, h1, '--', t, h2, '-')
```
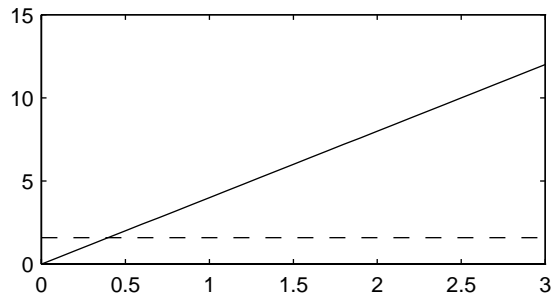
# Descriptive Statistics

Data samples can have thousands (even millions) of values. Descriptive statistics are a way to summarize this data into a few numbers that contain most of the relevant information. The following sections explore the features provided by the Statistics Toolbox for working with descriptive statistics:

- "Measures of Central Tendency (Location)"
- "Measures of Dispersion"
- "Functions for Data with Missing Values (NaNs)"
- "Function for Grouped Data"
- "Percentiles and Graphical Descriptions"
- "The Bootstrap"

## Measures of Central Tendency (Location)

The purpose of measures of central tendency is to locate the data values on the number line. Another term for these statistics is *measures of location*.

The table gives the function names and descriptions.

| Measures of Location | |
|---|---|
| geomean | Geometric mean |
| harmmean | Harmonic mean |
| mean | Arithmetic average (in MATLAB) |
| median | 50th percentile (in MATLAB) |
| trimmean | Trimmed mean |

The average is a simple and popular estimate of location. If the data sample comes from a normal distribution, then the sample average is also optimal (MVUE of $\mu$).

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Unfortunately, outliers, data entry errors, or glitches exist in almost all real data. The sample average is sensitive to these problems. One bad data value can move the average away from the center of the rest of the data by an arbitrarily large distance.

The median and trimmed mean are two measures that are resistant (robust) to outliers. The median is the 50th percentile of the sample, which will only change slightly if you add a large perturbation to any value. The idea behind the trimmed mean is to ignore a small percentage of the highest and lowest values of a sample when determining the center of the sample.

The geometric mean and harmonic mean, like the average, are not robust to outliers. They are useful when the sample is distributed lognormal or heavily skewed.

The example below shows the behavior of the measures of location for a sample with one outlier.

```
x = [ones(1,6) 100]

x =
     1     1     1     1     1     1   100

locate = [geomean(x) harmmean(x) mean(x) median(x)...
          trimmean(x,25)]

locate =

    1.9307    1.1647   15.1429    1.0000    1.0000
```

You can see that the mean is far from any data value because of the influence of the outlier. The median and trimmed mean ignore the outlying value and describe the location of the rest of the data values.

## Measures of Dispersion

The purpose of measures of dispersion is to find out how spread out the data values are on the number line. Another term for these statistics is measures of spread.

The table gives the function names and descriptions.

| Measures of Dispersion | |
| --- | --- |
| iqr | Interquartile Range |
| mad | Mean Absolute Deviation |
| range | Range |
| std | Standard deviation (in MATLAB) |
| var | Variance (in MATLAB) |

The range (the difference between the maximum and minimum values) is the simplest measure of spread. But if there is an outlier in the data, it will be the minimum or maximum value. Thus, the range is not robust to outliers.

The standard deviation and the variance are popular measures of spread that are optimal for normally distributed samples. The sample variance is the MVUE of the normal parameter $\sigma^2$. The standard deviation is the square root of the variance and has the desirable property of being in the same units as the data. That is, if the data is in meters, the standard deviation is in meters as well. The variance is in meters$^2$, which is more difficult to interpret.

Neither the standard deviation nor the variance is robust to outliers. A data value that is separate from the body of the data can increase the value of the statistics by an arbitrarily large amount.

The Mean Absolute Deviation (MAD) is also sensitive to outliers. But the MAD does not move quite as much as the standard deviation or variance in response to bad data.

The Interquartile Range (IQR) is the difference between the 75th and 25th percentile of the data. Since only the middle 50% of the data affects this measure, it is robust to outliers.

The example below shows the behavior of the measures of dispersion for a sample with one outlier.

```
x = [ones(1,6)  100]

x =
      1     1     1     1     1     1     100

stats = [iqr(x)  mad(x)  range(x)  std(x)]

stats =
        0    24.2449    99.0000    37.4185
```

## Functions for Data with Missing Values (NaNs)

Most real-world data sets have one or more missing elements. It is convenient to code missing entries in a matrix as NaN (Not a Number).

Here is a simple example.

```
m = magic(3);
m([1 5]) = [NaN NaN]

m =
    NaN     1     6
      3   NaN     7
      4     9     2
```

Any arithmetic operation that involves the missing values in this matrix yields NaN, as below.

```
sum(m)

ans =

    NaN   NaN    15
```

Removing cells with NaN would destroy the matrix structure. Removing whole rows that contain NaN would discard real data. Instead, the Statistics Toolbox has a variety of functions that are similar to other MATLAB functions, but that treat NaN values as missing and therefore ignore them in the calculations.

```
nansum(m)

ans =

     7     10     13
```

**NaN Functions**

| nanmax | Maximum ignoring NaNs |
|---|---|
| nanmean | Mean ignoring NaNs |
| nanmedian | Median ignoring NaNs |
| nanmin | Minimum ignoring NaNs |
| nanstd | Standard deviation ignoring NaNs |
| nansum | Sum ignoring NaNs |

In addition, other Statistics Toolbox functions operate only on the numeric values, ignoring NaNs. These include iqr, kurtosis, mad, prctile, range, skewness, and trimmean.

## Function for Grouped Data

As we saw in the previous section, the descriptive statistics functions can compute statistics on each column in a matrix. Sometimes, however, you may have your data arranged differently so that measurements appear in one column or variable, and a grouping code appears in a second column or variable. Although MATLAB's syntax makes it simple to apply functions to a subset of an array, in this case it is simpler to use the grpstats function.

The grpstats function can compute the mean, standard error of the mean, and count (number of observations) for each group defined by one or more grouping variables. If you supply a significance level, it also creates a graph of the group means with confidence intervals.

As an example, load the larger car data set. We can look at the average value of MPG (miles per gallon) for cars grouped by org (location of the origin of the car).

```
load carbig
grpstats(MPG, org, 0.05)
ans =
        20.084
        27.891
        30.451
```


Means and Confidence Intervals for Each Group
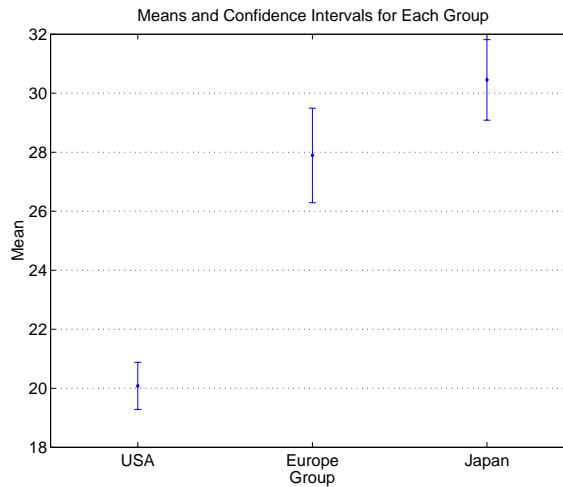
We can also get the complete set of statistics for MPG grouped by three variables:
org, cyl4 (the engine has four cylinders or not), and when (when the car was
made).

```
[m, s, c, n] = grpstats(MPG, {org cyl4 when});
[n num2cell([m s c])]

ans =

    'USA'       'Other'     'Early'     [14.896]    [0.33306]    [77]
    'USA'       'Other'     'Mid'       [17.479]    [0.30225]    [75]
    'USA'       'Other'     'Late'      [21.536]    [0.97961]    [25]
    'USA'       'Four'      'Early'     [23.333]    [0.87328]    [12]
    'USA'       'Four'      'Mid'       [27.027]    [0.75456]    [22]
    'USA'       'Four'      'Late'      [29.734]    [0.71126]    [38]
    'Europe'    'Other'     'Mid'       [  17.5]    [ 0.9478]    [ 4]
    'Europe'    'Other'     'Late'      [30.833]    [ 3.1761]    [ 3]
```

| | | | | | |
|---|---|---|---|---|---|
| 'Europe' | 'Four' | 'Early' | [24.714] | [0.73076] | [21] |
| 'Europe' | 'Four' | 'Mid' | [26.912] | [ 1.0116] | [26] |
| 'Europe' | 'Four' | 'Late' | [  35.7] | [ 1.4265] | [16] |
| 'Japan' | 'Other' | 'Early' | [    19] | [0.57735] | [ 3] |
| 'Japan' | 'Other' | 'Mid' | [20.833] | [0.92796] | [ 3] |
| 'Japan' | 'Other' | 'Late' | [  26.5] | [ 2.0972] | [ 4] |
| 'Japan' | 'Four' | 'Early' | [26.083] | [ 1.1772] | [12] |
| 'Japan' | 'Four' | 'Mid' | [  29.5] | [0.86547] | [25] |
| 'Japan' | 'Four' | 'Late' | [  35.3] | [0.68346] | [32] |

## Percentiles and Graphical Descriptions

Trying to describe a data sample with two numbers, a measure of location and a measure of spread, is frugal but may be misleading.

Another option is to compute a reasonable number of the sample percentiles. This provides information about the shape of the data as well as its location and spread.

The example shows the result of looking at every quartile of a sample containing a mixture of two distributions.

```
x = [normrnd(4, 1, 1, 100)  normrnd(6, 0.5, 1, 200)];
p = 100*(0:0.25:1);
y = prctile(x, p);
z = [p; y]

z =
         0    25.0000    50.0000    75.0000   100.0000
    1.5172     4.6842     5.6706     6.1804     7.6035
```

Compare the first two quantiles to the rest.

The box plot is a graph for descriptive statistics. The graph below is a box plot of the data above.

```
boxplot(x)
```
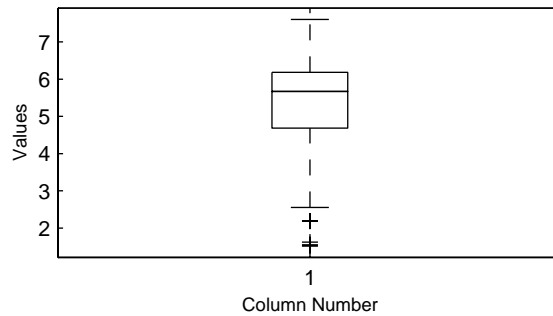
The long lower tail and plus signs show the lack of symmetry in the sample values. For more information on box plots, see "Statistical Plots" on page 1-128.

The histogram is a complementary graph.

hist(x)
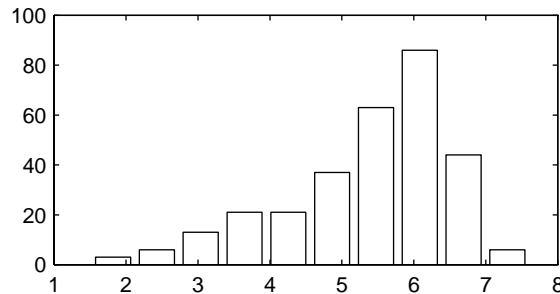


## The Bootstrap

In recent years the statistical literature has examined the properties of resampling as a means to acquire information about the uncertainty of statistical estimators.

The bootstrap is a procedure that involves choosing random samples *with replacement* from a data set and analyzing each sample the same way. Sampling *with replacement* means that every sample is returned to the data set after sampling. So a particular data point from the original data set could appear multiple times in a given bootstrap sample. The number of elements in each bootstrap sample equals the number of elements in the original data set.

The range of sample estimates we obtain allows us to establish the uncertainty of the quantity we are estimating.

Here is an example taken from Efron and Tibshirani (1993) comparing Law School Admission Test (LSAT) scores and subsequent law school grade point average (GPA) for a sample of 15 law schools.

```
load lawdata
plot(lsat, gpa, '+')
lsline
```
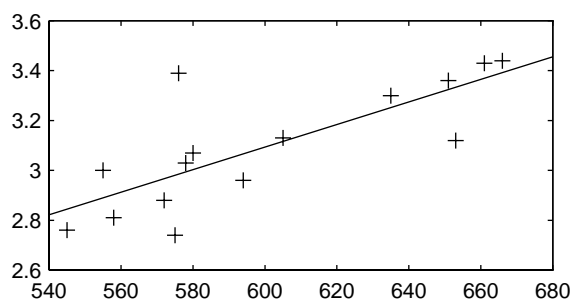


The least squares fit line indicates that higher LSAT scores go with higher law school GPAs. But how sure are we of this conclusion? The plot gives us some intuition but nothing quantitative.

We can calculate the correlation coefficient of the variables using the corrcoef function.

```
rhohat = corrcoef(lsat, gpa)

rhohat =

     1.0000     0.7764
     0.7764     1.0000
```

Now we have a number, 0.7764, describing the positive connection between LSAT and GPA, but though 0.7764 may seem large, we still do not know if it is statistically significant.

Using the bootstrp function we can resample the lsat and gpa vectors as many times as we like and consider the variation in the resulting correlation coefficients.

Here is an example.

```
rhos1000 = bootstrp(1000,'corrcoef',lsat,gpa);
```

This command resamples the lsat and gpa vectors 1000 times and computes the corrcoef function on each sample. Here is a histogram of the result.

```
hist(rhos1000(:,2),30)
```
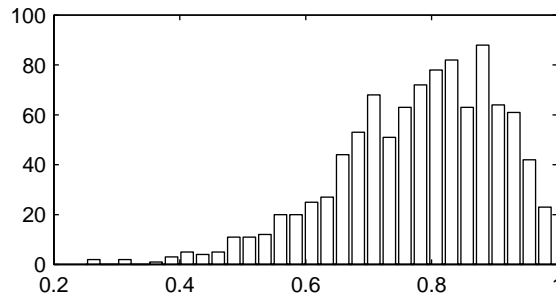


Nearly all the estimates lie on the interval [0.4 1.0].

This is strong quantitative evidence that LSAT and subsequent GPA are positively correlated. Moreover, it does not require us to make any strong assumptions about the probability distribution of the correlation coefficient.

# Cluster Analysis

Cluster analysis, also called segmentation analysis or taxonomy analysis, is a way to partition a set of objects into groups, or *clusters*, in such a way that the profiles of objects in the same cluster are very similar and the profiles of objects in different clusters are quite distinct.

Cluster analysis can be performed on many different types of data sets. For example, a data set might contain a number of observations of subjects in a study where each observation contains a set of variables.

Many different fields of study, such as engineering, zoology, medicine, linguistics, anthropology, psychology, and marketing, have contributed to the development of clustering techniques and the application of such techniques. For example, cluster analysis can be used to find two similar groups for the experiment and control groups in a study. In this way, if statistical differences are found in the groups, they can be attributed to the experiment and not to any initial difference between the groups.

The following sections explore the clustering features in the Statistics Toolbox:

- "Terminology and Basic Procedure"
- "Finding the Similarities Between Objects"
- "Defining the Links Between Objects"
- "Evaluating Cluster Formation"
- "Creating Clusters"

## Terminology and Basic Procedure

To perform cluster analysis on a data set using the Statistics Toolbox functions, follow this procedure:

1 **Find the similarity or dissimilarity between every pair of objects in the data set.** In this step, you calculate the *distance* between objects using the pdist function. The pdist function supports many different ways to compute this measurement. See "Finding the Similarities Between Objects" on page 1-54 for more information.

2 **Group the objects into a binary, hierarchical cluster tree.** In this step, you link together pairs of objects that are in close proximity using the

linkage function. The linkage function uses the distance information generated in step 1 to determine the proximity of objects to each other. As objects are paired into binary clusters, the newly formed clusters are grouped into larger clusters until a hierarchical tree is formed. See "Defining the Links Between Objects" on page 1-56 for more information.

**3 Determine where to divide the hierarchical tree into clusters.** In this step, you divide the objects in the hierarchical tree into clusters using the cluster function. The cluster function can create clusters by detecting natural groupings in the hierarchical tree or by cutting off the hierarchical tree at an arbitrary point. See "Creating Clusters" on page 1-64 for more information.

The following sections provide more information about each of these steps.

---

**Note** The Statistics Toolbox includes a convenience function, clusterdata, which performs all these steps for you. You do not need to execute the pdist, linkage, or cluster functions separately. However, the clusterdata function does not give you access to the options each of the individual routines offers. For example, if you use the pdist function you can choose the distance calculation method, whereas if you use the clusterdata function you cannot.

---

## Finding the Similarities Between Objects

You use the pdist function to calculate the distance between every pair of objects in a data set. For a data set made up of $m$ objects, there are $m \cdot (m-1)/2$ pairs in the data set. The result of this computation is commonly known as a similarity matrix (or dissimilarity matrix).

There are many ways to calculate this distance information. By default, the pdist function calculates the Euclidean distance between objects; however, you can specify one of several other options. See pdist for more information.

**Note** You can optionally normalize the values in the data set before calculating the distance information. In a real world data set, variables can be measured against different scales. For example, one variable can measure Intelligence Quotient (IQ) test scores and another variable can measure head circumference. These discrepancies can distort the proximity calculations. Using the zscore function, you can convert all the values in the data set to use the same proportional scale. See zscore for more information.

For example, consider a data set, X, made up of five objects where each object is a set of *x,y* coordinates.

- **Object 1**: 1, 2
- **Object 2**: 2.5, 4.5
- **Object 3**: 2, 2
- **Object 4**: 4, 1.5
- **Object 5**: 4, 2.5

You can define this data set as a matrix

    X = [1 2; 2.5 4.5; 2 2; 4 1.5; 4 2.5]

and pass it to pdist. The pdist function calculates the distance between object 1 and object 2, object 1 and object 3, and so on until the distances between all the pairs have been calculated. The following figure plots these objects in a graph. The distance between object 2 and object 3 is shown to illustrate one interpretation of distance.
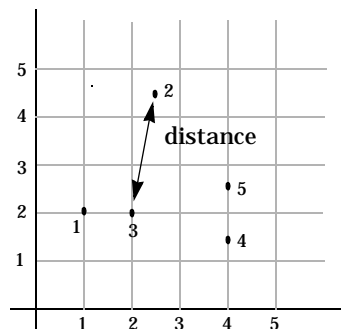
### Returning Distance Information

The pdist function returns this distance information in a vector, Y, where each element contains the distance between a pair of objects.

```
Y = pdist(X)

Y =

  Columns 1 through 7
    2.9155    1.0000    3.0414    3.0414    2.5495    3.3541    2.5000
  Columns 8 through 10
    2.0616    2.0616    1.0000
```

To make it easier to see the relationship between the distance information generated by pdist and the objects in the original data set, you can reformat the distance vector into a matrix using the squareform function. In this matrix, element *i,j* corresponds to the distance between object *i* and object *j* in the original data set. In the following example, element 1,1 represents the distance between object 1 and itself (which is zero). Element 1,2 represents the distance between object 1 and object 2, and so on.

```
squareform(Y)

ans =
         0    2.9155    1.0000    3.0414    3.0414
    2.9155         0    2.5495    3.3541    2.5000
    1.0000    2.5495         0    2.0616    2.0616
    3.0414    3.3541    2.0616         0    1.0000
    3.0414    2.5000    2.0616    1.0000         0
```

## Defining the Links Between Objects

Once the proximity between objects in the data set has been computed, you can determine which objects in the data set should be grouped together into clusters, using the linkage function. The linkage function takes the distance information generated by pdist and links pairs of objects that are close together into binary clusters (clusters made up of two objects). The linkage function then links these newly formed clusters to other objects to create bigger clusters until all the objects in the original data set are linked together in a hierarchical tree.

For example, given the distance vector Y generated by pdist from the sample data set of *x* and *y* coordinates, the linkage function generates a hierarchical cluster tree, returning the linkage information in a matrix, Z.

```
Z = linkage(Y)
Z =
      1.0000      3.0000      1.0000
      4.0000      5.0000      1.0000
      6.0000      7.0000      2.0616
      8.0000      2.0000      2.5000
```

In this output, each row identifies a link. The first two columns identify the objects that have been linked, that is, object 1, object 2, and so on. The third column contains the distance between these objects. For the sample data set of *x* and *y* coordinates, the linkage function begins by grouping together objects 1 and 3, which have the closest proximity (distance value = 1.0000). The linkage function continues by grouping objects 4 and 5, which also have a distance value of 1.0000.

The third row indicates that the linkage function grouped together objects 6 and 7. If our original sample data set contained only five objects, what are objects 6 and 7? Object 6 is the newly formed binary cluster created by the grouping of objects 1 and 3. When the linkage function groups two objects together into a new cluster, it must assign the cluster a unique index value, starting with the value *m*+1, where *m* is the number of objects in the original data set. (Values 1 through *m* are already used by the original data set.) Object 7 is the index for the cluster formed by objects 4 and 5.

As the final cluster, the linkage function grouped object 8, the newly formed cluster made up of objects 6 and 7, with object 2 from the original data set. The following figure graphically illustrates the way linkage groups the objects into a hierarchy of clusters.
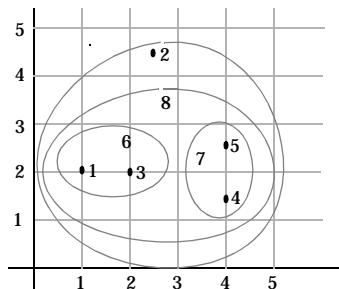
The hierarchical, binary cluster tree created by the linkage function is most easily understood when viewed graphically. The Statistics Toolbox includes the dendrogram function that plots this hierarchical tree information as a graph, as in the following example.

dendrogram(Z)
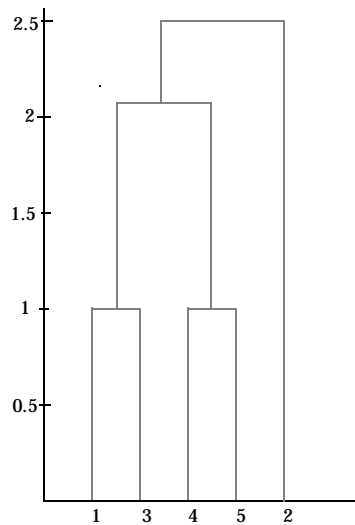


In the figure, the numbers along the horizontal axis represent the indices of the objects in the original data set. The links between objects are represented as upside down U-shaped lines. The height of the U indicates the distance between the objects. For example, the link representing the cluster containing objects 1 and 3 has a height of 1. For more information about creating a dendrogram diagram, see the dendrogram function reference page.

## Evaluating Cluster Formation

After linking the objects in a data set into a hierarchical cluster tree, you may want to verify that the tree represents significant similarity groupings. In addition, you may want more information about the links between the objects. The Statistics Toolbox provides functions to perform both these tasks, as described in the following sections:

- "Verifying the Cluster Tree"
- "Getting More Information About Cluster Links"

### Verifying the Cluster Tree

One way to measure the validity of the cluster information generated by the linkage function is to compare it with the original proximity data generated by the pdist function. If the clustering is valid, the linking of objects in the cluster tree should have a strong correlation with the distances between objects in the distance vector. The cophenet function compares these two sets of values and computes their correlation, returning a value called the *cophenetic correlation coefficient*. The closer the value of the cophenetic correlation coefficient is to 1, the better the clustering solution.

You can use the cophenetic correlation coefficient to compare the results of clustering the same data set using different distance calculation methods or clustering algorithms.

For example, you can use the cophenet function to evaluate the clusters created for the sample data set

```
c = cophenet(Z, Y)
c =
    0.8573
```

where Z is the matrix output by the linkage function and Y is the distance vector output by the pdist function.

Execute pdist again on the same data set, this time specifying the City Block metric. After running the linkage function on this new pdist output, use the cophenet function to evaluate the clustering using a different distance metric.

```
c = cophenet(Z, Y)
c =
    0.9289
```

The cophenetic correlation coefficient shows a stronger correlation when the City Block metric is used.

### Getting More Information About Cluster Links

One way to determine the natural cluster divisions in a data set is to compare the length of each link in a cluster tree with the lengths of neighboring links below it in the tree.

If a link is approximately the same length as neighboring links, it indicates that there are similarities between the objects joined at this level of the hierarchy. These links are said to exhibit a high level of consistency.

If the length of a link differs from neighboring links, it indicates that there are dissimilarities between the objects at this level in the cluster tree. This link is said to be inconsistent with the links around it. In cluster analysis, inconsistent links can indicate the border of a natural division in a data set. The cluster function uses a measure of inconsistency to determine where to divide a data set into clusters. (See "Creating Clusters" on page 1-64 for more information.)

The next section provides an example.

**Example: Inconsistent Links.**  To illustrate, the following example creates a data set of random numbers with three deliberate natural groupings. In the dendrogram, note how the objects tend to collect into three groups. These three groups are then connected by three longer links. These longer links are inconsistent when compared with the links below them in the hierarchy.

```
rand('seed', 3)
X = [rand(10, 2)+1; rand(10, 2)+2; rand(10, 2)+3];
Y = pdist(X);
Z = linkage(Y);
dendrogram(Z);
```

These links show inconsistency when compared to links below them.
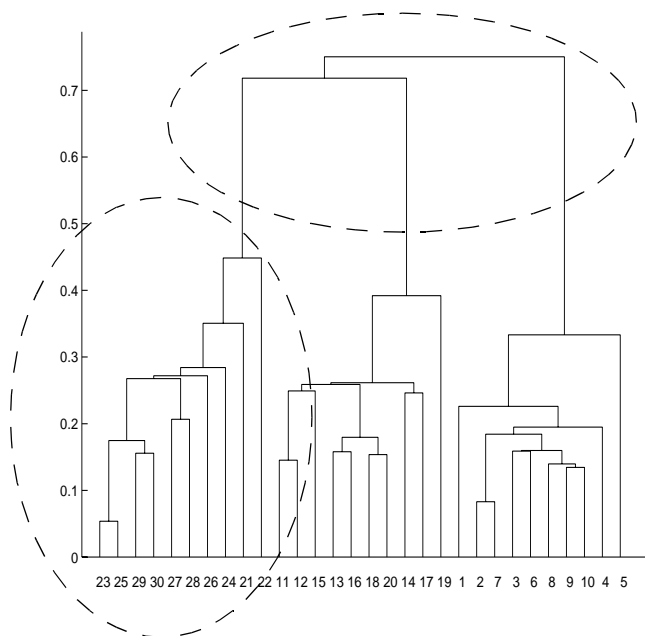


These links show consistency.

The relative consistency of each link in a hierarchical cluster tree can be quantified and expressed as the *inconsistency coefficient*. This value compares the length of a link in a cluster hierarchy with the average length of neighboring links. If the object is consistent with those around it, it will have a low inconsistency coefficient. If the object is inconsistent with those around it, it will have a higher inconsistency coefficient.

To generate a listing of the inconsistency coefficient for each link the cluster tree, use the `inconsistent` function. The `inconsistent` function compares each link in the cluster hierarchy with adjacent links two levels below it in the cluster hierarchy. This is called the *depth* of the comparison. Using the `inconsistent` function, you can specify other depths. The objects at the bottom of the cluster tree, called leaf nodes, that have no further objects below them, have an inconsistency coefficient of zero.

For example, returning to the sample data set of *x* and *y* coordinates, we can use the inconsistent function to calculate the inconsistency values for the links created by the linkage function, described in "Defining the Links Between Objects" on page 1-56.

```
I = inconsistent(Z)
I =
    1.0000         0    1.0000         0
    1.0000         0    1.0000         0
    1.3539    0.8668    3.0000    0.8165
    2.2808    0.3100    2.0000    0.7071
```

The inconsistent function returns data about the links in an (*m*-1)-by-4 matrix where each column provides data about the links.

| Column | Description |
|--------|-------------|
| 1 | Mean of the lengths of all the links included in the calculation |
| 2 | Standard deviation of all the links included in the calculation |
| 3 | Number of links included in the calculation |
| 4 | Inconsistency coefficient |

In the sample output, the first row represents the link between objects 1 and 3. (This cluster is assigned the index 6 by the linkage function.) Because this a leaf node, the inconsistency coefficient is zero. The second row represents the link between objects 4 and 5, also a leaf node. (This cluster is assigned the index 7 by the linkage function.)

The third row evaluates the link that connects these two leaf nodes, objects 6 and 7. (This cluster is called object 8 in the linkage output). Column three indicates that three links are considered in the calculation: the link itself and the two links directly below it in the hierarchy. Column one represents the mean of the lengths of these links. The inconsistent function uses the length information output by the linkage function to calculate the mean. Column two represents the standard deviation between the links. The last column contains the inconsistency value for these links, 0.8165.

The following figure illustrates the links and lengths included in this calculation.
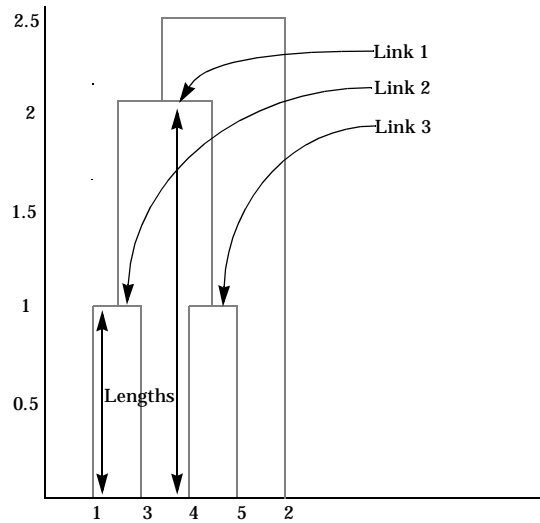


Row four in the output matrix describes the link between object 8 and object 2. Column three indicates that two links are included in this calculation: the link itself and the link directly below it in the hierarchy. The inconsistency coefficient for this link is 0.7071.

The following figure illustrates the links and lengths included in this calculation.
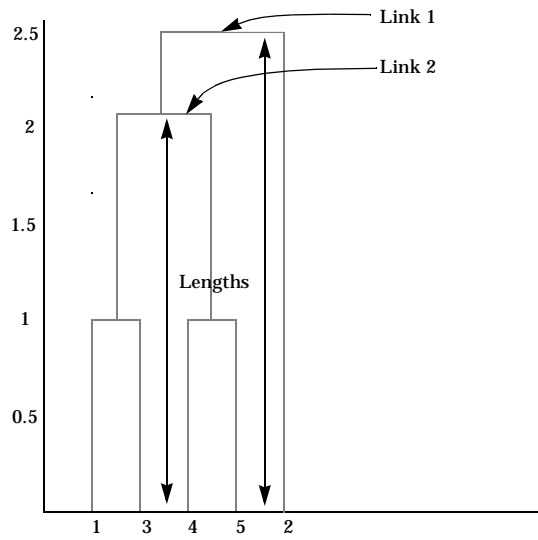


## Creating Clusters

After you create the hierarchical tree of binary clusters, you can divide the hierarchy into larger clusters using the cluster function. The cluster function lets you create clusters in two ways, as discussed in the following sections:

- "Finding the Natural Divisions in the Data Set"
- "Specifying Arbitrary Clusters"

### Finding the Natural Divisions in the Data Set

In the hierarchical cluster tree, the data set may naturally align itself into clusters. This can be particularly evident in a dendrogram diagram where groups of objects are densely packed in certain areas and not in others. The inconsistency coefficient of the links in the cluster tree can identify these points where the similarities between objects change. (See "Evaluating Cluster Formation" on page 1-59 for more information about the inconsistency coefficient.) You can use this value to determine where the cluster function draws cluster boundaries.

For example, if you use the cluster function to group the sample data set into clusters, specifying an inconsistency coefficient threshold of 0.9 as the value of the cutoff argument, the cluster function groups all the objects in the sample data set into one cluster. In this case, none of the links in the cluster hierarchy had an inconsistency coefficient greater than 0.9.

```
T = cluster(Z, 0.9)
T =
     1
     1
     1
     1
     1
```

The cluster function outputs a vector, T, that is the same size as the original data set. Each element in this vector contains the number of the cluster into which the corresponding object from the original data set was placed.

If you lower the inconsistency coefficient threshold to 0.8, the cluster function divides the sample data set into three separate clusters.

```
T = cluster(Z, 0.8)
T =
     1
     3
     1
     2
     2
```

This output indicates that objects 1 and 3 were placed in cluster 1, objects 4 and 5 were placed in cluster 2, and object 2 was placed in cluster 3.

### Specifying Arbitrary Clusters

Instead of letting the cluster function create clusters determined by the natural divisions in the data set, you can specify the number of clusters you want created. In this case, the value of the cutoff argument specifies the point in the cluster hierarchy at which to create the clusters.

For example, you can specify that you want the cluster function to divide the sample data set into two clusters. In this case, the cluster function creates one cluster containing objects 1, 3, 4, and 5 and another cluster containing object 2.

```
T = cluster(Z, 2)
T =
     1
     2
     1
     1
     1
```

To help you visualize how the cluster function determines how to create these clusters, the following figure shows the dendrogram of the hierarchical cluster tree. When you specify a value of 2, the cluster function draws an imaginary horizontal line across the dendrogram that bisects two vertical lines. All the objects below the line belong to one of these two clusters.
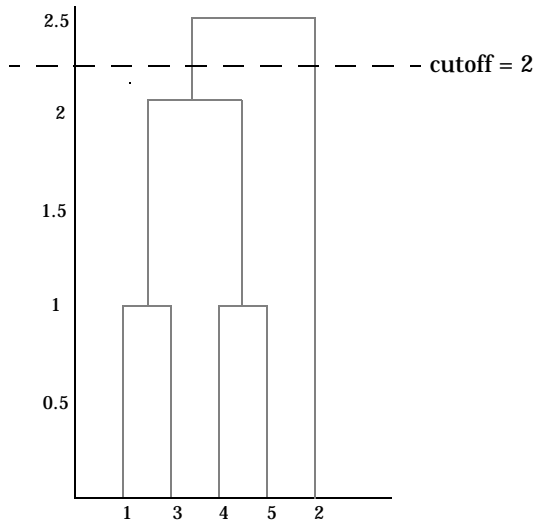


If you specify a cutoff value of 3, the cluster function cuts off the hierarchy at a lower point, bisecting three lines.

```
T = cluster(Z, 3)
T =
     1
     3
     1
     2
     2
```

This time, objects 1 and 3 are grouped in a cluster, objects 4 and 5 are grouped in a cluster, and object 2 is placed into a cluster, as seen in the following figure.
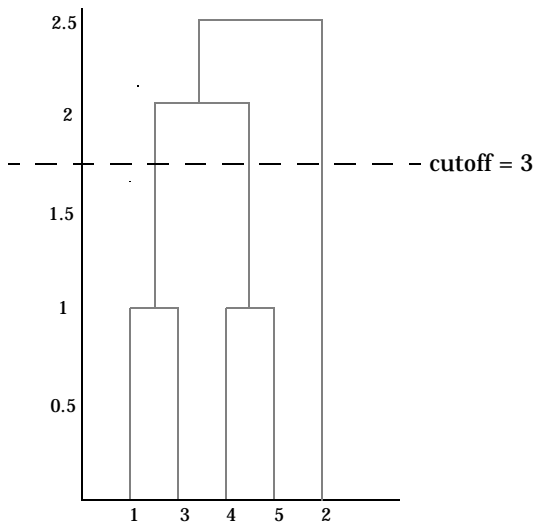
# Linear Models

Linear models represent the relationship between a continuous response variable and one or more predictor variables (either continuous or categorical) in the form

$$y = X\beta + \varepsilon$$

where:

- $y$ is an $n$-by-1 vector of observations of the response variable.
- $X$ is the $n$-by-$p$ design matrix determined by the predictors.
- $\beta$ is a $p$-by-1 vector of parameters.
- $\varepsilon$ is an $n$-by-1 vector of random disturbances, independent of each other and usually having a normal distribution.

MATLAB uses this general form of the linear model to solve a variety of specific regression and analysis of variance (ANOVA) problems. For example, for polynomial and multiple regression problems, the columns of $X$ are predictor variable values or powers of such values. For one-way, two-way, and higher-way ANOVA models, the columns of $X$ are dummy (or indicator) variables that encode the predictor categories. For analysis of covariance (ANOCOVA) models, $X$ contains values of a continuous predictor and codes for a categorical predictor.

The following sections describe a number of functions for fitting various types of linear models:

- "One-Way Analysis of Variance (ANOVA)"
- "Two-Way Analysis of Variance (ANOVA)"
- "N-Way Analysis of Variance"
- "Multiple Linear Regression"
- "Quadratic Response Surface Models"
- "Stepwise Regression"
- "Generalized Linear Models"
- "Robust and Nonparametric Methods"

See the sections below for a tour of some of the related graphical tools:

- "The polytool Demo" on page 1-156
- "The aoctool Demo" on page 1-161
- "The rsmdemo Demo" on page 1-170

# One-Way Analysis of Variance (ANOVA)

The purpose of one-way ANOVA is to find out whether data from several groups have a common mean. That is, to determine whether the groups are actually different in the measured characteristic.

One-way ANOVA is a simple special case of the linear model. The one-way ANOVA form of the model is

$$y_{ij} = \alpha_{.j} + \varepsilon_{ij}$$

where:

- $y_{ij}$ is a matrix of observations in which each column represents a different group.
- $\alpha_{.j}$ is a matrix whose columns are the group means. (The "dot j" notation means that $\alpha$ applies to all rows of the $j$th column. That is, the value $\alpha_{ij}$ is the same for all $i$.)
- $\varepsilon_{ij}$ is a matrix of random disturbances.

The model posits that the columns of $y$ are a constant plus a random disturbance. You want to know if the constants are all the same.

The following sections explore one-way ANOVA in greater detail:

- "Example: One-Way ANOVA"
- "Multiple Comparisons"

### Example: One-Way ANOVA

The data below comes from a study by Hogg and Ledolter (1987) of bacteria counts in shipments of milk. The columns of the matrix hogg represent different shipments. The rows are bacteria counts from cartons of milk chosen randomly from each shipment. Do some shipments have higher counts than others?

```
load hogg
hogg

hogg =

    24    14    11     7    19
    15     7     9     7    24
    21    12     7     4    19
    27    17    13     7    15
    33    14    12    12    10
    23    16    18    18    20

[p,tbl,stats] = anova1(hogg);
p

p =
   1.1971e-04
```
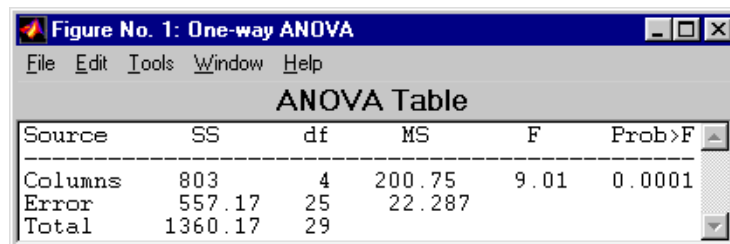
The standard ANOVA table has columns for the sums of squares, degrees of freedom, mean squares (SS/df), F statistic, and p-value.

| Figure No. 1: One-way ANOVA | | | | | |
|---|---|---|---|---|---|
| File Edit Tools Window Help | | | | | |

**ANOVA Table**

| Source | SS | df | MS | F | Prob>F |
|---|---|---|---|---|---|
| Columns | 803 | 4 | 200.75 | 9.01 | 0.0001 |
| Error | 557.17 | 25 | 22.287 | | |
| Total | 1360.17 | 29 | | | |

You can use the F statistic to do a hypothesis test to find out if the bacteria counts are the same. anova1 returns the p-value from this hypothesis test.

In this case the p-value is about 0.0001, a very small value. This is a strong indication that the bacteria counts from the different tankers are not the same. An F statistic as extreme as the observed F would occur by chance only once in 10,000 times if the counts were truly equal.

The p-value returned by anova1 depends on assumptions about the random disturbances $\varepsilon_{ij}$ in the model equation. For the p-value to be correct, these disturbances need to be independent, normally distributed, and have constant variance. See "Robust and Nonparametric Methods" on page 1-95 for a nonparametric function that does not require a normal assumption.

You can get some graphical assurance that the means are different by looking at the box plots in the second figure window displayed by anova1.
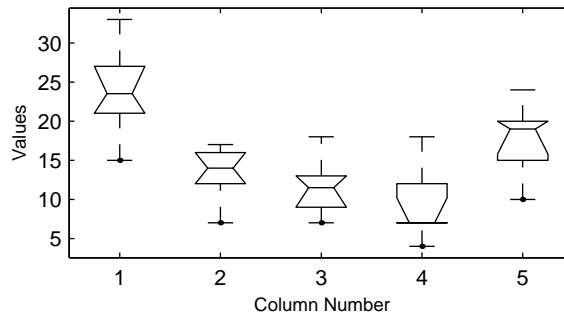


### Multiple Comparisons

Sometimes you need to determine not just if there are any differences among the means, but specifically which pairs of means are significantly different. It is tempting to perform a series of t tests, one for each pair of means, but this procedure has a pitfall.

In a t test, we compute a t statistic and compare it to a critical value. The critical value is chosen so that when the means are really the same (any apparent difference is due to random chance), the probability that the t statistic will exceed the critical value is small, say 5%. When the means are different, the probability that the statistic will exceed the critical value is larger.

In this example there are five means, so there are 10 pairs of means to compare. It stands to reason that if all the means are the same, and if we have a 5% chance of incorrectly concluding that there is a difference in one pair, then the probability of making at least one incorrect conclusion among all 10 pairs is much larger than 5%.

Fortunately, there are procedures known as *multiple comparison procedures* that are designed to compensate for multiple tests.

**Example: Multiple Comparisons.** You can perform a multiple comparison test using the multcompare function and supplying it with the stats output from anova1.

```
[c, m] = multcompare(stats)

c =
     1.0000      2.0000      2.4953     10.5000     18.5047
     1.0000      3.0000      4.1619     12.1667     20.1714
     1.0000      4.0000      6.6619     14.6667     22.6714
     1.0000      5.0000     -2.0047      6.0000     14.0047
     2.0000      3.0000     -6.3381      1.6667      9.6714
     2.0000      4.0000     -3.8381      4.1667     12.1714
     2.0000      5.0000    -12.5047     -4.5000      3.5047
     3.0000      4.0000     -5.5047      2.5000     10.5047
     3.0000      5.0000    -14.1714     -6.1667      1.8381
     4.0000      5.0000    -16.6714     -8.6667     -0.6619

m =
    23.8333      1.9273
    13.3333      1.9273
    11.6667      1.9273
     9.1667      1.9273
    17.8333      1.9273
```

The first output from multcompare has one row for each pair of groups, with an estimate of the difference in group means and a confidence interval for that group. For example, the second row has the values

```
     1.0000      3.0000      4.1619     12.1667     20.1714
```

indicating that the mean of group 1 minus the mean of group 3 is estimated to be 12.1667, and a 95% confidence interval for this difference is [4.1619, 20.1714]. This interval does not contain 0, so we can conclude that the means of groups 1 and 3 are different.

The second output contains the mean and its standard error for each group.

It is easier to visualize the difference between group means by looking at the graph that multcompare produces.
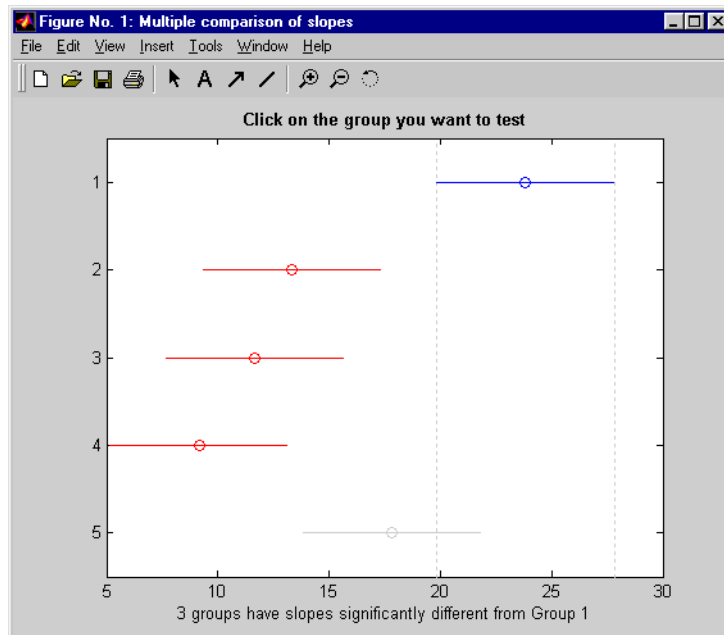
The graph shows that group 1 is significantly different from groups 2, 3, and 4. By using the mouse to select group 4, you can determine that it is also significantly different from group 5. Other pairs are not significantly different.

## Two-Way Analysis of Variance (ANOVA)

The purpose of two-way ANOVA is to find out whether data from several groups have a common mean. One-way ANOVA and two-way ANOVA differ in that the groups in two-way ANOVA have two categories of defining characteristics instead of one.

Suppose an automobile company has two factories, and each factory makes the same three models of car. It is reasonable to ask if the gas mileage in the cars varies from factory to factory as well as from model to model. We use two predictors, factory and model, to explain differences in mileage.

There could be an overall difference in mileage due to a difference in the production methods between factories. There is probably a difference in the mileage of the different models (irrespective of the factory) due to differences in design specifications. These effects are called *additive*.

Finally, a factory might make high mileage cars in one model (perhaps because of a superior production line), but not be different from the other factory for other models. This effect is called an *interaction*. It is impossible to detect an interaction unless there are duplicate observations for some combination of factory and car model.

Two-way ANOVA is a special case of the linear model. The two-way ANOVA form of the model is

$$y_{ijk} = \mu + \alpha_{.j} + \beta_{i.} + \gamma_{ij} + \varepsilon_{ijk}$$

where, with respect to the automobile example above:

- $y_{ijk}$ is a matrix of gas mileage observations (with row index $i$, column index $j$, and repetition index $k$).
- $\mu$ is a constant matrix of the overall mean gas mileage.
- $\alpha_{.j}$ is a matrix whose columns are the deviations of each car's gas mileage (from the mean gas mileage $\mu$) that are attributable to the car's *model*. All values in a given column of $\alpha_{.j}$ are identical, and the values in each row of $\alpha_{.j}$ sum to 0.
- $\beta_{i.}$ is a matrix whose rows are the deviations of each car's gas mileage (from the mean gas mileage $\mu$) that are attributable to the car's *factory*. All values in a given row of $\beta_{i.}$ are identical, and the values in each column of $\beta_{i.}$ sum to 0.
- $\gamma_{ij}$ is a matrix of interactions. The values in each row of $\gamma_{ij}$ sum to 0, and the values in each column of $\gamma_{ij}$ sum to 0.
- $\varepsilon_{ijk}$ is a matrix of random disturbances.

The next section provides an example of a two-way analysis.

### Example: Two-Way ANOVA

The purpose of the example is to determine the effect of car model and factory on the mileage rating of cars.

```
load mileage
mileage
```

```
mileage =

    33.3000    34.5000    37.4000
    33.4000    34.8000    36.8000
    32.9000    33.8000    37.6000
    32.6000    33.4000    36.6000
    32.5000    33.7000    37.0000
    33.0000    33.9000    36.7000

cars = 3;
[p,tbl,stats] = anova2(mileage,cars);
p

p =
    0.0000    0.0039    0.8411
```
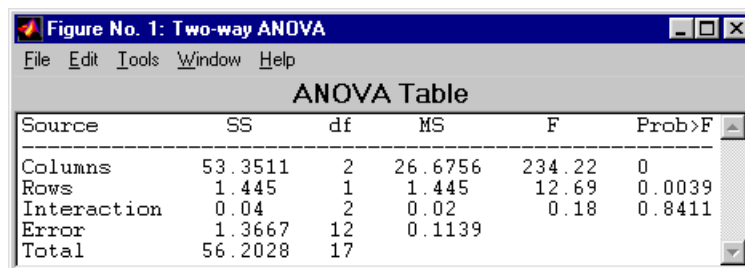
There are three models of cars (columns) and two factories (rows). The reason there are six rows in mileage instead of two is that each factory provides three cars of each model for the study. The data from the first factory is in the first three rows, and the data from the second factory is in the last three rows.

The standard ANOVA table has columns for the sums of squares, degrees-of-freedom, mean squares (SS/df), F statistics, and p-values.



You can use the F statistics to do hypotheses tests to find out if the mileage is the same across models, factories, and model-factory pairs (after adjusting for the additive effects). anova2 returns the p-value from these tests.

The p-value for the model effect is zero to four decimal places. This is a strong indication that the mileage varies from one model to another. An F statistic as extreme as the observed F would occur by chance less than once in 10,000 times if the gas mileage were truly equal from model to model. If you used the

mul tcompare function to perform a multiple comparison test, you would find that each pair of the three models is significantly different.

The p-value for the factory effect is 0.0039, which is also highly significant. This indicates that one factory is out-performing the other in the gas mileage of the cars it produces. The observed p-value indicates that an F statistic as extreme as the observed F would occur by chance about four out of 1000 times if the gas mileage were truly equal from factory to factory.

There does not appear to be any interaction between factories and models. The p-value, 0.8411, means that the observed result is quite likely (84 out 100 times) given that there is no interaction.

The p-values returned by anova2 depend on assumptions about the random disturbances $\varepsilon_{ijk}$ in the model equation. For the p-values to be correct these disturbances need to be independent, normally distributed, and have constant variance. See "Robust and Nonparametric Methods" on page 1-95 for nonparametric methods that do not require a normal distribution.

In addition, anova2 requires that data be *balanced*, which in this case means there must be the same number of cars for each combination of model and factory. The next section discusses a function that supports unbalanced data with any number of predictors.

## N-Way Analysis of Variance

You can use N-way ANOVA to determine if the means in a set of data differ when grouped by multiple factors. If they do differ, you can determine which factors or combinations of factors are associated with the difference.

N-way ANOVA is a generalization of two-way ANOVA. For three factors, the model can be written

$$y_{ijkl} = \mu + \alpha_{.j.} + \beta_{i..} + \gamma_{..k} + (\alpha\beta)_{ij.} + (\alpha\gamma)_{i.k} + (\beta\gamma)_{.jk} + (\alpha\beta\gamma)_{ijk} + \varepsilon_{ijkl}$$

In this notation parameters with two subscripts, such as $(\alpha\beta)_{ij.}$, represent the interaction effect of two factors. The parameter $(\alpha\beta\gamma)_{ijk}$ represents the three-way interaction. An ANOVA model can have the full set of parameters or any subset, but conventionally it does not include complex interaction terms unless it also includes all simpler terms for those factors. For example, one would generally not include the three-way interaction without also including all two-way interactions.

The anovan function performs N-way ANOVA. Unlike the anova1 and anova2 functions, anovan does not expect data in a tabular form. Instead, it expects a vector of response measurements and a separate vector (or text array) containing the values corresponding to each factor. This input data format is more convenient than matrices when there are more than two factors or when the number of measurements per factor combination is not constant.

The following examples explore anovan in greater detail:

- "Example: N-Way ANOVA with Small Data Set"
- "Example: N-Way ANOVA with Large Data Set"

### Example: N-Way ANOVA with Small Data Set

Consider the following two-way example using anova2.

```
m = [23 15 20; 27 17 63; 43 3 55; 41 9 90]
m =
    23    15    20
    27    17    63
    43     3    55
    41     9    90

anova2(m, 2)

ans =
    0.0197    0.2234    0.2663
```

The factor information is implied by the shape of the matrix m and the number of measurements at each factor combination (2). Although anova2 does not actually require arrays of factor values, for illustrative purposes we could create them as follows.

```
cfactor = repmat(1:3, 4, 1)

cfactor =

     1     2     3
     1     2     3
     1     2     3
     1     2     3
```

```
rfactor = [ones(2, 3);  2*ones(2, 3)]

rfactor =

     1      1      1
     1      1      1
     2      2      2
     2      2      2
```

The cfactor matrix shows that each column of m represents a different level of the column factor. The rfactor matrix shows that the top two rows of m represent one level of the row factor, and bottom two rows of m represent a second level of the row factor. In other words, each value m(i,j) represents an observation at column factor level cfactor(i,j) and row factor level cfactor(i,j).

To solve the above problem with anovan, we need to reshape the matrices m, cfactor, and rfactor to be vectors.

```
m = m(:);
cfactor = cfactor(:);
rfactor = rfactor(:);

[m cfactor rfactor]

ans =

    23      1      1
    27      1      1
    43      1      2
    41      1      2
    15      2      1
    17      2      1
     3      2      2
     9      2      2
    20      3      1
    63      3      1
    55      3      2
    90      3      2
```

```
anovan(m, {cfactor rfactor}, 2)

ans =

    0.0197
    0.2234
    0.2663
```

### Example: N-Way ANOVA with Large Data Set

In the previous example we used anova2 to study a small data set measuring car mileage. Now we study a larger set of car data with mileage and other information on 406 cars made between 1970 and 1982. First we load the data set and look at the variable names.

```
load carbig
whos

  Name             Size          Bytes  Class

  Acceleration     406x1          3248  double array
  Cylinders        406x1          3248  double array
  Displacement     406x1          3248  double array
  Horsepower       406x1          3248  double array
  MPG              406x1          3248  double array
  Model            406x36        29232  char array
  Model_Year       406x1          3248  double array
  Origin           406x7          5684  char array
  Weight           406x1          3248  double array
  cyl4             406x5          4060  char array
  org              406x7          5684  char array
  when             406x5          4060  char array
```

We will focus our attention on four variables. MPG is the number of miles per gallon for each of 406 cars (though some have missing values coded as NaN). The other three variables are factors: cyl4 (four-cylinder car or not), org (car originated in Europe, Japan, or the USA), and when (car was built early in the period, in the middle of the period, or late in the period).

First we fit the full model, requesting up to three-way interactions and Type 3 sums-of-squares.

```
varnames = {'Origin';'4Cyl';'MfgDate'};
anovan(MPG, {org cyl4 when}, 3, 3, varnames)

ans =
    0.0000
       NaN
         0
    0.7032
    0.0001
    0.2072
    0.6990
```



Note that many terms are marked by a "#" symbol as not having full rank, and one of them has zero degrees of freedom and is missing a p-value. This can happen when there are missing factor combinations and the model has higher-order terms. In this case, the cross-tabulation below shows that there are no cars made in Europe during the early part of the period with other than four cylinders, as indicated by the 0 in table(2, 1, 1).

```
[table, factorvals] = crosstab(org, when, cyl4)

table(:,:,1) =

    82    75    25
     0     4     3
     3     3     4
```

```
table(:,:,2) =

     12      22      38
     23      26      17
     12      25      32

factorvals =

     'USA'        'Early'      'Other'
     'Europe'     'Mid'        'Four'
     'Japan'      'Late'          []
```

Consequently it is impossible to estimate the three-way interaction effects, and including the three-way interaction term in the model makes the fit singular.

Using even the limited information available in the ANOVA table, we can see that the three-way interaction has a p-value of 0.699, so it is not significant. We decide to request only two-way interactions this time.
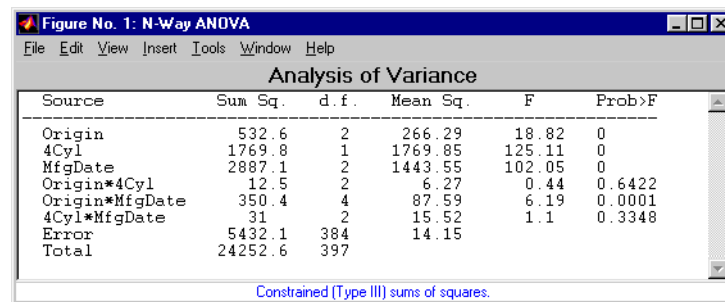
```
[p,tbl,stats,termvec] = anovan(MPG,{org cyl4 when},2,3,varnames);
termvec'

ans =

     1       2       4       3       5       6
```



Now all terms are estimable. The p-values for interaction term 4 (Origin*4Cyl) and interaction term 6 (4Cyl*MfgDate) are much larger than a typical cutoff value of 0.05, indicating these terms are not significant. We could choose to omit these terms and pool their effects into the error term. The output termvec variable returns a vector of codes, each of which is a bit pattern representing a term. We can omit terms from the model by deleting their

entries from termvec and running anovan again, this time supplying the resulting vector as the model argument.

```
termvec([4 6]) = []

termvec =
      1
      2
      4
      5

anovan(MPG, {org cyl4 when}, termvec, 3, varnames)
```
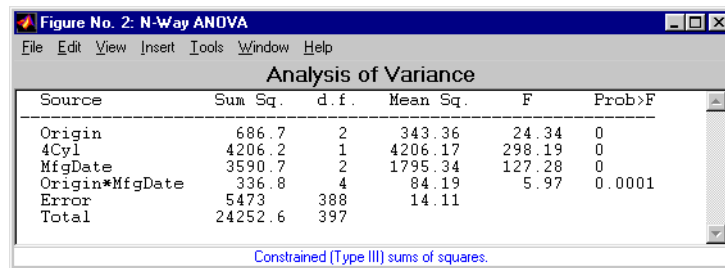


Now we have a more parsimonious model indicating that the mileage of these cars seems to be related to all three factors, and that the effect of the manufacturing date depends on where the car was made.

## Multiple Linear Regression

The purpose of multiple linear regression is to establish a quantitative relationship between a group of predictor variables (the columns of *X*) and a response, *y.* This relationship is useful for:

- Understanding which predictors have the greatest effect.
- Knowing the direction of the effect (i.e., increasing *x* increases/decreases *y*).
- Using the model to predict future values of the response when only the predictors are currently known.

The following sections explain multiple linear regression in greater detail:

- "Mathematical Foundations of Multiple Linear Regression"
- "Example: Multiple Linear Regression"

### Mathematical Foundations of Multiple Linear Regression

The linear model takes its common form

$$y = X\beta + \varepsilon$$

where:

- $y$ is an $n$-by-1 vector of observations.
- $X$ is an $n$-by-$p$ matrix of regressors.
- $\beta$ is a $p$-by-1 vector of parameters.
- $\varepsilon$ is an $n$-by-1 vector of random disturbances.

The solution to the problem is a vector, $b$, which estimates the unknown vector of parameters, $\beta$. The least squares solution is

$$b = \hat{\beta} = (X^T X)^{-1} X^T y$$

This equation is useful for developing later statistical formulas, but has poor numeric properties. `regress` uses QR decomposition of $X$ followed by the backslash operator to compute $b$. The QR decomposition is not necessary for computing $b$, but the matrix $R$ is useful for computing confidence intervals.

You can plug $b$ back into the model formula to get the predicted $y$ values at the data points.

$$\hat{y} = Xb = Hy$$
$$H = X(X^T X)^{-1} X^T$$

Statisticians use a hat (circumflex) over a letter to denote an estimate of a parameter or a prediction from a model. The projection matrix $H$ is called the *hat matrix*, because it puts the "hat" on $y$.

The residuals are the difference between the observed and predicted $y$ values.

$$r = y - \hat{y} = (I - H)y$$

The residuals are useful for detecting failures in the model assumptions, since they correspond to the errors, $\varepsilon$, in the model equation. By assumption, these errors each have independent normal distributions with mean zero and a constant variance.

The residuals, however, are correlated and have variances that depend on the locations of the data points. It is a common practice to scale ("Studentize") the residuals so they all have the same variance.

In the equation below, the scaled residual, $t_i$, has a Student's t distribution with ($n$-$p$-1) degrees of freedom

$$t_i = \frac{r_i}{\hat{\sigma}_{(i)}\sqrt{1 - h_i}}$$

where

$$\hat{\sigma}^2_{(i)} = \frac{\|r\|^2}{n - p - 1} - \frac{r_i^2}{(n - p - 1)(1 - h_i)}$$

and:

- $t_i$ is the scaled residual for the $i$th data point.
- $r_i$ is the raw residual for the $i$th data point.
- $n$ is the sample size.
- $p$ is the number of parameters in the model.
- $h_i$ is the $i$th diagonal element of $H$.

The left-hand side of the second equation is the estimate of the variance of the errors excluding the $i$th data point from the calculation.

A hypothesis test for outliers involves comparing $t_i$ with the critical values of the t distribution. If $t_i$ is large, this casts doubt on the assumption that this residual has the same variance as the others.

A confidence interval for the mean of each error is

$$c_i = r_i \pm t_{\left(1 - \frac{\alpha}{2}, v\right)} \hat{\sigma}_{(i)}\sqrt{1 - h_i}$$

Confidence intervals that do not include zero are equivalent to rejecting the hypothesis (at a significance probability of $\alpha$) that the residual mean is zero. Such confidence intervals are good evidence that the observation is an outlier for the given model.

### Example: Multiple Linear Regression

The example comes from Chatterjee and Hadi (1986) in a paper on regression diagnostics. The data set (originally from Moore (1975)) has five predictor variables and one response.

```
load moore
X = [ones(size(moore,1),1) moore(:,1:5)];
```

Matrix X has a column of ones, and then one column of values for each of the five predictor variables. The column of ones is necessary for estimating the *y*-intercept of the linear model.

```
y = moore(:,6);
[b,bint,r,rint,stats] = regress(y,X);
```

The *y*-intercept is b(1), which corresponds to the column index of the column of ones.

```
stats
stats =

    0.8107   11.9886    0.0001
```

The elements of the vector stats are the regression $R^2$ statistic, the F statistic (for the hypothesis test that all the regression coefficients are zero), and the p-value associated with this F statistic.

$R^2$ is 0.8107 indicating the model accounts for over 80% of the variability in the observations. The F statistic of about 12 and its p-value of 0.0001 indicate that it is highly unlikely that all of the regression coefficients are zero.

```
rcoplot(r,rint)
```
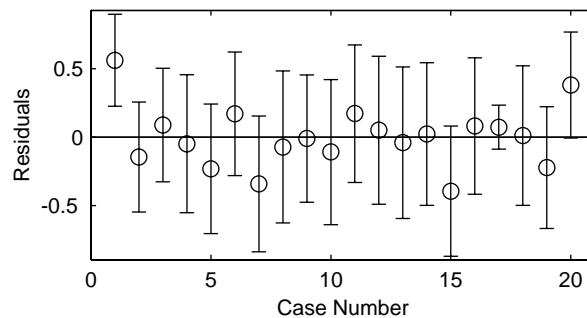
The plot shows the residuals plotted in case order (by row). The 95% confidence intervals about these residuals are plotted as error bars. The first observation is an outlier since its error bar does not cross the zero reference line.

In problems with just a single predictor, it is simpler to use the polytool function (see "The polytool Demo" on page 1-156). This function can form an *X* matrix with predictor values, their squares, their cubes, and so on.

## Quadratic Response Surface Models

Response Surface Methodology (RSM) is a tool for understanding the quantitative relationship between multiple input variables and one output variable.

Consider one output, *z*, as a polynomial function of two inputs, *x* and *y*. The function $z = f(x,y)$ describes a two-dimensional surface in the space $(x,y,z)$. Of course, you can have as many input variables as you want and the resulting surface becomes a hypersurface. You can have multiple output variables with a separate hypersurface for each one.

For three inputs $(x_1, x_2, x_3)$, the equation of a quadratic response surface is

$$y = b_0 + b_1 x_1 + b_2 x_2 + b_3 x_3 + \dots \qquad \text{(linear terms)}$$

$$+ b_{12} x_1 x_2 + b_{13} x_1 x_3 + b_{23} x_2 x_3 + \dots \qquad \text{(interaction terms)}$$

$$+ b_{11} x_1^2 + b_{22} x_2^2 + b_{33} x_3^2 \qquad \text{(quadratic terms)}$$

It is difficult to visualize a *k*-dimensional surface in *k*+1 dimensional space for *k*>2. The function rstool is a graphical user interface (GUI) designed to make this visualization more intuitive, as is discussed in the next section.

### Exploring Graphs of Multidimensional Polynomials

The function rstool is useful for fitting response surface models. The purpose of rstool is larger than just fitting and prediction for polynomial models. This GUI provides an environment for exploration of the graph of a multidimensional polynomial.

You can learn about rstool by trying the commands below. The chemistry behind the data in reaction.mat deals with reaction kinetics as a function of

the partial pressure of three chemical reactants: hydrogen, n-pentane, and isopentane.

```
load reaction
rstool(reactants, rate, 'quadratic', 0.01, xn, yn)
```

You will see a "vector" of three plots. The dependent variable of all three plots is the reaction rate. The first plot has hydrogen as the independent variable. The second and third plots have n-pentane and isopentane respectively.

Each plot shows the fitted relationship of the reaction rate to the independent variable at a fixed value of the other two independent variables. The fixed value of each independent variable is in an editable text box below each axis. You can change the fixed value of any independent variable by either typing a new value in the box or by dragging any of the three vertical lines to a new position.

When you change the value of an independent variable, all the plots update to show the current picture at the new point in the space of the independent variables.

Note that while this example only uses three inputs (reactants) and one output (rate), rstool can accommodate an arbitrary number of inputs and outputs. Interpretability may be limited by the size of the monitor for large numbers of inputs or outputs.

The GUI also has two pop-up menus. The **Export** menu facilitates saving various important variables in the GUI to the base workspace. Below the **Export** menu there is another menu that allows you to change the order of the polynomial model from within the GUI. If you used the commands above, this menu will have the string **Full Quadratic**. Other choices are:

• **Linear** – has the constant and first order terms only.

• **Pure Quadratic** – includes constant, linear and squared terms.

• **Interactions** – includes constant, linear, and cross product terms.

The rstool GUI is used by the rsmdemo function to visualize the results of a designed experiment for studying a chemical reaction. See "The rsmdemo Demo" on page 1-170.

## Stepwise Regression

Stepwise regression is a technique for choosing the variables to include in a multiple regression model. Forward stepwise regression starts with no model terms. At each step it adds the most statistically significant term (the one with the highest F statistic or lowest p-value) until there are none left. Backward stepwise regression starts with all the terms in the model and removes the least significant terms until all the remaining terms are statistically significant. It is also possible to start with a subset of all the terms and then add significant terms or remove insignificant terms.

An important assumption behind the method is that some input variables in a multiple regression do not have an important explanatory effect on the response. If this assumption is true, then it is a convenient simplification to keep only the statistically significant terms in the model.

One common problem in multiple regression analysis is multicollinearity of the input variables. The input variables may be as correlated with each other as they are with the response. If this is the case, the presence of one input variable in the model may mask the effect of another input. Stepwise regression used as a canned procedure is a dangerous tool because the resulting model may include different variables depending on the choice of starting model and inclusion strategy.

The following example explores an interactive tool for stepwise regression.

### Example: Stepwise Regression

The Statistics Toolbox provides an interactive graphical user interface (GUI) to make comparison of competing models more understandable. You can explore the GUI using the Hald (1960) data set. Here are the commands to get started.

```
load hald
stepwise(ingredients, heat)
```

The Hald data come from a study of the heat of reaction of various cement mixtures. There are four components in each mixture, and the amount of heat produced depends on the amount of each ingredient in the mixture.

The interface consists of three interactively linked figure windows. Two of these are discussed in the following sections:

- "Stepwise Regression Plot"
- "Stepwise Regression Diagnostics Table"

All three windows have *hot* regions. When your mouse is above one of these regions, the pointer changes from an arrow to a circle. Clicking on this point initiates some activity in the interface.

### Stepwise Regression Plot

This plot shows the regression coefficient and confidence interval for every term (in or out of the model). The green lines represent terms in the model while red lines indicate terms that are not currently in the model.

Statistically significant terms are solid lines. Dotted lines show that the fitted coefficient is not significantly different from zero.

Clicking on a line in this plot toggles its state. That is, a term currently in the model (green line) is removed (turns red), and a term currently not in the model (red line) is added (turns green).

The coefficient for a term out of the model is the coefficient resulting from adding that term to the current model.

Scale Inputs. Pressing this button centers and normalizes the columns of the input matrix to have a standard deviation of one.

Export. This pop-up menu allows you to export variables from the stepwise function to the base workspace.

Close. The **Close** button removes all the figure windows.

### Stepwise Regression Diagnostics Table

This table is a quantitative view of the information in the Stepwise Regression Plot. The table shows the Hald model with the second and third terms removed.

| Column # | Parameter | Confidence Intervals | |
|---|---|---|---|
| | | Lower | Upper |
| 1 | 1.44 | 1.02 | 1.86 |
| 2 | 0.4161 | −0.1602 | 0.9924 |
| 3 | −0.41 | −1.029 | 0.2086 |
| 4 | −0.614 | −0.7615 | −0.4664 |

| RMSE | R-square | F | P |
|---|---|---|---|
| 2.734 | 0.9725 | 176.6 | 1.581e-08 |

**Coefficients and Confidence Intervals.** The table at the top of the figure shows the regression coefficient and confidence interval for every term (in or out of the model.) The green rows in the table (on your monitor) represent terms in the model while red rows indicate terms not currently in the model.

Clicking on a row in this table toggles the state of the corresponding term. That is, a term currently in the model (green row) is removed (turns red), and a term currently not in the model (red row) is added to the model (turns green).

The coefficient for a term out of the model is the coefficient resulting from adding that term to the current model.

**Additional Diagnostic Statistics.** There are also several diagnostic statistics at the bottom of the table:

- RMSE – the root mean squared error of the current model.
- R-square – the amount of response variability explained by the model.
- F – the overall F statistic for the regression.
- P – the associated significance probability.

**Close Button.** Shuts down all windows.

**Help Button.** Activates online help.

**Stepwise History.** This plot shows the RMSE and a confidence interval for every model generated in the course of the interactive use of the other windows.

**Recreating a Previous Model.** Clicking on one of these lines recreates the current model at that point in the analysis using a *new* set of windows. You can thus compare the two candidate models directly.

## Generalized Linear Models

So far, the functions in this section have dealt with models that have a linear relationship between the response and one or more predictors. Sometimes you may have a nonlinear relationship instead. To fit nonlinear models you can use the functions described in "Nonlinear Regression Models" on page 1-100.

There are some nonlinear models, known as generalized linear models, that you can fit using simpler linear methods. To understand generalized linear models, first let's review the linear models we have seen so far. Each of these models has the following three characteristics:

- The response has a normal distribution with mean $\mu$.
- A coefficient vector $b$ defines a linear combination $X*b$ of the predictors $X$.
- The model equates the two as $\mu = X*b$.

In generalized linear models, these characteristics are generalized as follows:

- The response has a distribution that may be normal, binomial, Poisson, gamma, or inverse Gaussian, with parameters including a mean $\mu$.
- A coefficient vector $b$ defines a linear combination $X*b$ of the predictors $X$.
- A link function $f(\cdot)$ defines the link between the two as $f(\mu) = X*b$.

The following example explores this in greater detail.

### Example: Generalized Linear Models

For example, consider the following data derived from the `carbig` data set. We have cars of various weights, and we record the total number of cars of each weight and the number qualifying as poor-mileage cars because their miles per gallon value is below some target. (Suppose we don't know the miles per gallon for each car, only the number passing the test.) It might be reasonable to

assume that the value of the variable poor follows a binomial distribution with parameter N=total and with a p parameter that depends on the car weight. A plot shows that the proportion of poor-mileage cars follows a nonlinear S-shape.

```
w = [2100 2300 2500 2700 2900 3100 3300 3500 3700 3900 4100 4300]';
poor = [1 2 0 3 8 8 14 17 19 15 17 21]';
total = [48 42 31 34 31 21 23 23 21 16 17 21]';

[w poor total]
ans =
        2100            1            48
        2300            2            42
        2500            0            31
        2700            3            34
        2900            8            31
        3100            8            21
        3300           14            23
        3500           17            23
        3700           19            21
        3900           15            16
        4100           17            17
        4300           21            21

plot(w, poor./total, 'x')
```
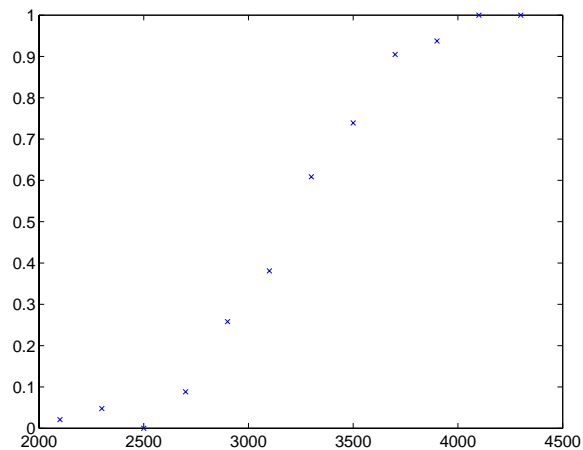
This shape is typical of graphs of proportions, as they have natural boundaries at 0.0 and 1.0.

A linear regression model would not produce a satisfactory fit to this graph. Not only would the fitted line not follow the data points, it would produce invalid proportions less than 0 for light cars, and higher than 1 for heavy cars.

There is a class of regression models for dealing with proportion data. The logistic model is one such model. It defines the relationship between proportion $p$ and weight $w$ to be

$$\log\left(\frac{p}{1-p}\right) = b_1 + b_2 w$$

Is this a good model for our data? It would be helpful to graph the data on this scale, to see if the relationship appears linear. However, some of our proportions are 0 and 1, so we cannot explicitly evaluate the left-hand-side of the equation. A useful trick is to compute adjusted proportions by adding small increments to the poor and total values — say a half observation to poor and a full observation to total. This keeps the proportions within range. A graph now shows a more nearly linear relationship.

```
padj = (poor+.5) ./ (total+1);
plot(w,log(padj./(1-padj)),'x')
```
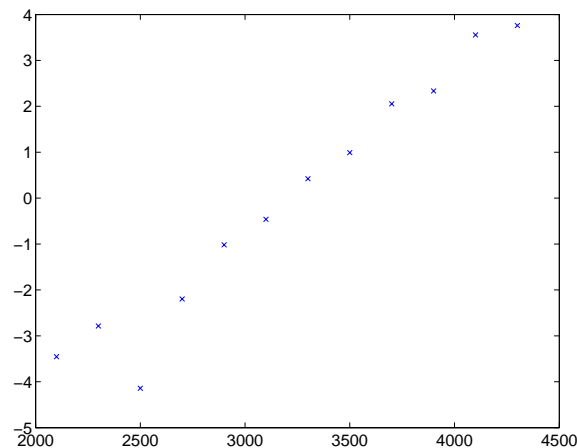


We can use the glmfit function to fit this logistic model.

```
b = glmfit(w, [poor total], 'binomial')

b =
  -13.3801
    0.0042
```

To use these coefficients to compute a fitted proportion, we have to invert the logistic relationship. Some simple algebra shows that the logistic equation can also be written as

$$p = \frac{1}{1 + \exp(-b_1 - b_2 w)}$$

Fortunately, the function glmval can decode this link function to compute the fitted values. Using this function we can graph fitted proportions for a range of car weights, and superimpose this curve on the original scatter plot.

```
x = 2100:100:4500;
y = glmval(b, x, 'logit');
plot(w, poor./total, 'x', x, y, 'r-')
```
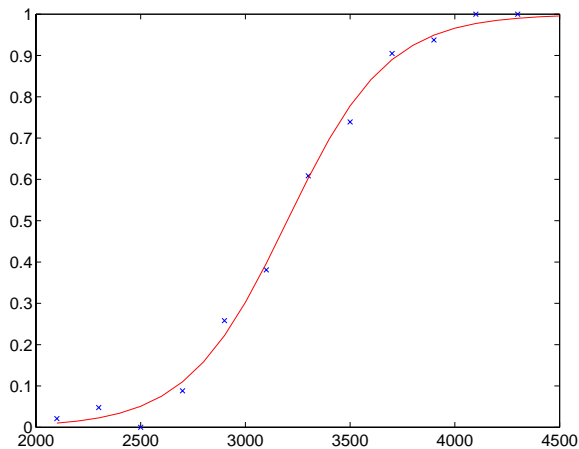


Generalized linear models can fit a variety of distributions with a variety of relationships between the distribution parameters and the predictors. A full description is beyond the scope of this document. For more information see Dobson (1990), or McCullagh and Nelder (1990). Also see the reference material for glmfit.

# Robust and Nonparametric Methods

As mentioned in the previous sections, regression and analysis of variance procedures depend on certain assumptions, such as a normal distribution for the error term. Sometimes such an assumption is not warranted. For example, if the distribution of the errors is asymmetric or prone to extreme outliers, that is a violation of the assumption of normal errors.

The Statistics Toolbox has a robust regression function that is useful when there may be outliers. Robust methods are designed to be relatively insensitive to large changes in a small part of the data.

The Statistics Toolbox also has nonparametric versions of the one-way and two-way analysis of variance functions. Unlike classical tests, nonparametric tests make only mild assumptions about the data, and are appropriate when the distribution of the data is not normal. On the other hand, they are less powerful than classical methods for normally distributed data.

The following sections describe the robust regression and nonparametric functions in greater detail:

- "Robust Regression"
- "Kruskal-Wallis Test"
- "Friedman's Test"

Both of the nonparametric functions described here can return a `stats` structure that you can use as input to the `multcompare` function to perform multiple comparisons.

### Robust Regression

In "Example: Multiple Linear Regression" on page 1-85 we found an outlier when we used ordinary least squares regression to model a response as a function of five predictors. How did that outlier affect the results?

Let's estimate the coefficients using the `robustfit` function.

```
load moore
x = moore(:, 1:5);
y = moore(:, 6);
[br, statsr] = robustfit(x, y);
br
```

**1-95**

```
br =
    -1.7742
     0.0000
     0.0009
     0.0002
     0.0062
     0.0001
```

Compare these estimates to those we obtained from the regress function.

```
b
b =
    -2.1561
    -0.0000
     0.0013
     0.0001
     0.0079
     0.0001
```

To understand why the two differ, it is helpful to look at the weight variable from the robust fit. It measures how much weight was given to each point during the fit. In this case, the first point had a very low weight so it was effectively ignored.

```
statsr.w'

ans =

  Columns 1 through 7
    0.0577    0.9977    0.9776    0.9455    0.9687    0.8734    0.9177
  Columns 8 through 14
    0.9990    0.9653    0.9679    0.9768    0.9882    0.9998    0.9979
  Columns 15 through 20
    0.8185    0.9757    0.9875    0.9991    0.9021    0.6953
```

For another example illustrating robust fitting, see "The robustdemo Demo" on page 1-172.

## Kruskal-Wallis Test

In "One-Way Analysis of Variance (ANOVA)" on page 1-69 we used one-way analysis of variance to determine if the bacteria counts of milk varied from shipment to shipment. Our one-way analysis rested on the assumption that the measurements were independent, and that each had a normal distribution with a common variance and with a mean that was constant in each column. We concluded that the column means were not all the same. Let's repeat that analysis using a nonparametric procedure.

The Kruskal-Wallis test is a nonparametric version of one-way analysis of variance. The assumption behind this test is that the measurements come from a continuous distribution, but not necessarily a normal distribution. The test is based on an analysis of variance using the ranks of the data values, not the data values themselves. Output includes a table similar to an anova table, and a box plot.

We can run this test as follows.

```
p = kruskalwallis(hogg)
p =
    0.0020
```

The low p-value means the Kruskal-Wallis test results agree with the one-way analysis of variance results.

## Friedman's Test

In "Two-Way Analysis of Variance (ANOVA)" on page 1-73 we used two-way analysis of variance to study the effect of car model and factory on car mileage. We tested whether either of these factors had a significant effect on mileage, and whether there was an interaction between these factors. We concluded that there was no interaction, but that each individual factor had a significant effect. Now we will see if a nonparametric analysis will lead to the same conclusion.

Friedman's test is a nonparametric test for data having a two-way layout (data grouped by two categorical factors). Unlike two-way analysis of variance, Friedman's test does not treat the two factors symmetrically and it does not test for an interaction between them. Instead, it is a test for whether the columns are different after adjusting for possible row differences. The test is based on an analysis of variance using the ranks of the data across categories of the row factor. Output includes a table similar to an anova table.

We can run Friedman's test as follows.

```
p = friedman(mileage, 3)

ans =

    7.4659e-004
```

Recall the classical analysis of variance gave a p-value to test column effects, row effects, and interaction effects. This p-value is for column effects. Using either this p-value or the p-value from ANOVA ($p < 0.0001$), we conclude that there are significant column effects.

In order to test for row effects, we need to rearrange the data to swap the roles of the rows in columns. For a data matrix x with no replications, we could simply transpose the data and type

```
p = friedman(x')
```

With replicated data it is slightly more complicated. A simple way is to transform the matrix into a three-dimensional array with the first dimension representing the replicates, swapping the other two dimensions, and restoring the two-dimensional shape.

```
x = reshape(mileage, [3 2 3]);
x = permute(x, [1 3 2]);
x = reshape(x, [9 2])
x =
    33.3000    32.6000
    33.4000    32.5000
    32.9000    33.0000
    34.5000    33.4000
    34.8000    33.7000
    33.8000    33.9000
    37.4000    36.6000
    36.8000    37.0000
    37.6000    36.7000

friedman(x, 3)

ans =

    0.0082
```

Again, the conclusion is similar to the conclusion from the classical analysis of variance. Both this p-value and the one from ANOVA (p = 0.0039) lead us to conclude there are significant row effects.

You cannot use Friedman's test to test for interactions between the row and column factors.

# Nonlinear Regression Models

Response Surface Methodology (RSM) is an empirical modeling approach using polynomials as local approximations to the true input/output relationship. This empirical approach is often adequate for process improvement in an industrial setting.

In scientific applications there is usually relevant theory that allows us to make a mechanistic model. Often such models are nonlinear in the unknown parameters. Nonlinear models are more difficult to fit, requiring iterative methods that start with an initial guess of the unknown parameters. Each iteration alters the current guess until the algorithm converges.

The Statistics Toolbox has functions for fitting nonlinear models of the form

$$y = f(X, \beta) + \varepsilon$$

where:

- $y$ is an-$n$ by-1 vector of observations.
- $f$ is any function of $X$ and $\beta$.
- $X$ is an $n$-by-$p$ matrix of input variables.
- $\beta$ is a $p$-by-1 vector of unknown parameters to be estimated.
- $\varepsilon$ is an $n$-by-1 vector of random disturbances.

This is explored further in the following example.

## Example: Nonlinear Modeling

The Hougen-Watson model (Bates and Watts 1988) for reaction kinetics is one specific example of this type. The form of the model is

$$rate = \frac{\beta_1 \cdot x_2 - x_3 / \beta_5}{1 + \beta_2 \cdot x_1 + \beta_3 \cdot x_2 + \beta_4 \cdot x_3}$$

where $\beta_1$, $\beta_2$, ..., $\beta_5$ are the unknown parameters, and $x_1$, $x_2$, and $x_3$ are the three input variables. The three inputs are hydrogen, n-pentane, and isopentane. It is easy to see that the parameters do not enter the model linearly.

The file reaction.mat contains simulated data from this reaction.

```
load reaction
who
Your variables are:

beta        rate        xn
model       reactants   yn
```

The variables are as follows:

- rate is a 13-by-1 vector of observed reaction rates.
- reactants is a 13-by-3 matrix of reactants.
- beta is 5-by-1 vector of initial parameter estimates.
- model is a string containing the nonlinear function name.
- xn is a string matrix of the names of the reactants.
- yn is a string containing the name of the response.

The data and model are explored further in the following sections:

- "Fitting the Hougen-Watson Model"
- "Confidence Intervals on the Parameter Estimates"
- "Confidence Intervals on the Predicted Responses"
- "An Interactive GUI for Nonlinear Fitting and Prediction"

### Fitting the Hougen-Watson Model

The Statistics Toolbox provides the function nlinfit for finding parameter estimates in nonlinear modeling. nlinfit returns the least squares parameter estimates. That is, it finds the parameters that minimize the sum of the squared differences between the observed responses and their fitted values. It uses the Gauss-Newton algorithm with Levenberg-Marquardt modifications for global convergence.

nlinfit requires the input data, the responses, and an initial guess of the unknown parameters. You must also supply the name of a function that takes the input data and the current parameter estimate and returns the predicted responses. In MATLAB terminology, nlinfit is called a "function" function.

Here is the hougen function.

```
function yhat = hougen(beta, x)
%HOUGEN Hougen-Watson model for reaction kinetics.
%   YHAT = HOUGEN(BETA, X) gives the predicted values of the
%   reaction rate, YHAT, as a function of the vector of
%   parameters, BETA, and the matrix of data, X.
%   BETA must have five elements and X must have three
%   columns.
%
%   The model form is:
%   y = (b1*x2 - x3/b5)./(1+b2*x1+b3*x2+b4*x3)

b1 = beta(1);
b2 = beta(2);
b3 = beta(3);
b4 = beta(4);
b5 = beta(5);

x1 = x(:, 1);
x2 = x(:, 2);
x3 = x(:, 3);

yhat = (b1*x2 - x3/b5)./(1+b2*x1+b3*x2+b4*x3);
```

To fit the reaction data, call the function nlinfit.

```
load reaction
betahat = nlinfit(reactants, rate, 'hougen', beta)

betahat =

    1.2526
    0.0628
    0.0400
    0.1124
    1.1914
```

nlinfit has two optional outputs. They are the residuals and Jacobian matrix at the solution. The residuals are the differences between the observed and fitted responses. The Jacobian matrix is the direct analog of the matrix $X$ in the standard linear regression model.

These outputs are useful for obtaining confidence intervals on the parameter estimates and predicted responses.

### Confidence Intervals on the Parameter Estimates

Using nlparci, form 95% confidence intervals on the parameter estimates, betahat, from the reaction kinetics example.

```
[betahat, resid, J] = nlinfit(reactants, rate, 'hougen', beta);
betaci = nlparci(betahat, resid, J)

betaci =

    -0.7467    3.2519
    -0.0377    0.1632
    -0.0312    0.1113
    -0.0609    0.2857
    -0.7381    3.1208
```

### Confidence Intervals on the Predicted Responses

Using nlpredci, form 95% confidence intervals on the predicted responses from the reaction kinetics example.

```
[yhat, delta] = nlpredci('hougen', reactants, betahat, resid, J);
opd = [rate yhat delta]

opd =

     8.5500     8.2937     0.9178
     3.7900     3.8584     0.7244
     4.8200     4.7950     0.8267
     0.0200    -0.0725     0.4775
     2.7500     2.5687     0.4987
    14.3900    14.2227     0.9666
     2.5400     2.4393     0.9247
     4.3500     3.9360     0.7327
    13.0000    12.9440     0.7210
     8.5000     8.2670     0.9459
     0.0500    -0.1437     0.9537
    11.3200    11.3484     0.9228
     3.1300     3.3145     0.8418
```

Matrix opd has the observed rates in column 1 and the predictions in column 2. The 95% confidence interval is column 2±column 3. These are simultaneous confidence intervals for the estimated function at each input value. They are not intervals for new response observations at those inputs, even though most of the confidence intervals do contain the original observations.

### An Interactive GUI for Nonlinear Fitting and Prediction

The function nlintool for nonlinear models is a direct analog of rstool for polynomial models. nlintool calls nlinfit and requires the same inputs.

The purpose of nlintool is larger than just fitting and prediction for nonlinear models. This GUI provides an environment for exploration of the graph of a multidimensional nonlinear function.

If you have already loaded reaction.mat, you can start nlintool.

```
nlintool(reactants, rate, 'hougen', beta, 0.01, xn, yn)
```

You will see a "vector" of three plots. The dependent variable of all three plots is the reaction rate. The first plot has hydrogen as the independent variable. The second and third plots have n-pentane and isopentane respectively.

Each plot shows the fitted relationship of the reaction rate to the independent variable at a fixed value of the other two independent variables. The fixed value of each independent variable is in an editable text box below each axis. You can change the fixed value of any independent variable by either typing a new value in the box or by dragging any of the three vertical lines to a new position.

When you change the value of an independent variable, all the plots update to show the current picture at the new point in the space of the independent variables.

Note that while this example only uses three reactants, nlintool can accommodate an arbitrary number of independent variables. Interpretability may be limited by the size of the monitor for large numbers of inputs.

# Hypothesis Tests

A hypothesis test is a procedure for determining if an assertion about a characteristic of a population is reasonable.

For example, suppose that someone says that the average price of a gallon of regular unleaded gas in Massachusetts is $1.15. How would you decide whether this statement is true? You could try to find out what every gas station in the state was charging and how many gallons they were selling at that price. That approach might be definitive, but it could end up costing more than the information is worth.

A simpler approach is to find out the price of gas at a small number of randomly chosen stations around the state and compare the average price to $1.15.

Of course, the average price you get will probably not be exactly $1.15 due to variability in price from one station to the next. Suppose your average price was $1.18. Is this three cent difference a result of chance variability, or is the original assertion incorrect? A hypothesis test can provide an answer.

The following sections provide an overview of hypothesis testing with the Statistics Toolbox:

- "Hypothesis Test Terminology"
- "Hypothesis Test Assumptions"
- "Example: Hypothesis Testing"
- "Available Hypothesis Tests"

## Hypothesis Test Terminology

To get started, there are some terms to define and assumptions to make:

- The *null hypothesis* is the original assertion. In this case the null hypothesis is that the average price of a gallon of gas is $1.15. The notation is $H_0: \mu = 1.15$.

- There are three possibilities for the *alternative hypothesis*. You might only be interested in the result if gas prices were actually higher. In this case, the alternative hypothesis is $H_1: \mu > 1.15$. The other possibilities are $H_1: \mu < 1.15$ and $H_1: \mu \neq 1.15$.

- The *significance level* is related to the degree of certainty you require in order to reject the null hypothesis in favor of the alternative. By taking a small

sample you cannot be certain about your conclusion. So you decide in advance to reject the null hypothesis if the probability of observing your sampled result is less than the significance level. For a typical significance level of 5%, the notation is $\alpha = 0.05$. For this significance level, the probability of incorrectly rejecting the null hypothesis when it is actually true is 5%. If you need more protection from this error, then choose a lower value of $\alpha$.

- The *p-value* is the probability of observing the given sample result under the assumption that the null hypothesis is true. If the p-value is less than $\alpha$, then you reject the null hypothesis. For example, if $\alpha = 0.05$ and the p-value is 0.03, then you reject the null hypothesis.

  The converse is not true. If the p-value is greater than $\alpha$, you have insufficient evidence to reject the null hypothesis.

- The outputs for many hypothesis test functions also include *confidence intervals*. Loosely speaking, a confidence interval is a range of values that have a chosen probability of containing the true hypothesized quantity. Suppose, in our example, 1.15 is inside a 95% confidence interval for the mean, $\mu$. That is equivalent to being unable to reject the null hypothesis at a significance level of 0.05. Conversely if the $100(1-\alpha)$ confidence interval does not contain 1.15, then you reject the null hypothesis at the $\alpha$ level of significance.

## Hypothesis Test Assumptions

The difference between hypothesis test procedures often arises from differences in the assumptions that the researcher is willing to make about the data sample. For example, the Z-test assumes that the data represents independent samples from the same normal distribution and that you know the standard deviation, $\sigma$. The t-test has the same assumptions except that you estimate the standard deviation using the data instead of specifying it as a known quantity.

Both tests have an associated signal-to-noise ratio

$$Z = \frac{\bar{x} - \mu}{\sigma} \quad or \quad T = \frac{\bar{x} - \mu}{s}$$

$$\text{where} \quad \bar{x} = \sum_{i=1}^{n} \frac{x_i}{n}$$

The signal is the difference between the average and the hypothesized mean. The noise is the standard deviation posited or estimated.

If the null hypothesis is true, then $Z$ has a standard normal distribution, N(0,1). $T$ has a Student's t distribution with the degrees of freedom, $\nu$, equal to one less than the number of data values.

Given the observed result for $Z$ or $T$, and knowing the distribution of $Z$ and $T$ assuming the null hypothesis is true, it is possible to compute the probability (p-value) of observing this result. A very small p-value casts doubt on the truth of the null hypothesis. For example, suppose that the p-value was 0.001, meaning that the probability of observing the given $Z$ or $T$ was one in a thousand. That should make you skeptical enough about the null hypothesis that you reject it rather than believe that your result was just a lucky 999 to 1 shot.

There are also nonparametric tests that do not even require the assumption that the data come from a normal distribution. In addition, there are functions for testing whether the normal assumption is reasonable.

## Example: Hypothesis Testing

This example uses the gasoline price data in gas.mat. There are two samples of 20 observed gas prices for the months of January and February, 1993.

```
load gas
prices = [price1 price2];
```

As a first step, you may want to test whether the samples from each month follow a normal distribution. As each sample is relatively small, you might choose to perform a Lilliefors test (rather than a Bera-Jarque test):

```
lillietest(price1)

ans =

     0

lillietest(price2)

ans =

     0
```

The result of the hypothesis test is a Boolean value that is 0 when you do not reject the null hypothesis, and 1 when you do reject that hypothesis. In each case, there is no need to reject the null hypothesis that the samples have a normal distribution.

Suppose it is historically true that the standard deviation of gas prices at gas stations around Massachusetts is four cents a gallon. The Z-test is a procedure for testing the null hypothesis that the average price of a gallon of gas in January (price1) is $1.15.

```
[h, pvalue, ci] = ztest(price1/100, 1.15, 0.04)

h =
     0

pvalue =

    0.8668

ci =

    1.1340    1.1690
```

The Boolean output is h = 0, so you do not reject the null hypothesis.

The result suggests that $1.15 is reasonable. The 95% confidence interval [1.1340 1.1690] neatly brackets $1.15.

What about February? Try a t-test with price2. Now you are not assuming that you know the standard deviation in price.

```
[h, pvalue, ci] = ttest(price2/100, 1.15)

h =
     1

pvalue =

    4.9517e-04

ci =
    1.1675    1.2025
```

With the Boolean result h = 1, you can reject the null hypothesis at the default significance level, 0.05.

It looks like $1.15 is not a reasonable estimate of the gasoline price in February. The low end of the 95% confidence interval is greater than 1.15.

The function `ttest2` allows you to compare the means of the two data samples.

```
[h, sig, ci] = ttest2(price1, price2)

h =
     1

sig =

    0.0083

ci =

    -5.7845    -0.9155
```

The confidence interval (`ci` above) indicates that gasoline prices were between one and six cents lower in January than February.

If the two samples were not normally distributed but had similar shape, it would have been more appropriate to use the nonparametric rank sum test in place of the t-test. We can still use the rank sum test with normally distributed data, but it is less powerful than the t-test.

```
[p, h, stats] = ranksum(price1, price2)

p =
    0.0092

h =
     1

stats =
         zval: -2.6064
      ranksum: 314
```

As might be expected, the rank sum test leads to the same conclusion but it is less sensitive to the difference between samples (higher p-value).

The box plot below gives the same conclusion graphically. Note that the notches have little, if any, overlap. Refer to "Statistical Plots" on page 1-128 for more information about box plots.

```
boxplot(prices, 1)
set(gca, 'XtickLabel', str2mat('January', 'February'))
xlabel('Month')
ylabel('Prices ($0.01)')
```
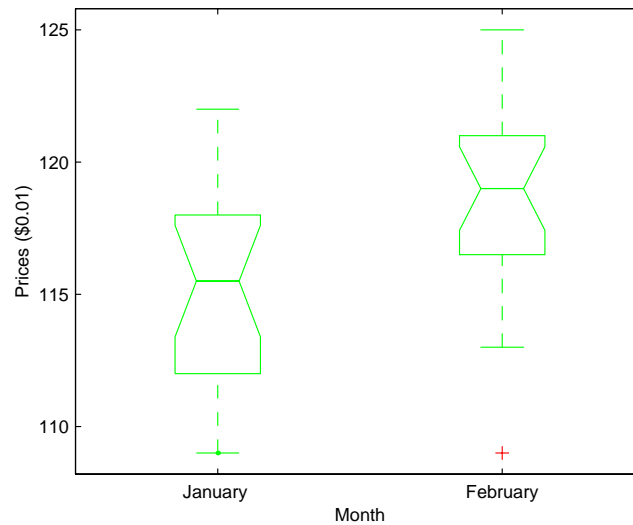
## Available Hypothesis Tests

The Statistics Toolbox has functions for performing the following tests.

| Function | What it Tests |
|---|---|
| jbtest | Normal distribution for one sample |
| kstest | Any specified distribution for one sample |
| kstest2 | Equal distributions for two samples |
| lillietest | Normal distribution for one sample |
| ranksum | Median of two unpaired samples |
| signrank | Median of two paired samples |
| signtest | Median of two paired samples |
| ttest | Mean of one normal sample |
| ttest2 | Mean of two normal samples |
| ztest | Mean of normal sample with known standard deviation |

# Multivariate Statistics

Multivariate statistics is an omnibus term for a number of different statistical methods. The defining characteristic of these methods is that they all aim to understand a data set by considering a group of variables together rather than focusing on only one variable at a time.

The Statistics Toolbox has functions for principal components analysis (`princomp`), multivariate analysis of variance (`manova1`), and linear discriminant analysis (`classify`). The following sections illustrate the first two functions:

- "Principal Components Analysis"
- "Multivariate Analysis of Variance (MANOVA)"

## Principal Components Analysis

One of the difficulties inherent in multivariate statistics is the problem of visualizing multidimensionality. In MATLAB, the `plot` command displays a graph of the relationship between two variables. The `plot3` and `surf` commands display different three-dimensional views. When there are more than three variables, it stretches the imagination to visualize their relationships.

Fortunately, in data sets with many variables, groups of variables often move together. One reason for this is that more than one variable may be measuring the same driving principle governing the behavior of the system. In many systems there are only a few such driving forces. But an abundance of instrumentation allows us to measure dozens of system variables. When this happens, we can take advantage of this redundancy of information. We can simplify our problem by replacing a group of variables with a single new variable.

Principal components analysis is a quantitatively rigorous method for achieving this simplification. The method generates a new set of variables, called *principal components*. Each principal component is a linear combination of the original variables. All the principal components are orthogonal to each other so there is no redundant information. The principal components as a whole form an orthogonal basis for the space of the data.

There are an infinite number of ways to construct an orthogonal basis for several columns of data. What is so special about the principal component basis?

The first principal component is a single axis in space. When you project each observation on that axis, the resulting values form a new variable. And the variance of this variable is the maximum among all possible choices of the first axis.

The second principal component is another axis in space, perpendicular to the first. Projecting the observations on this axis generates another new variable. The variance of this variable is the maximum among all possible choices of this second axis.

The full set of principal components is as large as the original set of variables. But it is commonplace for the sum of the variances of the first few principal components to exceed 80% of the total variance of the original data. By examining plots of these few new variables, researchers often develop a deeper understanding of the driving forces that generated the original data.

The following section provides an example.

### Example: Principal Components Analysis

Let us look at a sample application that uses nine different indices of the quality of life in 329 U.S. cities. These are climate, housing, health, crime, transportation, education, arts, recreation, and economics. For each index, higher is better; so, for example, a higher index for crime means a lower crime rate.

We start by loading the data in `cities.mat`.

```
load cities
whos
```

| Name       | Size   | Bytes | Class        |
|------------|--------|-------|--------------|
| categories | 9x14   | 252   | char array   |
| names      | 329x43 | 28294 | char array   |
| ratings    | 329x9  | 23688 | double array |

The whos command generates a table of information about all the variables in the workspace.

The cities data set contains three variables:

- categories, a string matrix containing the names of the indices.
- names, a string matrix containing the 329 city names.
- ratings, the data matrix with 329 rows and 9 columns.

Let's look at the value of the categories variable.

```
categories
categories =

climate
housing
health
crime
transportation
education
arts
recreation
economics
```

Now, let's look at the first several rows of names variable.

```
first5 = names(1:5,:)
first5 =

Abilene, TX
Akron, OH
Albany, GA
Albany-Troy, NY
Albuquerque, NM
```
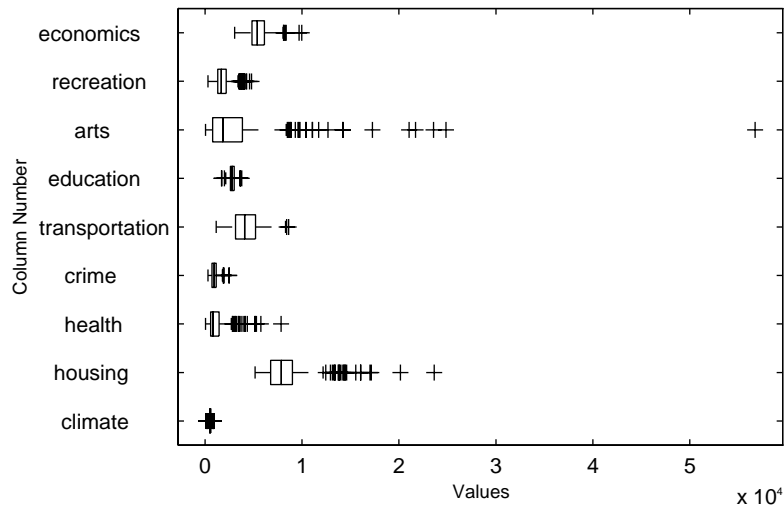
To get a quick impression of the ratings data, make a box plot.

```
boxplot(ratings, 0, '+', 0)
set(gca, 'YTicklabel', categories)
```

These commands generate the plot below. Note that there is substantially more variability in the ratings of the arts and housing than in the ratings of crime and climate.

Ordinarily you might also graph pairs of the original variables, but there are 36 two-variable plots. Perhaps principal components analysis can reduce the number of variables we need to consider.

Sometimes it makes sense to compute principal components for raw data. This is appropriate when all the variables are in the same units. Standardizing the data is reasonable when the variables are in different units or when the variance of the different columns is substantial (as in this case).

You can standardize the data by dividing each column by its standard deviation.

```
stdr = std(ratings);
sr = ratings./repmat(stdr,329,1);
```

Now we are ready to find the principal components.

```
[pcs, newdata, variances, t2] = princomp(sr);
```

The following sections explain the four outputs from princomp:

- "The Principal Components (First Output)"
- "The Component Scores (Second Output)"
- "The Component Variances (Third Output)"
- "Hotelling's T2 (Fourth Output)"

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### The Principal Components (First Output)

The first output of the `princomp` function, `pcs`, contains the nine principal components. These are the linear combinations of the original variables that generate the new variables.

Let's look at the first three principal component vectors.

```
p3 = pcs(:, 1:3)
p3 =

    0.2064     0.2178    -0.6900
    0.3565     0.2506    -0.2082
    0.4602    -0.2995    -0.0073
    0.2813     0.3553     0.1851
    0.3512    -0.1796     0.1464
    0.2753    -0.4834     0.2297
    0.4631    -0.1948    -0.0265
    0.3279     0.3845    -0.0509
    0.1354     0.4713     0.6073
```

The largest weights in the first column (first principal component) are the third and seventh elements, corresponding to the variables `health` and `arts`. All the elements of the first principal component are the same sign, making it a weighted average of all the variables.

To show the orthogonality of the principal components, note that premultiplying them by their transpose yields the identity matrix.

```
I = p3'*p3
I =

    1.0000    -0.0000    -0.0000
   -0.0000     1.0000    -0.0000
   -0.0000    -0.0000     1.0000
```

### The Component Scores (Second Output)

The second output, newdata, is the data in the new coordinate system defined by the principal components. This output is the same size as the input data matrix.

A plot of the first two columns of newdata shows the ratings data projected onto the first two principal components.

```
plot(newdata(:, 1), newdata(:, 2), '+')
xlabel('1st Principal Component');
ylabel('2nd Principal Component');
```
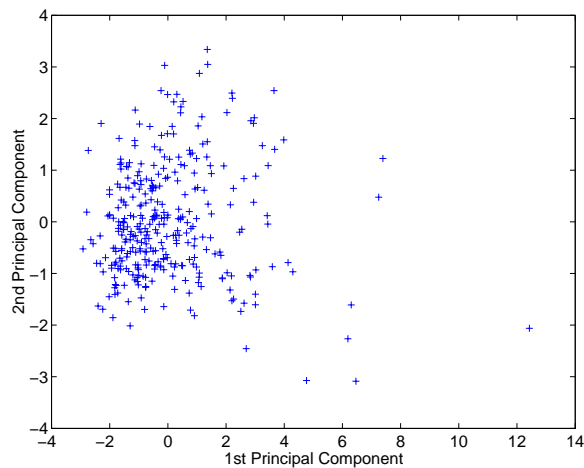


Note the outlying points in the lower right corner.

The function gname is useful for graphically identifying a few points in a plot like this. You can call gname with a string matrix containing as many case labels as points in the plot. The string matrix names works for labeling points with the city names.

```
gname(names)
```

Move your cursor over the plot and click once near each point at the top right. As you click on each point, MATLAB labels it with the proper row from the names string matrix. When you are finished labeling points, press the **Return** key.

Here is the resulting plot.
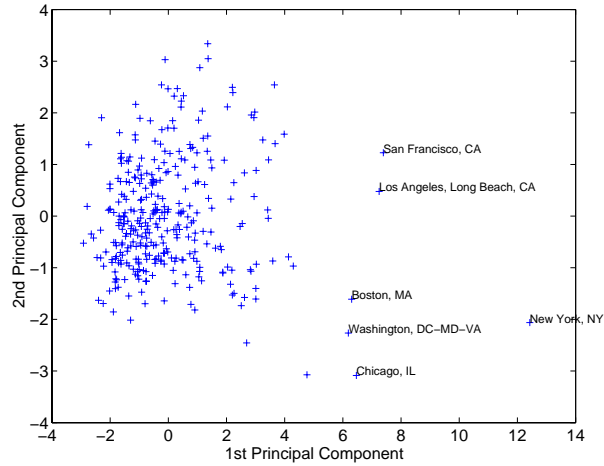


The labeled cities are the biggest population centers in the United States. Perhaps we should consider them as a completely separate group. If we call gname without arguments, it labels each point with its row number.
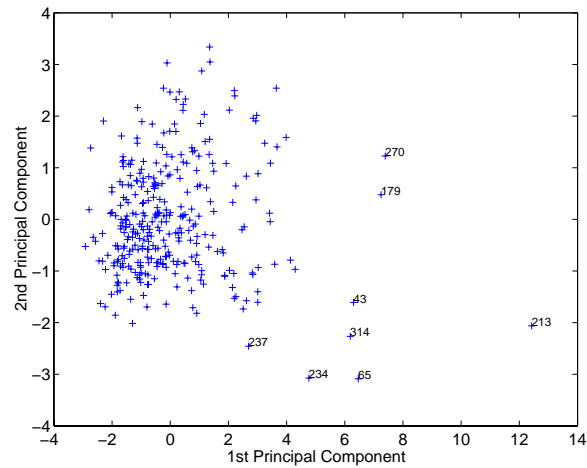
We can create an index variable containing the row numbers of all the metropolitan areas we chose.

```
metro = [43 65 179 213 234 270 314];
names(metro,:)

ans =

Boston, MA
Chicago, IL
Los Angeles, Long Beach, CA
New York, NY
Philadelphia, PA-NJ
San Francisco, CA
Washington, DC-MD-VA
```

To remove these rows from the ratings matrix, type the following.

```
rsubset = ratings;
nsubset = names;
nsubset(metro,:) = [];
rsubset(metro,:) = [];

size(rsubset)
ans =

   322     9
```

To practice, repeat the analysis using the variable rsubset as the new data matrix and nsubset as the string matrix of labels.

### The Component Variances (Third Output)

The third output, variances, is a vector containing the variance explained by the corresponding column of newdata.

```
variances
variances =

    3.4083
    1.2140
    1.1415
    0.9209
    0.7533
    0.6306
    0.4930
    0.3180
    0.1204
```

You can easily calculate the percent of the total variability explained by each principal component.

```
percent_explained = 100*variances/sum(variances)
percent_explained =

   37.8699
   13.4886
   12.6831
   10.2324
    8.3698
    7.0062
    5.4783
    3.5338
    1.3378
```

A "Scree" plot is a pareto plot of the percent variability explained by each principal component.

```
pareto(percent_explained)
xlabel('Principal Component')
ylabel('Variance Explained (%)')
```
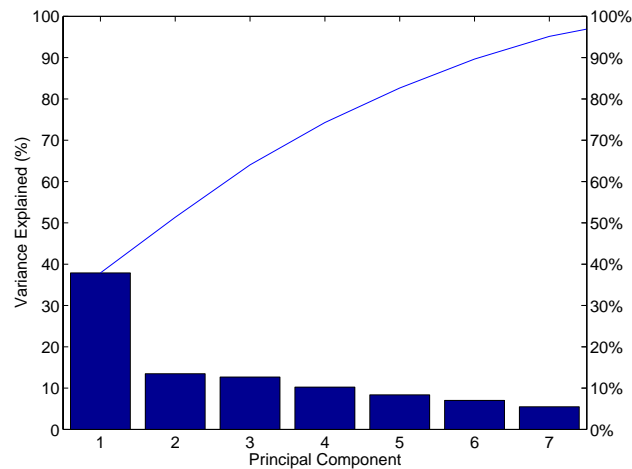
We can see that the first three principal components explain roughly two thirds of the total variability in the standardized ratings.

### Hotelling's T$^2$ (Fourth Output)

The last output of the princomp function, t2, is Hotelling's T$^2$, a statistical measure of the multivariate distance of each observation from the center of the data set. This is an analytical way to find the most extreme points in the data.

```
[st2, index] = sort(t2);        % Sort in ascending order.
st2 = flipud(st2);              % Values in descending order.
index = flipud(index);          % Indices in descending order.

extreme = index(1)
extreme =

   213

names(extreme,:)
ans =

New York, NY
```

It is not surprising that the ratings for New York are the furthest from the average U.S. town.

# Multivariate Analysis of Variance (MANOVA)

We reviewed the analysis of variance technique in "One-Way Analysis of Variance (ANOVA)" on page 1-69. With this technique we can take a set of grouped data and determine whether the mean of a variable differs significantly between groups. Often we have multiple variables, and we are interested in determining whether the entire set of means is different from one group to the next. There is a multivariate version of analysis of variance that can address that problem, as illustrated in the following example.

### Example: Multivariate Analysis of Variance

The carsmall data set has measurements on a variety of car models from the years 1970, 1976, and 1982. Suppose we are interested in whether the characteristics of the cars have changed over time.

First we load the data.

```
load carsmall
whos
```

| Name | Size | Bytes | Class |
|------|------|-------|-------|
| Acceleration | 100x1 | 800 | double array |
| Cylinders | 100x1 | 800 | double array |
| Displacement | 100x1 | 800 | double array |
| Horsepower | 100x1 | 800 | double array |
| MPG | 100x1 | 800 | double array |
| Model | 100x36 | 7200 | char array |
| Model_Year | 100x1 | 800 | double array |
| Origin | 100x7 | 1400 | char array |
| Weight | 100x1 | 800 | double array |

Four of these variables (Acceleration, Displacement, Horsepower, and MPG) are continuous measurements on individual car models. The variable Model_Year indicates the year in which the car was made. We can create a grouped plot matrix of these variables using the gplotmatrix function.

```
x = [MPG Horsepower Displacement Weight];
gplotmatrix(x,[],Model_Year,[],'+xo')
```
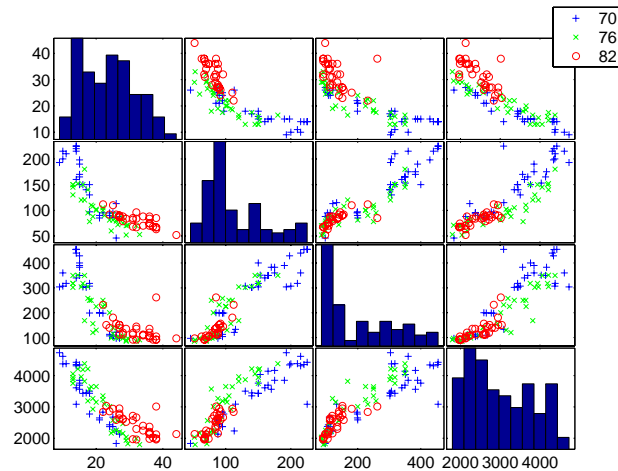
(When the second argument of gplotmatrix is empty, the function graphs the columns of the x argument against each other, and places histograms along the diagonals. The empty fourth argument produces a graph with the default colors. The fifth argument controls the symbols used to distinguish between groups.)

It appears the cars do differ from year to year. The upper right plot, for example, is a graph of MPG versus Weight. The 1982 cars appear to have higher mileage than the older cars, and they appear to weigh less on average. But as a group, are the three years significantly different from one another? The manova1 function can answer that question.

```
[d, p, stats] = manova1(x, Model_Year)

d =
     2

p =

  1.0e-006 *
         0
    0.1141
```

```
stats =
           W: [4x4 double]
           B: [4x4 double]
           T: [4x4 double]
         dfW: 90
         dfB: 2
         dfT: 92
      lambda: [2x1 double]
       chisq: [2x1 double]
     chisqdf: [2x1 double]
     eigenval: [4x1 double]
     eigenvec: [4x4 double]
       canon: [100x4 double]
       mdist: [100x1 double]
      gmdist: [3x3 double]
```

The manova1 function produces three outputs:

- The first output, d, is an estimate of the dimension of the group means. If the means were all the same, the dimension would be 0, indicating that the means are at the same point. If the means differed but fell along a line, the dimension would be 1. In the example the dimension is 2, indicating that the group means fall in a plane but not along a line. This is the largest possible dimension for the means of three groups.

- The second output, p, is a vector of p-values for a sequence of tests. The first p-value tests whether the dimension is 0, the next whether the dimension is 1, and so on. In this case both p-values are small. That's why the estimated dimension is 2.

- The third output, stats, is a structure containing several fields, described in the following section.

**The Fields of the stats Structure.** The W, B, and T fields are matrix analogs to the within, between, and total sums of squares in ordinary one-way analysis of variance. The next three fields are the degrees of freedom for these matrices. Fields lambda, chisq, and chisqdf are the ingredients of the test for the dimensionality of the group means. (The p-values for these tests are the first output argument of manova1.)

The next three fields are used to do a canonical analysis. Recall that in principal components analysis ("Principal Components Analysis" on

page 1-112) we look for the combination of the original variables that has the largest possible variation. In multivariate analysis of variance, we instead look for the linear combination of the original variables that has the largest separation between groups. It is the single variable that would give the most significant result in a univariate one-way analysis of variance. Having found that combination, we next look for the combination with the second highest separation, and so on.

The eigenvec field is a matrix that defines the coefficients of the linear combinations of the original variables. The eigenval field is a vector measuring the ratio of the between-group variance to the within-group variance for the corresponding linear combination. The canon field is a matrix of the canonical variable values. Each column is a linear combination of the mean-centered original variables, using coefficients from the eigenvec matrix.

A grouped scatter plot of the first two canonical variables shows more separation between groups then a grouped scatter plot of any pair of original variables. In this example it shows three clouds of points, overlapping but with distinct centers. One point in the bottom right sits apart from the others. By using the gname function, we can see that this is the 20th point.

```
c1 = stats.canon(:,1);
c2 = stats.canon(:,2);
gscatter(c2,c1,Model_Year,[],'oxs')
gname
```
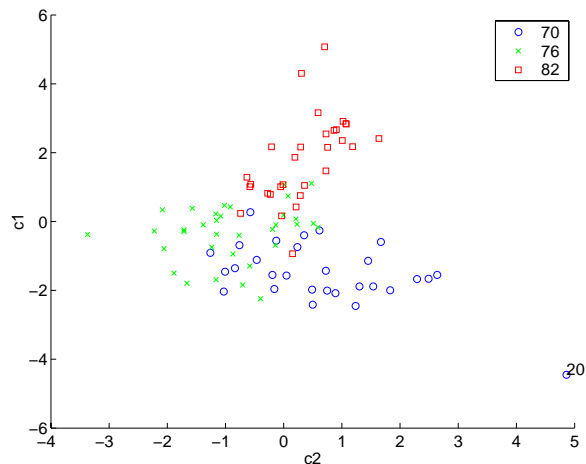
Roughly speaking, the first canonical variable, c1, separates the 1982 cars (which have high values of c1) from the older cars. The second canonical variable, c2, reveals some separation between the 1970 and 1976 cars.

The final two fields of the stats structure are Mahalanobis distances. The mdist field measures the distance from each point to its group mean. Points with large values may be outliers. In this data set, the largest outlier is the one we saw in the scatter plot, the Buick Estate station wagon. (Note that we could have supplied the model name to the gname function above if we wanted to label the point with its model name rather than its row number.)

```
max(stats.mdist)
ans =

   31.5273

find(stats.mdist == ans)
ans =

    20

Model(20,:)
ans =

buick_estate_wagon_(sw)
```

The gmdist field measures the distances between each pair of group means. The following commands examine the group means and their distances:

```
grpstats(x, Model_Year)

ans =

  1.0e+003 *
    0.0177    0.1489    0.2869    3.4413
    0.0216    0.1011    0.1978    3.0787
    0.0317    0.0815    0.1289    2.4535

stats.gmdist

ans =
         0    3.8277   11.1106
    3.8277         0    6.1374
   11.1106    6.1374         0
```

As might be expected, the multivariate distance between the extreme years 1970 and 1982 (11.1) is larger than the difference between more closely spaced years (3.8 and 6.1). This is consistent with the scatter plots, where the points seem to follow a progression as the year changes from 1970 through 1976 to 1982. If we had more groups, we might have found it instructive to use the `manovacluster` function to draw a diagram that presents clusters of the groups, formed using the distances between their means.

# Statistical Plots

The Statistics Toolbox adds specialized plots to the extensive graphics capabilities of MATLAB.

- *Box plots* are graphs for describing data samples. They are also useful for graphic comparisons of the means of many samples (see "One-Way Analysis of Variance (ANOVA)" on page 1-69).
- *Distribution plots* are graphs for visualizing the distribution of one or more samples. They include normal and Weibull probability plots, quantile-quantile plots, and empirical cumulative distribution plots.
- *Scatter plots* are graphs for visualizing the relationship between a pair of variables or several such pairs. Grouped versions of these plots use different plotting symbols to indicate group membership. The gname function can label points on these plots with a text label or an observation number.

The plot types are described further in the following sections:

- "Box Plots"
- "Distribution Plots"
- "Scatter Plots"

## Box Plots

The graph shows an example of a notched box plot.
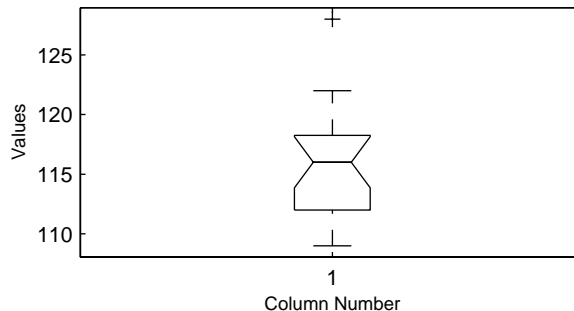
This plot has several graphic elements:

- The lower and upper lines of the "box" are the 25th and 75th percentiles of the sample. The distance between the top and bottom of the box is the interquartile range.
- The line in the middle of the box is the sample median. If the median is not centered in the box, that is an indication of skewness.
- The "whiskers" are lines extending above and below the box. They show the extent of the rest of the sample (unless there are outliers). Assuming no outliers, the maximum of the sample is the top of the upper whisker. The minimum of the sample is the bottom of the lower whisker. By default, an outlier is a value that is more than 1.5 times the interquartile range away from the top or bottom of the box.
- The plus sign at the top of the plot is an indication of an outlier in the data. This point may be the result of a data entry error, a poor measurement or a change in the system that generated the data.
- The notches in the box are a graphic confidence interval about the median of a sample. Box plots do not have notches by default.

A side-by-side comparison of two notched box plots is the graphical equivalent of a t-test. See "Hypothesis Tests" on page 1-105.

## Distribution Plots

There are several types of plots for examining the distribution of one or more samples, as described in the following sections:

- "Normal Probability Plots"
- "Quantile-Quantile Plots"
- "Weibull Probability Plots"
- "Empirical Cumulative Distribution Function (CDF)"

### Normal Probability Plots

A normal probability plot is a useful graph for assessing whether data comes from a normal distribution. Many statistical procedures make the assumption that the underlying distribution of the data is normal, so this plot can provide some assurance that the assumption of normality is not being violated, or provide an early warning of a problem with your assumptions.

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This example shows a typical normal probability plot.

```
x = normrnd(10, 1, 25, 1);
normplot(x)
```
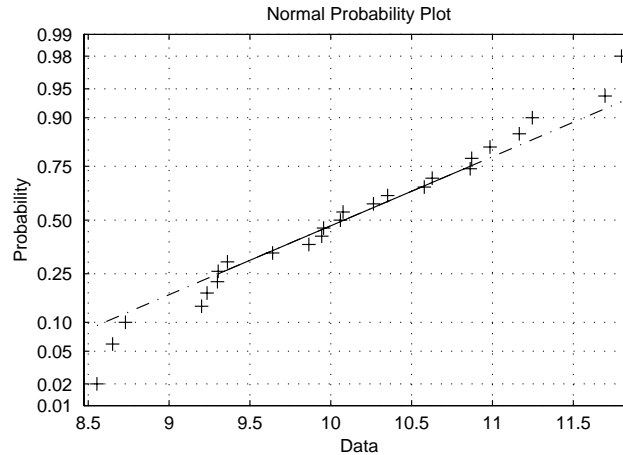


The plot has three graphical elements. The plus signs show the empirical probability versus the data value for each point in the sample. The solid line connects the 25th and 75th percentiles of the data and represents a robust linear fit (i.e., insensitive to the extremes of the sample). The dashed line extends the solid line to the ends of the sample.

The scale of the *y*-axis is not uniform. The *y*-axis values are probabilities and, as such, go from zero to one. The distance between the tick marks on the *y*-axis matches the distance between the quantiles of a normal distribution. The quantiles are close together near the median (probability = 0.5) and stretch out symmetrically moving away from the median. Compare the vertical distance from the bottom of the plot to the probability 0.25 with the distance from 0.25 to 0.50. Similarly, compare the distance from the top of the plot to the probability 0.75 with the distance from 0.75 to 0.50.

If all the data points fall near the line, the assumption of normality is reasonable. But, if the data is nonnormal, the plus signs may follow a curve, as in the example using exponential data below.

```
x = exprnd(10, 100, 1);
normplot(x)
```
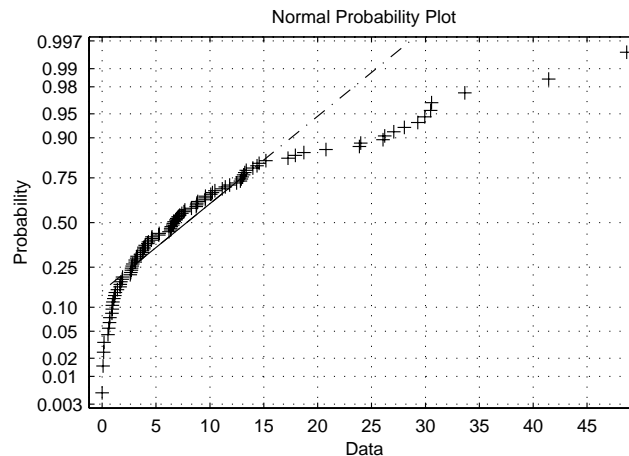


This plot is clear evidence that the underlying distribution is not normal.

### Quantile-Quantile Plots

A quantile-quantile plot is useful for determining whether two samples come from the same distribution (whether normally distributed or not).

The example shows a quantile-quantile plot of two samples from a Poisson distribution.

```
x = poissrnd(10, 50, 1);
y = poissrnd(5, 100, 1);
qqplot(x, y);
```
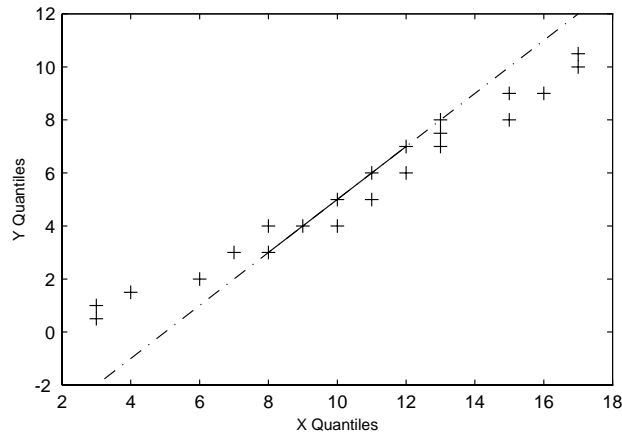
Even though the parameters and sample sizes are different, the straight line relationship shows that the two samples come from the same distribution.

Like the normal probability plot, the quantile-quantile plot has three graphical elements. The pluses are the quantiles of each sample. By default the number of pluses is the number of data values in the smaller sample. The solid line joins the 25th and 75th percentiles of the samples. The dashed line extends the solid line to the extent of the sample.

The example below shows what happens when the underlying distributions are not the same.

```
x = normrnd(5, 1, 100, 1);
y = weibrnd(2, 0.5, 100, 1);
qqplot(x, y);
```
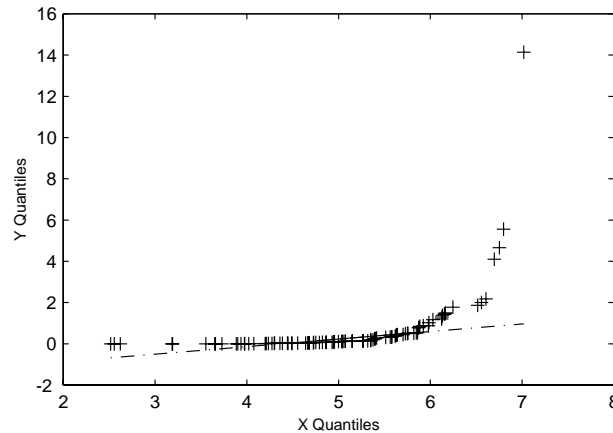
These samples clearly are not from the same distribution.

It is incorrect to interpret a linear plot as a *guarantee* that the two samples come from the same distribution. But, for assessing the validity of a statistical procedure that depends on the two samples coming from the same distribution (e.g., ANOVA), a linear quantile-quantile plot should be sufficient.

### Weibull Probability Plots

A Weibull probability plot is a useful graph for assessing whether data comes from a Weibull distribution. Many reliability analyses make the assumption that the underlying distribution of the lifetimes is Weibull, so this plot can provide some assurance that this assumption is not being violated, or provide an early warning of a problem with your assumptions.

The scale of the *y*-axis is not uniform. The *y*-axis values are probabilities and, as such, go from zero to one. The distance between the tick marks on the *y*-axis matches the distance between the quantiles of a Weibull distribution.

If the data points (pluses) fall near the line, the assumption that the data comes from a Weibull distribution is reasonable.

This example shows a typical Weibull probability plot.

```
y = weibrnd(2, 0. 5, 100, 1);
weibplot(y)
```
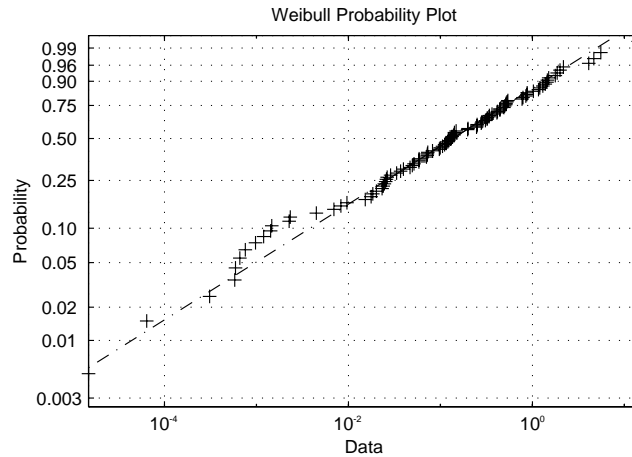


### Empirical Cumulative Distribution Function (CDF)

If you are not willing to assume that your data follows a specific probability distribution, you can use the cdfplot function to graph an empirical estimate of the cumulative distribution function (cdf). This function computes the proportion of data points less than each *x* value, and plots the proportion as a function of *x*. The *y*-axis scale is linear, not a probability scale for a specific distribution.

This example shows the empirical cumulative distribution function for a Weibull sample.

```
y = weibrnd(2, 0. 5, 100, 1);
cdfplot(y)
```
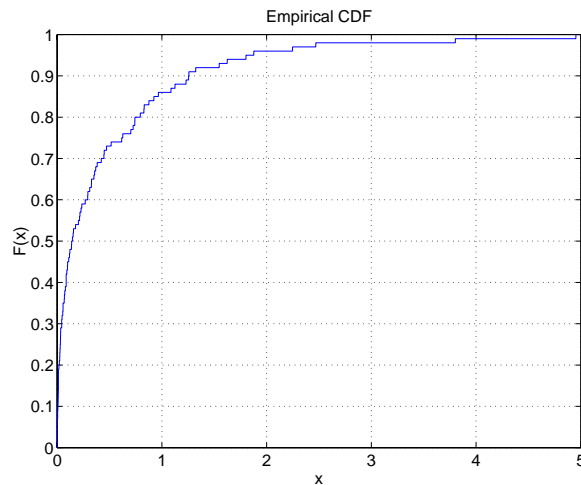
The plot shows a probability function that rises steeply near *x*=0 and levels off for larger values. Over 80% of the observations are less than 1, with the remaining values spread over the range [1 5].

## Scatter Plots

A scatter plot is a simple plot of one variable against another. The MATLAB plot and scatter functions can produce scatter plots. The MATLAB plotmatrix function can produce a matrix of such plots showing the relationship between several pairs of variables.

The Statistics Toolbox adds functions that produce grouped versions of these plots. These are useful for determining whether the values of two variables or the relationship between those variables is the same in each group.

Suppose we want to examine the weight and mileage of cars from three different model years.

```
load carsmall
gscatter(Weight, MPG, Model_Year, '', 'xos')
```
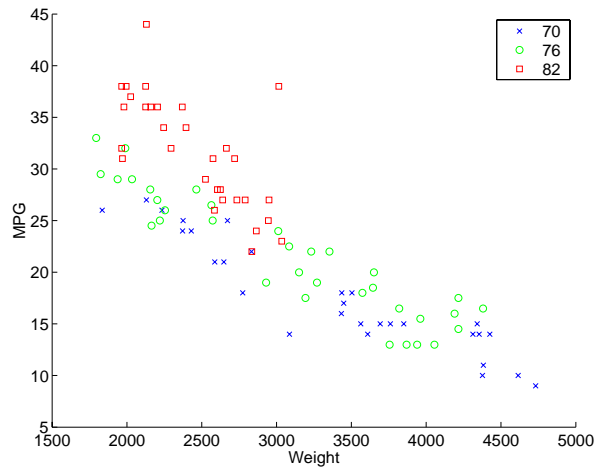
This shows that not only is there a strong relationship between the weight of a car and its mileage, but also that newer cars tend to be lighter and have better gas mileage than older cars.

(The default arguments for gscatter produce a scatter plot with the different groups shown with the same symbol but different colors. The last two arguments above request that all groups be shown in default colors and with different symbols.)

The carsmall data set contains other variables that describe different aspects of cars. We can examine several of them in a single display by creating a grouped plot matrix.

```
xvars = [Weight Displacement Horsepower];
yvars = [MPG Acceleration];
gplotmatrix(xvars,yvars,Model_Year,'','xos')
```
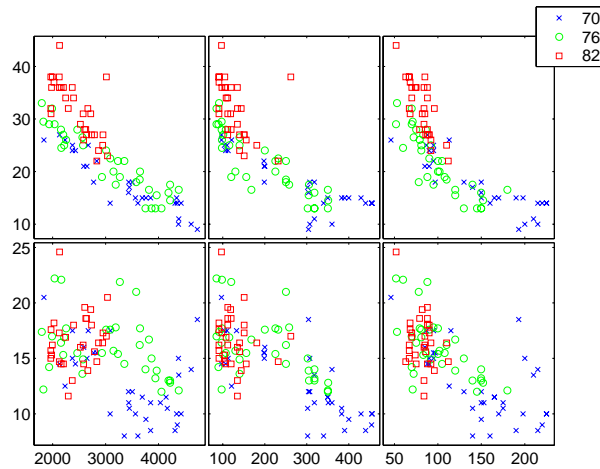
The upper right subplot displays MPG against Horsepower, and shows that over the years the horsepower of the cars has decreased but the gas mileage has improved.

The gplotmatrix function can also graph all pairs from a single list of variables, along with histograms for each variable. See "Multivariate Analysis of Variance (MANOVA)" on page 1-122.

# Statistical Process Control (SPC)

SPC is an omnibus term for a number of methods for assessing and monitoring the quality of manufactured goods. These methods are simple, which makes them easy to implement even in a production environment. The following sections discuss some of the SPC features of the Statistics Toolbox:

- "Control Charts"
- "Capability Studies"

## Control Charts

These graphs were popularized by Walter Shewhart in his work in the 1920s at Western Electric. A control chart is a plot of a measurements over time with statistical limits applied. Actually, *control* chart is a slight misnomer. The chart itself is actually a monitoring tool. The control activity may occur if the chart indicates that the process is changing in an undesirable systematic direction.

The Statistics Toolbox supports three common control charts, described in the following sections:

- "Xbar Charts"
- "S Charts"
- "EWMA Charts"

### Xbar Charts

Xbar charts are a plot of the average of a sample of a process taken at regular intervals. Suppose we are manufacturing pistons to a tolerance of 0.5 thousandths of an inch. We measure the runout (deviation from circularity in thousandths of an inch) at four points on each piston.

```
load parts
conf = 0.99;
spec = [-0.5 0.5];
xbarplot(runout, conf, spec)
```

Xbar Chart
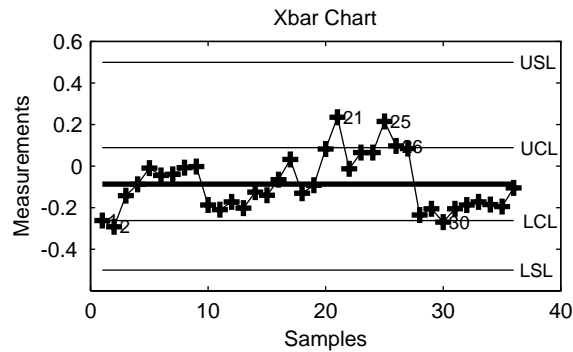


The lines at the bottom and the top of the plot show the process specifications. The central line is the average runout over all the pistons. The two lines flanking the center line are the 99% statistical control limits. By chance only one measurement in 100 should fall outside these lines. We can see that even in this small run of 36 parts, there are several points outside the boundaries (labeled by their observation numbers). This is an indication that the process mean is not in statistical control. This might not be of much concern in practice, since all the parts are well within specification.

### S Charts

The S chart is a plot of the standard deviation of a process taken at regular intervals. The standard deviation is a measure of the variability of a process. So, the plot indicates whether there is any systematic change in the process variability. Continuing with the piston manufacturing example, we can look at the standard deviation of each set of four measurements of runout.

```
schart(runout)
```

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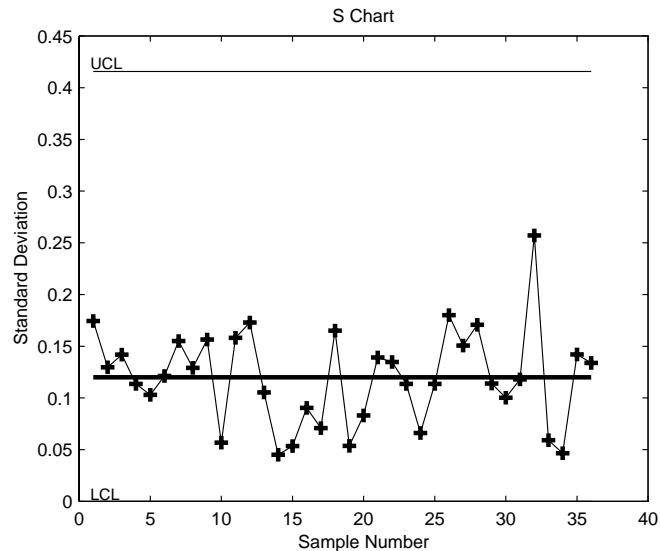
The average runout is about 0.1 thousandths of an inch. There is no indication of nonrandom variability.

### EWMA Charts

The exponentially-weighted moving average (EWMA) chart is another chart for monitoring the process average. It operates on slightly different assumptions than the Xbar chart. The mathematical model behind the Xbar chart posits that the process mean is actually constant over time and any variation in individual measurements is due entirely to chance.

The EWMA model is a little looser. Here we assume that the mean may be varying in time. Here is an EWMA chart of our runout example. Compare this with the plot in "Xbar Charts" on page 1-138.

```
ewmaplot(runout, 0.5, 0.01, spec)
```

Exponentially Weighted Moving Average (EWMA) Chart
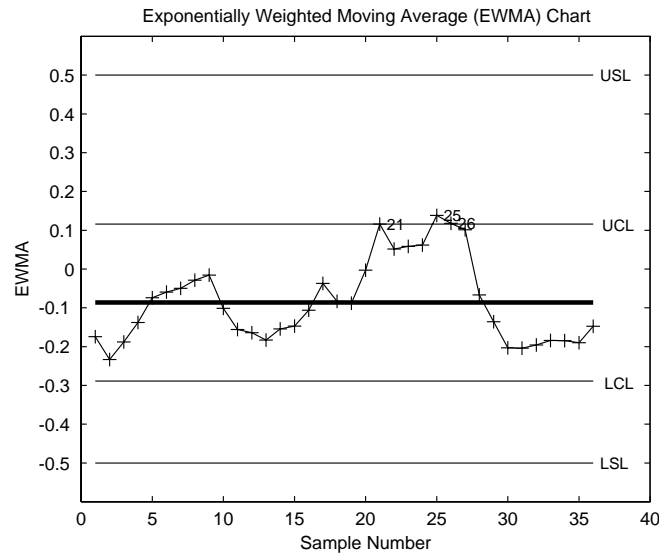


## Capability Studies

Before going into full-scale production, many manufacturers run a pilot study to determine whether their process can actually build parts to the specifications demanded by the engineering drawing.

Using the data from these capability studies with a statistical model allows us to get a preliminary estimate of the percentage of parts that will fall outside the specifications.

```
[p, Cp, Cpk]  = capable(mean(runout), spec)

p  =
   1.3940e-09

Cp  =
   2.3950

Cpk  =
   1.9812
```

The result above shows that the probability (p = 1.3940e-09) of observing an unacceptable runout is extremely low. Cp and Cpk are two popular capability indices.

$C_p$ is the ratio of the range of the specifications to six times the estimate of the process standard deviation.

$$C_p = \frac{USL - LSL}{6\sigma}$$

For a process that has its average value on target, a $C_p$ of 1 translates to a little more than one defect per thousand. Recently many industries have set a quality goal of one part per million. This would correspond to a $C_p = 1.6$. The higher the value of $C_p$, the more capable the process.

$C_{pk}$ is the ratio of difference between the process mean and the closer specification limit to three times the estimate of the process standard deviation.

$$C_{pk} = min\left(\frac{USL - \mu}{3\sigma}, \frac{\mu - LSL}{3\sigma}\right)$$

where the process mean is $\mu$. For processes that do not maintain their average on target, $C_{pk}$, is a more descriptive index of process capability.

# Design of Experiments (DOE)

There is a world of difference between data and information. To extract information from data you have to make assumptions about the system that generated the data. Using these assumptions and physical theory you may be able to develop a mathematical model of the system.

Generally, even rigorously formulated models have some unknown constants. The goal of experimentation is to acquire data that allow us to estimate these constants.

But why do we need to experiment at all? We could instrument the system we want to study and just let it run. Sooner or later we would have all the data we could use.

In fact, this is a fairly common approach. There are three characteristics of historical data that pose problems for statistical modeling:

- Suppose we observe a change in the operating variables of a system followed by a change in the outputs of the system. That does *not* necessarily mean that the change in the system *caused* the change in the outputs.

- A common assumption in statistical modeling is that the observations are independent of each other. This is not the way a system in normal operation works.

- Controlling a system in operation often means changing system variables in tandem. But if two variables change together, it is impossible to separate their effects mathematically.

Designed experiments directly address these problems. The overwhelming advantage of a designed experiment is that you actively manipulate the system you are studying. With DOE you may generate fewer data points than by using passive instrumentation, but the quality of the information you get will be higher.

The Statistics Toolbox provides several functions for generating experimental designs appropriate to various situations. These are discussed in the following sections:

- "Full Factorial Designs"
- "Fractional Factorial Designs"
- "D-Optimal Designs"

## Full Factorial Designs

Suppose you want to determine whether the variability of a machining process is due to the difference in the lathes that cut the parts or the operators who run the lathes.

If the same operator always runs a given lathe then you cannot tell whether the machine or the operator is the cause of the variation in the output. By allowing every operator to run every lathe you can separate their effects.

This is a factorial approach. `fullfact` is the function that generates the design. Suppose we have four operators and three machines. What is the factorial design?

```
d = fullfact([4 3])

d =
     1     1
     2     1
     3     1
     4     1
     1     2
     2     2
     3     2
     4     2
     1     3
     2     3
     3     3
     4     3
```

Each row of d represents one operator/machine combination. Note that there are 4*3 = 12 rows.

One special subclass of factorial designs is when all the variables take only two values. Suppose you want to quickly determine the sensitivity of a process to high and low values of three variables.

```
d2 = ff2n(3)
```

```
d2 =
     0      0      0
     0      0      1
     0      1      0
     0      1      1
     1      0      0
     1      0      1
     1      1      0
     1      1      1
```

There are $2^3 = 8$ combinations to check.

## Fractional Factorial Designs

One difficulty with factorial designs is that the number of combinations increases exponentially with the number of variables you want to manipulate.

For example, the sensitivity study discussed above might be impractical if there were seven variables to study instead of just three. A full factorial design would require $2^7 = 128$ runs!

If we assume that the variables do not act synergistically in the system, we can assess the sensitivity with far fewer runs. The theoretical minimum number is eight. A design known as the Plackett-Burman design uses a Hadamard matrix to define this minimal number of runs. To see the design (X) matrix for the Plackett-Burman design, we use the hadamard function.

```
X = hadamard(8)

X =
     1      1      1      1      1      1      1      1
     1    - 1      1    - 1      1    - 1      1    - 1
     1      1    - 1    - 1      1      1    - 1    - 1
     1    - 1    - 1      1      1    - 1    - 1      1
     1      1      1      1    - 1    - 1    - 1    - 1
     1    - 1      1    - 1    - 1      1    - 1      1
     1      1    - 1    - 1    - 1    - 1      1      1
     1    - 1    - 1      1    - 1      1      1    - 1
```

The last seven columns are the actual variable settings (-1 for low, 1 for high.) The first column (all ones) allows us to measure the mean effect in the linear equation, $y = X\beta + \varepsilon$.

The Plackett-Burman design enables us to study the main (linear) effects of each variable with a small number of runs. It does this by using a fraction, in this case 8/128, of the runs required for a full factorial design. A drawback of this design is that if the effect of one variable does vary with the value of another variable, then the estimated effects will be biased (that is, they will tend to be off by a systematic amount).

At a cost of a somewhat larger design, we can find a fractional factorial that is much smaller than a full factorial, but that does allow estimation of main effects independent of interactions between pairs of variables. We can do this by specifying generators that control the confounding between variables.

As an example, suppose we create a design with the first four variables varying independently as in a full factorial, but with the other three variables formed by multiplying different triplets of the first four. With this design the effects of the last three variables are confounded with three-way interactions among the first four variables. The estimated effect of any single variable, however, is not confounded with (is independent of) interaction effects between any pair of variables. Interaction effects are confounded with each other. Box, Hunter, and Hunter (1978) present the properties of these designs and provide the generators needed to produce them.

The `fracfact` function can produce this fractional factorial design using the generator strings that Box, Hunter, and Hunter provide.

```
X = fracfact('a b c d abc bcd acd')
```

```
X =
     -1      -1      -1      -1      -1      -1      -1
     -1      -1      -1       1      -1       1       1
     -1      -1       1      -1       1       1       1
     -1      -1       1       1       1      -1      -1
     -1       1      -1      -1       1       1      -1
     -1       1      -1       1       1      -1       1
     -1       1       1      -1      -1      -1       1
     -1       1       1       1      -1       1      -1
      1      -1      -1      -1       1      -1       1
      1      -1      -1       1       1       1      -1
      1      -1       1      -1      -1       1      -1
      1      -1       1       1      -1      -1       1
      1       1      -1      -1      -1       1       1
      1       1      -1       1      -1      -1      -1
      1       1       1      -1       1      -1      -1
      1       1       1       1       1       1       1
```

## D-Optimal Designs

All the designs above were in use by early in the 20th century. In the 1970s statisticians started to use the computer in experimental design by recasting the design of experiments (DOE) in terms of optimization. A D-optimal design is one that maximizes the determinant of Fisher's information matrix, $X^{T}X$. This matrix is proportional to the inverse of the covariance matrix of the parameters. So maximizing $det(X^{T}X)$ is equivalent to minimizing the determinant of the covariance of the parameters.

A D-optimal design minimizes the volume of the confidence ellipsoid of the regression estimates of the linear model parameters, β.

There are several functions in the Statistics Toolbox that generate D-optimal designs. These are cordexch, daugment, dcovary, and rowexch. The following sections explore D-optimal design in greater detail:

- "Generating D-Optimal Designs"
- "Augmenting D-Optimal Designs"
- "Designing Experiments with Uncontrolled Inputs"

### Generating D-Optimal Designs

cordexch and rowexch are two competing optimization algorithms for computing a D-optimal design given a model specification.

Both cordexch and rowexch are iterative algorithms. They operate by improving a starting design by making incremental changes to its elements. In the coordinate exchange algorithm, the increments are the individual elements of the design matrix. In row exchange, the elements are the rows of the design matrix. Atkinson and Donev (1992) is a reference.

To generate a D-optimal design you must specify the number of inputs, the number of runs, and the order of the model you want to fit.

Both cordexch and rowexch take the following strings to specify the model:

- 'linear' or 'l' – the default model with constant and first order terms
- 'interaction' or 'i' – includes constant, linear, and cross product terms
- 'quadratic' or 'q' – interactions plus squared terms
- 'purequadratic' or 'p' – includes constant, linear and squared terms

Alternatively, you can use a matrix of integers to specify the terms. Details are in the help for the utility function x2fx.

For a simple example using the coordinate-exchange algorithm, consider the problem of quadratic modeling with two inputs. The model form is

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + \beta_{11} x_1^2 + \beta_{22} x_2^2 + \varepsilon$$

Suppose we want the D-optimal design for fitting this model with nine runs.
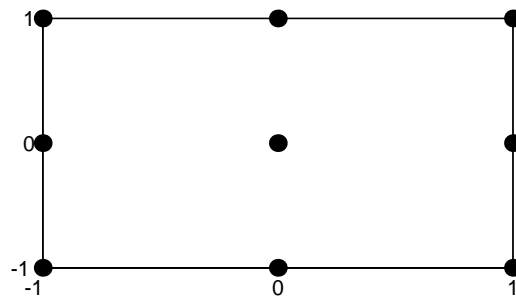
```
settings = cordexch(2, 9, 'q')
settings =

    -1     1
     1     1
     0     1
     1    -1
    -1    -1
     0    -1
     1     0
     0     0
    -1     0
```

We can plot the columns of settings against each other to get a better picture of the design.

```
h = plot(settings(:,1),settings(:,2),'.');
set(gca,'Xtick',[-1 0 1])
set(gca,'Ytick',[-1 0 1])
set(h,'Markersize',20)
```



For a simple example using the row-exchange algorithm, consider the interaction model with two inputs. The model form is

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + \varepsilon$$

Suppose we want the D-optimal design for fitting this model with four runs.

```
[settings, X] = rowexch(2,4,'i')

settings =

    -1     1
    -1    -1
     1    -1
     1     1

X =
     1    -1     1    -1
     1    -1    -1     1
     1     1    -1    -1
     1     1     1     1
```

The settings matrix shows how to vary the inputs from run to run. The X matrix is the design matrix for fitting the above regression model. The first column of X

is for fitting the constant term. The last column is the element-wise product of the second and third columns.

The associated plot is simple but elegant.

```
h = plot(settings(:, 1), settings(:, 2), '.');
set(gca, 'Xtick', [-1 0 1])
set(gca, 'Ytick', [-1 0 1])
set(h, 'Markersize', 20)
```
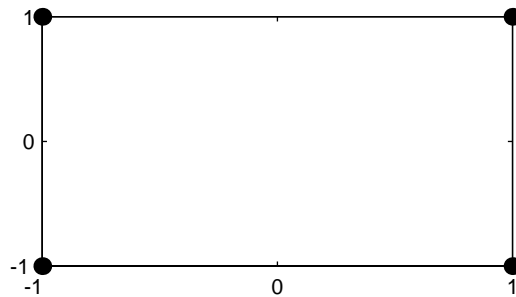


### Augmenting D-Optimal Designs

In practice, experimentation is an iterative process. We often want to add runs to a completed experiment to learn more about our system. The function daugment allows you choose these extra runs optimally.

Suppose we have executed the eight-run design below for fitting a linear model to four input variables.

```
settings = cordexch(4, 8)
settings =

     1    -1     1     1
    -1    -1     1    -1
    -1     1     1     1
     1     1     1    -1
    -1     1    -1     1
     1    -1    -1     1
    -1    -1    -1    -1
     1     1    -1    -1
```

This design is adequate to fit the linear model for four inputs, but cannot fit the six cross-product (interaction) terms. Suppose we are willing to do eight more runs to fit these extra terms. Here's how.

```
[augmented, X] = daugment(settings,8,'i');

augmented
augmented =

      1    -1     1     1
     -1    -1     1    -1
     -1     1     1     1
      1     1     1    -1
     -1     1    -1     1
      1    -1    -1     1
     -1    -1    -1    -1
      1     1    -1    -1
     -1    -1    -1     1
      1     1     1     1
     -1    -1     1     1
     -1     1     1    -1
      1    -1     1    -1
      1    -1    -1    -1
     -1     1    -1    -1
      1     1    -1     1

info = X'*X
info =

     16     0     0     0     0     0     0     0     0     0     0
      0    16     0     0     0     0     0     0     0     0     0
      0     0    16     0     0     0     0     0     0     0     0
      0     0     0    16     0     0     0     0     0     0     0
      0     0     0     0    16     0     0     0     0     0     0
      0     0     0     0     0    16     0     0     0     0     0
      0     0     0     0     0     0    16     0     0     0     0
      0     0     0     0     0     0     0    16     0     0     0
      0     0     0     0     0     0     0     0    16     0     0
      0     0     0     0     0     0     0     0     0    16     0
      0     0     0     0     0     0     0     0     0     0    16
```

The augmented design is orthogonal, since X' *X is a multiple of the identity matrix. In fact, this design is the same as a $2^4$ factorial design.

### Designing Experiments with Uncontrolled Inputs

Sometimes it is impossible to control every experimental input. But you may know the values of some inputs in advance. An example is the time each run takes place. If a process is experiencing linear drift, you may want to include the time of each test run as a variable in the model.

The function dcovary allows you to choose the settings for each run in order to maximize your information despite a linear drift in the process.

Suppose we want to execute an eight-run experiment with three factors that is optimal with respect to a linear drift in the response over time. First we create our drift input variable. Note, that drift is normalized to have mean zero. Its minimum is -1 and its maximum is 1.

```
drift = (linspace(-1, 1, 8))'
drift =

    -1.0000
    -0.7143
    -0.4286
    -0.1429
     0.1429
     0.4286
     0.7143
     1.0000

settings = dcovary(3, drift, 'linear')
settings =

     1.0000     1.0000    -1.0000    -1.0000
    -1.0000    -1.0000    -1.0000    -0.7143
    -1.0000     1.0000     1.0000    -0.4286
     1.0000    -1.0000     1.0000    -0.1429
    -1.0000     1.0000    -1.0000     0.1429
     1.0000     1.0000     1.0000     0.4286
    -1.0000    -1.0000     1.0000     0.7143
     1.0000    -1.0000    -1.0000     1.0000
```

# Demos

The Statistics Toolbox has demonstration programs that create an interactive environment for exploring the probability distributions, random number generation, curve fitting, and design of experiments functions. Most of them provide a graphical user interface that can be used with your real data, not just with the sample data provided.

The available demos are listed below.

| Demo | Purpose |
|------|---------|
| aoctool | Interactive graphic prediction of anocova fits |
| disttool | Graphic interaction with probability distributions |
| glmdemo | Generalized linear models slide show |
| nlintool | Interactive fitting of nonlinear models |
| polytool | Interactive graphic prediction of polynomial fits |
| randtool | Interactive control of random number generation |
| robustdemo | Interactive comparison of robust and least squares fits |
| rsmdemo | Design of experiments and regression modeling |
| rstool | Exploring graphs of multidimensional polynomials |
| stepwise | Interactive stepwise regression |

Most of these functions are described below. The nlintool, rstool, and stepwise demos are discussed in earlier sections:

- nlintool: "An Interactive GUI for Nonlinear Fitting and Prediction" on page 1-104
- rstool: "Exploring Graphs of Multidimensional Polynomials" on page 1-86
- stepwise: "Example: Stepwise Regression" on page 1-88

## The disttool Demo

disttool is a graphic environment for developing an intuitive understanding of probability distributions.

The disttool demo has the following features:

- A graph of the cdf (pdf) for the given parameters of a distribution.
- A pop-up menu for changing the distribution function.
- A pop-up menu for changing the function type (cdf <–> pdf).
- Sliders to change the parameter settings.
- Data entry boxes to choose specific parameter values.
- Data entry boxes to change the limits of the parameter sliders.
- Draggable horizontal and vertical reference lines to do interactive evaluation of the function at varying values.
- A data entry box to evaluate the function at a specific *x*-value.
- For cdf plots, a data entry box on the probability axis (*y*-axis) to find critical values corresponding to a specific probability.
- A **Close** button to end the demonstration.
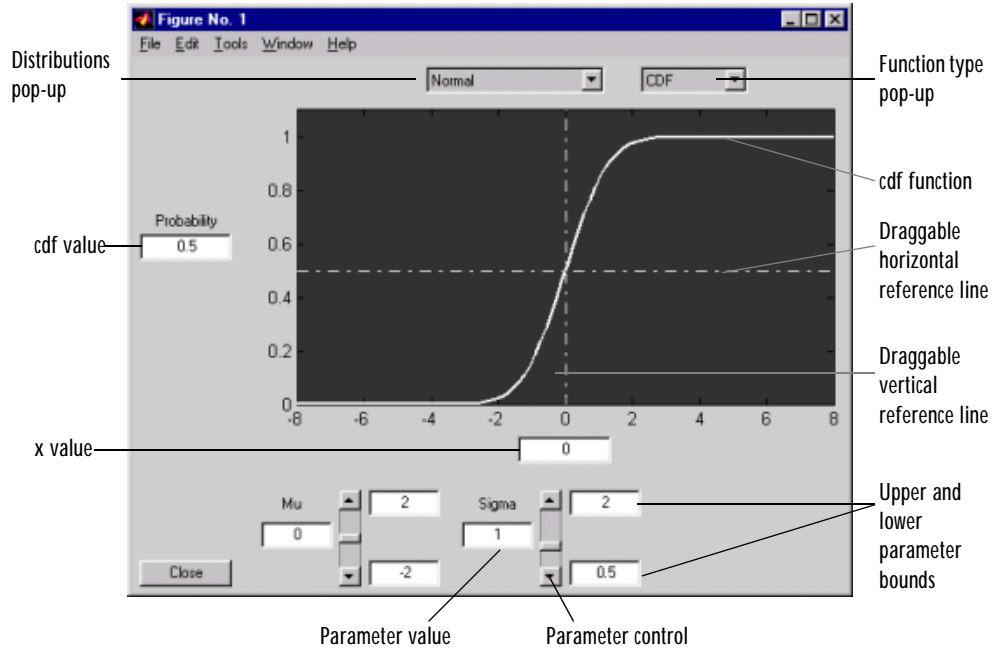
## The polytool Demo

The `polytool` demo is an interactive graphic environment for polynomial curve fitting and prediction.

The `polytool` demo has the following features:

- A graph of the data, the fitted polynomial, and global confidence bounds on a new predicted value.
- *y*-axis text to display the predicted *y*-value and its uncertainty at the current *x*-value.
- A data entry box to change the degree of the polynomial fit.
- A data entry box to evaluate the polynomial at a specific *x*-value.
- A draggable vertical reference line to do interactive evaluation of the polynomial at varying *x*-values.
- **Bounds** and **Method** menus to control the confidence bounds and choose between least squares or robust fitting.
- A **Close** button to end the demonstration.
- An **Export** list box to store fit results into variables.

You can use `polytool` to do curve fitting and prediction for any set of *x-y* data, but, for the sake of demonstration, the Statistics Toolbox provides a data set (`polydata.mat`) to teach some basic concepts.

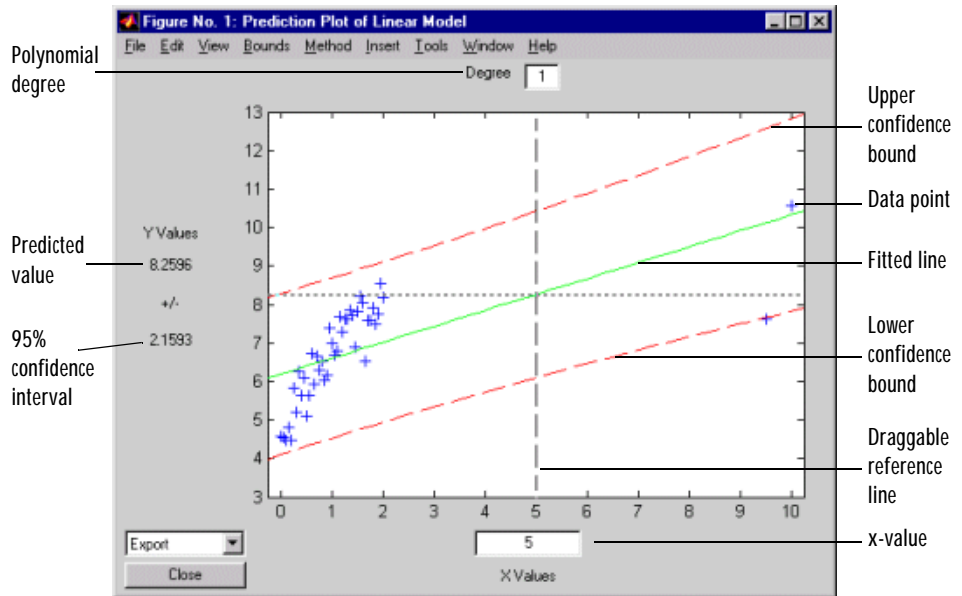To start the demonstration, you must first load the data set.

```
load polydata
who

Your variables are:

x          x1          y          y1
```

The variables x and y are observations made with error from a cubic polynomial. The variables x1 and y1 are data points from the "true" function without error.

If you do not specify the degree of the polynomial, `polytool` does a linear fit to the data.

```
polytool(x, y)
```

Polynomial degree

Predicted value

95% confidence interval

Upper confidence bound

Data point

Fitted line

Lower confidence bound

Draggable reference line

x-value

The linear fit is not very good. The bulk of the data with *x*-values between zero and two has a steeper slope than the fitted line. The two points to the right are dragging down the estimate of the slope.

In the **Degree** box at the top, type 3 for a cubic model. Then, drag the vertical reference line to the *x*-value of 2 (or type 2 in the **X Values** text box).

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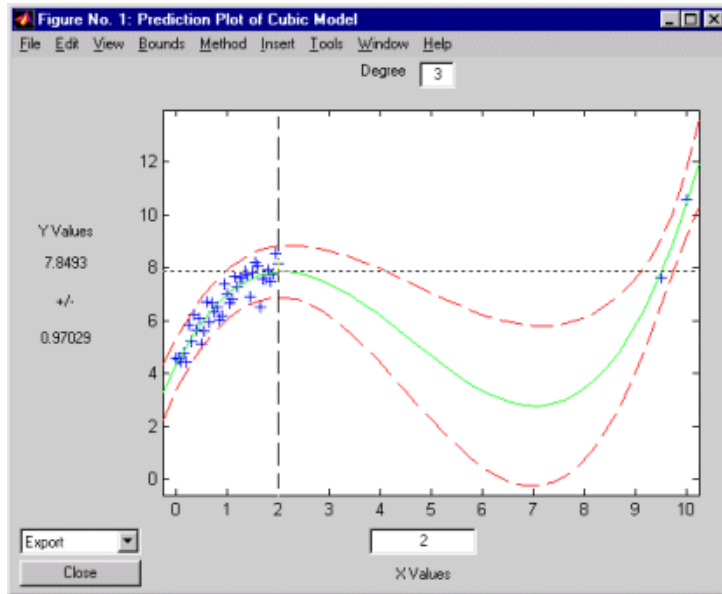
This graph shows a much better fit to the data. The confidence bounds are closer together indicating that there is less uncertainty in prediction. The data at both ends of the plot tracks the fitted curve.

The following sections explore additional aspects of the tool:

- "Confidence Bounds"
- "Overfitting"

### Confidence Bounds
By default, the confidence bounds are nonsimultaneous bounds for a new observation. What does this mean? Let $p(x)$ be the true but unknown function we want to estimate. The graph contains the following three curves:

- $f(x)$, our fitted function
- $l(x)$, the lower confidence bounds
- $u(x)$, the upper confidence bounds

Suppose we plan to take a new observation at the value $x_{n+1}$. Call it $y_{n+1}(x_{n+1})$. This new observation has its own error $\varepsilon_{n+1}$, so it satisfies the equation

$$y_{n+1}(x_{n+1}) = p(x_{n+1}) + \varepsilon_{n+1}$$

What are the likely values for this new observation? The confidence bounds provide the answer. The interval $[l_{n+1}, u_{n+1}]$ is a 95% confidence bound for $y_{n+1}(x_{n+1})$.

These are the default bounds, but the **Bounds** menu on the polytool figure window provides options for changing the meaning of these bounds. This menu has options that let you specify whether the bounds are to apply to the estimated function or to a new observation, and whether the bounds should be simultaneous or not. Using these options you can produce any of the following types of confidence bounds.

| Simultaneous? | For Quantity | Yields Confidence Bounds for |
|---|---|---|
| Nonsimultaneous | Observation | $y_{n+1}(x_{n+1})$ |
| Nonsimultaneous | Curve | $p(x_{n+1})$ |
| Simultaneous | Observation | $y_{n+1}(x)$, globally for any $x$ |
| Simultaneous | Curve | $p(x)$, simultaneously for all $x$ |

### Overfitting

If the cubic polynomial is a good fit, it is tempting to try a higher order polynomial to see if even more precise predictions are possible.

Since the true function is cubic, this amounts to overfitting the data. Use the data entry box for degree and type 5 for a quintic model.
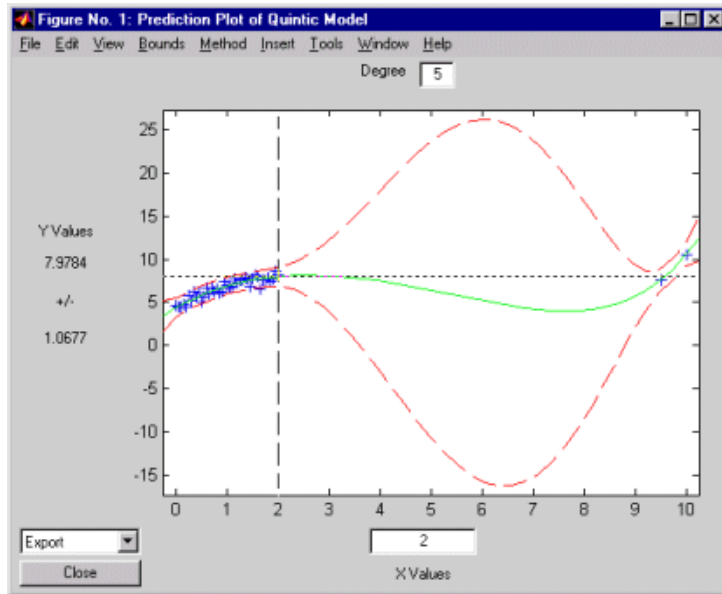
As measured by the confidence bounds, the fit is precise near the data points. But, in the region between the data groups, the uncertainty of prediction rises dramatically.

This bulge in the confidence bounds happens because the data really does not contain enough information to estimate the higher order polynomial terms precisely, so even interpolation using polynomials can be risky in some cases.

## The aoctool Demo

The `aoctool` demo is an interactive graphical environment for fitting and prediction with analysis of covariance (anocova) models. It is similar to the `polytool` demo.

Analysis of covariance is a technique for analyzing grouped data having a response (*y*, the variable to be predicted) and a predictor (*x*, the variable used to do the prediction). Using analysis of covariance, you can model *y* as a linear function of *x*, with the coefficients of the line possibly varying from group to group. The `aoctool` function fits the following models for the *i*th group:

**1** same mean $\qquad\qquad y = \alpha + \varepsilon$

**2** separate means $\qquad\quad y = (\alpha + \alpha_i) + \varepsilon$

**3** same line $\qquad\qquad\quad y = \alpha + \beta x + \varepsilon$

**4** parallel lines $\qquad\qquad y = (\alpha + \alpha_i) + \beta x + \varepsilon$

**5** separate lines $\qquad\qquad y = (\alpha + \alpha_i) + (\beta + \beta_i)x + \varepsilon$

In the fourth model, for example, the intercept varies from one group to the next, but the slope is the same for each group. In the first model, there is a common intercept and no slope. In order to make the group coefficients well determined, we impose the constraints $\Sigma\alpha_i = \Sigma\beta_i = 0$.

The `aoctool` demo displays the results of the fit in three figure windows. One window displays estimates of the coefficients ($\alpha$, $\alpha_i$, $\beta$, $\beta_i$). A second displays an analysis of variance table that you can use to test whether a more complex model is significantly better than a simpler one. The third, main graphics window has the following features:

- A graph of the data with superimposed fitted lines and optional confidence bounds.
- *y*-axis text to display the predicted *y*-value and its uncertainty at the current *x*-value for the current group, if a group is currently selected.
- A data entry box to evaluate the fit at a specific *x*-value.
- A list box to evaluate the fit for a specific group or to display fitted lines for all groups.
- A draggable vertical reference line to do interactive evaluation of the fit at varying *x*-values.

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- A **Close** button to end the demonstration.
- An **Export** list box to store fit results into variables.

The following section provides an illustrative example.

### Example: aoctool with Sample Data

The Statistics Toolbox has a small data set named `carsmall` with information about cars. It is a good sample data set to use with `aoctool`. You can also use `aoctool` with your own data.

To start the demonstration, load the data set.

```
load carsmall
who

Your variables are:

Acceleration    Horsepower    Model_Year
Cylinders       MPG           Origin
Displacement    Model         Weight
```

Suppose we want to study the relationship between the weight of a car and its mileage, and whether this relationship has changed over the years.

Next, start up the tool.

```
[h, atab, ctab, stats] = aoctool(Weight, MPG, Model_Year);
Note: 6 observations with missing values have been removed.
```

The graphical output consists of the following main window, plus a table of coefficient estimates and an analysis of variance table.
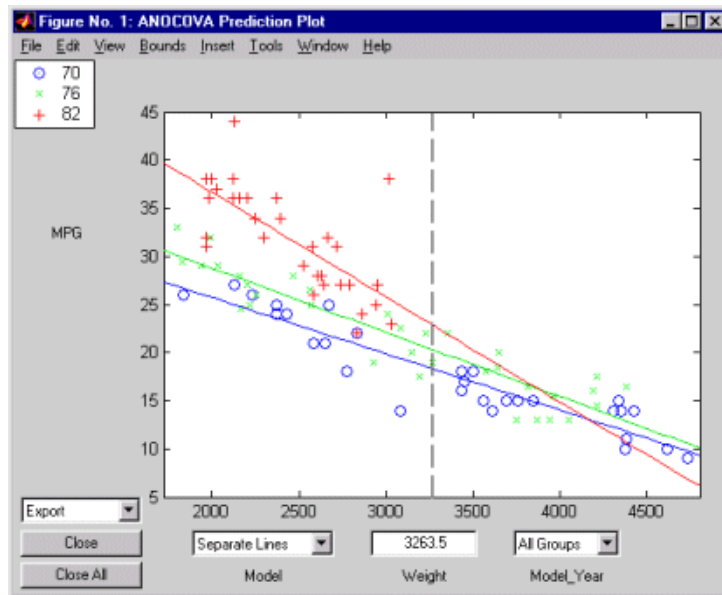
The group of each data point is coded by its color and symbol, and the fit for each group has the same color as the data points.



The initial fit models the *y* variable, MPG, as a linear function of the *x* variable, Weight. Each group has a separate line. The coefficients of the three lines
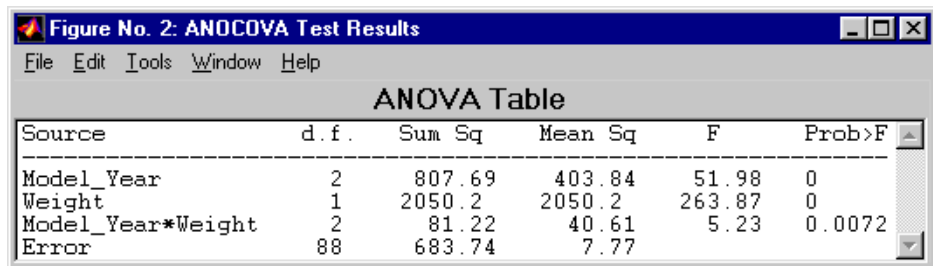
appear in the figure titled **ANOCOVA Coefficients**. You can see that the slopes are roughly -0.0078, with a small deviation for each group:

Model year 70: $\quad y = (45.9798 - 8.5805) + (-0.0078 + 0.002)x + \varepsilon$

Model year 76: $\quad y = (45.9798 - 3.8902) + (-0.0078 + 0.0011)x + \varepsilon$

Model year 82: $\quad y = (45.9798 + 12.4707) + (-0.0078 - 0.0031)x + \varepsilon$

Notice that the three fitted lines have slopes that are roughly similar. Could they really be the same? The Model_Year*Weight interaction expresses the difference in slopes, and the ANOVA table shows a test for the significance of this term. With an F statistic of 5.23 and a p-value of 0.0072, the slopes are significantly different.

Figure No. 2: ANOCOVA Test Results

File  Edit  Tools  Window  Help

### ANOVA Table

| Source | d.f. | Sum Sq | Mean Sq | F | Prob>F |
|--------|------|--------|---------|---|--------|
| Model_Year | 2 | 807.69 | 403.84 | 51.98 | 0 |
| Weight | 1 | 2050.2 | 2050.2 | 263.87 | 0 |
| Model_Year*Weight | 2 | 81.22 | 40.61 | 5.23 | 0.0072 |
| Error | 88 | 683.74 | 7.77 | | |

To examine the fits when the slopes are constrained to be the same, return to the **ANOCOVA Prediction Plot** window and use the **Model** pop-up to select a **Parallel Lines** model. The window updates to show the graph below.
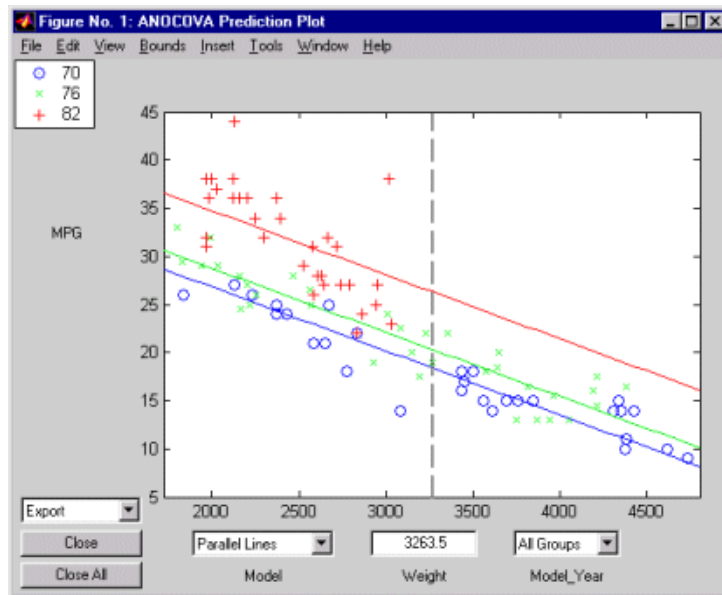
Though this fit looks reasonable, we know it is significantly worse than the **Separate Lines** model. Use the **Model** pop-up again to return to the original model.

The following sections focus on two other interesting aspects of aoctool:

- "Confidence Bounds"
- "Multiple Comparisons"

Confidence Bounds.  Now we have estimates of the relationship between MPG and Weight for each Model_Year, but how accurate are they? We can superimpose confidence bounds on the fits by examining them one group at a time. In the **Model_Year** menu at the lower right of the figure, change the setting from **All Groups** to 82. The data and fits for the other groups are dimmed, and confidence bounds appear around the 82 fit.
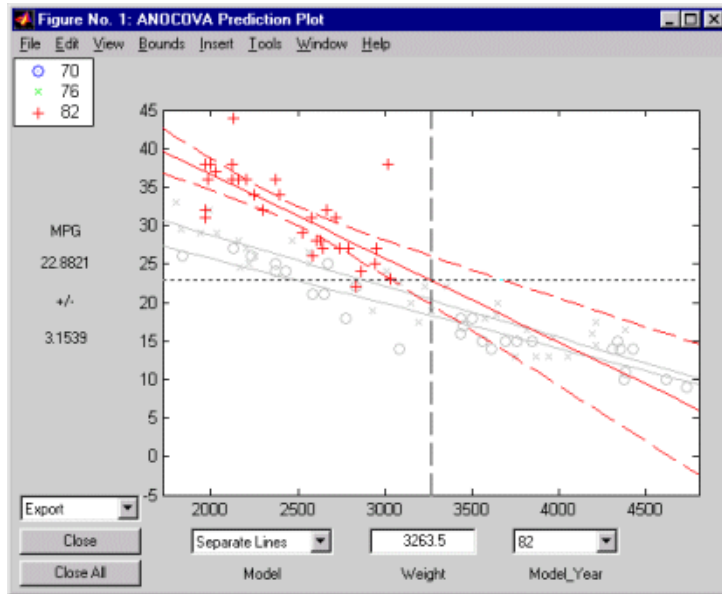
The dashed lines form an envelope around the fitted line for model year 82. Under the assumption that the true relationship is linear, these bounds provide a 95% confidence region for the true line. Note that the fits for the other model years are well outside these confidence bounds for Weight values between 2000 and 3000.

Sometimes it is more valuable to be able to predict the response value for a new observation, not just estimate the average response value. Like the polytool function, the aoctool function has a **Bounds** menu to change the definition of the confidence bounds. Use that menu to change from **Line** to **Observation**. The resulting wider intervals reflect the uncertainty in the parameter estimates as well as the randomness of a new observation.
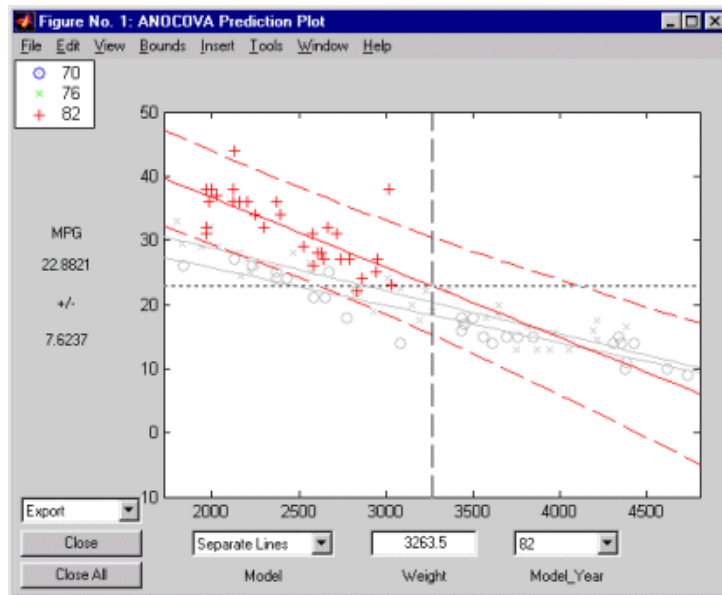
Also like the polytool function, the aoctool function has crosshairs you can use to manipulate the Weight and watch the estimate and confidence bounds along the *y*-axis update. These values appear only when a single group is selected, not when **All Groups** is selected.

**Multiple Comparisons.** We can perform a multiple comparison test by using the stats output from aoctool as input to the multcompare function. The multcompare function can test either slopes, intercepts, or population marginal means (the heights of the four lines evaluated at the mean X value). In this example, we have already determined that the slopes are not all the same, but could it be that two are the same and only the other one is different? We can test that hypothesis.

```
multcompare(stats, 0.05, 'on', '', 's')

ans =

    1.0000    2.0000   -0.0012    0.0008    0.0029
    1.0000    3.0000    0.0013    0.0051    0.0088
    2.0000    3.0000    0.0005    0.0042    0.0079
```

This matrix shows that the estimated difference between the intercepts of groups 1 and 2 (1970 and 1976) is 0.0008, and a confidence interval for the difference is [-0.0012, 0.0029]. There is no significant difference between the two. There are significant differences, however, between the intercept for 1982 and each of the other two. The graph shows the same information.
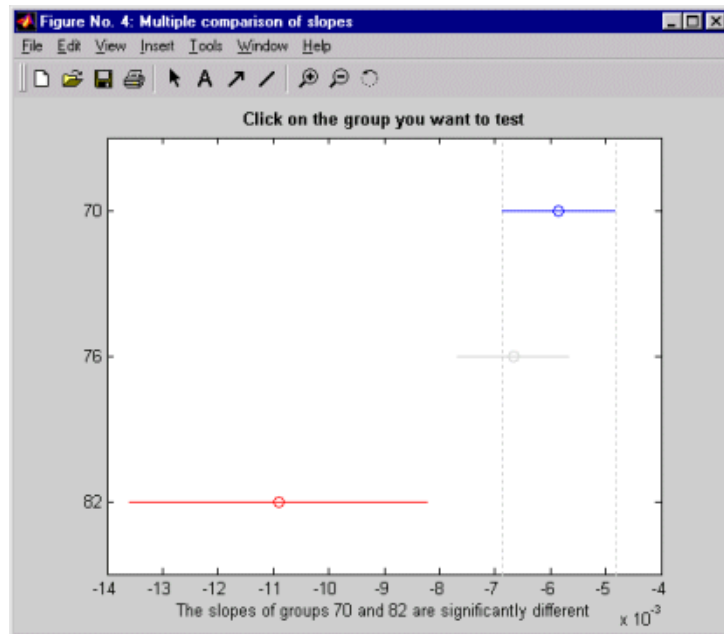


Note that the stats structure was created in the initial call to the aoctool function, so it is based on the initial model fit (typically a separate-lines model). If you change the model interactively and want to base your multiple comparisons on the new model, you need to run aoctool again to get another stats structure, this time specifying your new model as the initial model.

## The randtool Demo

randtool is a graphic environment for generating random samples from various probability distributions and displaying the sample histogram.

The randtool demo has the following features:

- A histogram of the sample.
- A pop-up menu for changing the distribution function.
- Sliders to change the parameter settings.
- A data entry box to choose the sample size.
- Data entry boxes to choose specific parameter values.
- Data entry boxes to change the limits of the parameter sliders.
- An **Output** button to output the current sample to the variable ans.
- A **Resample** button to allow repetitive sampling with constant sample size and fixed parameters.
- A **Close** button to end the demonstration.
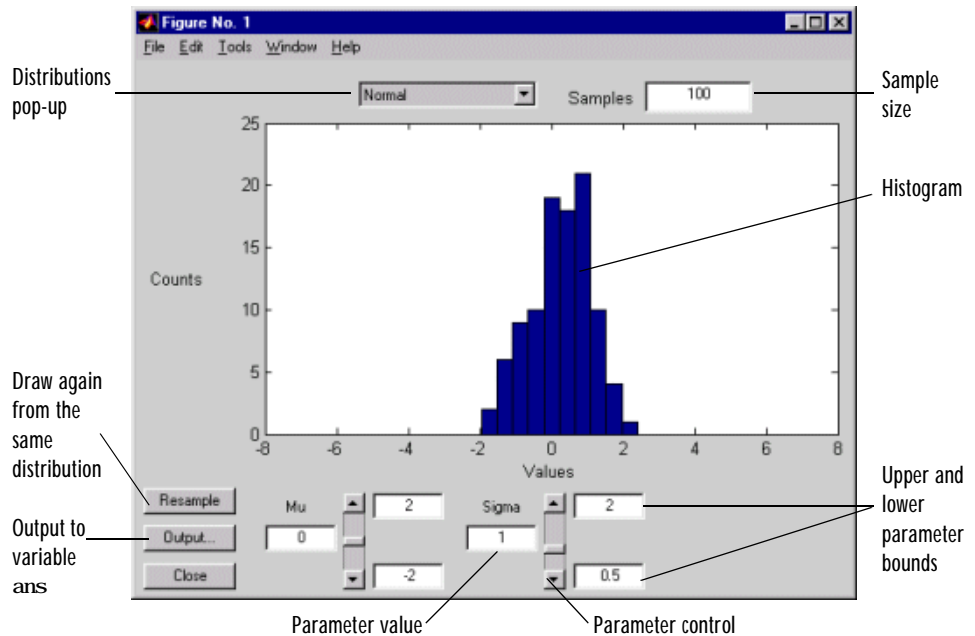
## The rsmdemo Demo

The rsmdemo utility is an interactive graphic environment that demonstrates the design of experiments and surface fitting through the simulation of a chemical reaction. The goal of the demo is to find the levels of the reactants needed to maximize the reaction rate.

There are two parts to the demo:

- "Part 1" – Compare data gathered through trial and error with data from a designed experiment.
- "Part 2" – Compare response surface (polynomial) modeling with nonlinear modeling.

### Part 1

Begin the demo by using the sliders in the **Reaction Simulator** window to control the partial pressures of three reactants: **Hydrogen**, **n-Pentane**, and **Isopentane**. Each time you click the **Run** button, the levels for the reactants and results of the run are entered in the **Trial and Error Data** window.

Based on the results of previous runs, you can change the levels of the reactants to increase the reaction rate. (The results are determined using an underlying model that takes into account the noise in the process, so even if you keep all of the levels the same, the results will vary from run to run.) You are allotted a budget of 13 runs. When you have completed the runs, you can use the **Plot** menu on the **Trial and Error Data** window to plot the relationships between the reactants and the reaction rate, or click the **Analyze** button. When you click **Analyze**, rsmdemo calls the rstool function, which you can then use to try to optimize the results.)

Next, perform another set of 13 runs, this time from a designed experiment. In the **Experimental Design Data** window, click the **Do Experiment** button. rsmdemo calls the cordexch function to generate a D-optimal design, and then, for each run, computes the reaction rate.

Now use the **Plot** menu on the **Experimental Design Data** window to plot the relationships between the levels of the reactants and the reaction rate, or click the **Response Surface** button to call rstool to find the optimal levels of the reactants.

Compare the analysis results for the two sets of data. It is likely (though not certain) that you'll find some or all of these differences:

- You can fit a full quadratic model with the data from the designed experiment, but the trial and error data may be insufficient for fitting a quadratic model or interactions model.
- Using the data from the designed experiment, you are more likely to be able to find levels for the reactants that result in the maximum reaction rate. Even if you find the best settings using the trial and error data, the confidence bounds are likely to be wider than those from the designed experiment.

### Part 2

Now analyze the experimental design data with a polynomial model and a nonlinear model, and comparing the results. The true model for the process, which is used to generate the data, is actually a nonlinear model. However, within the range of the data, a quadratic model approximates the true model quite well.

To see the polynomial model, click the **Response Surface** button on the **Experimental Design Data** window. rsmdemo calls rstool, which fits a full quadratic model to the data. Drag the reference lines to change the levels of the reactants, and find the optimal reaction rate. Observe the width of the confidence intervals.

Now click the **Nonlinear Model** button on the **Experimental Design Data** window. rsmdemo calls nlintool, which fits a Hougen-Watson model to the data. As with the quadratic model, you can drag the reference lines to change the reactant levels. Observe the reaction rate and the confidence intervals.

Compare the analysis results for the two models. Even though the true model is nonlinear, you may find that the polynomial model provides a good fit. Because polynomial models are much easier to fit and work with than nonlinear models, a polynomial model is often preferable even when modeling a nonlinear process. Keep in mind, however, that such models are unlikely to be reliable for extrapolating outside the range of the data.

## The glmdemo Demo

The gl mdemo function presents a simple slide show describing generalized linear models. It presents examples of what functions and distributions are available with generalized linear models. It presents an example where traditional linear least squares fitting is not appropriate, and shows how to use the gl mfi t function to fit a logistic regression model and the gl mval function to compute predictions from that model.

## The robustdemo Demo

The robustdemo function presents a simple comparison of least squares and robust fits for a response and a single predictor. You can use robustdemo with your own data or with the sample data provided.

To begin using robustdemo with the built-in sample data, simply type the function name.

```
robustdemo
```

The resulting figure presents a scatter plot with two fitted lines. One line is the fit from an ordinary least squares regression. The other is from a robust regression. Along the bottom of the figure are the equations for the fitted line and the estimated error standard deviation for each fit.

The effect of any point on the least squares fit depends on the residual and leverage for that point. The residual is simply the vertical distance from the point to the line. The leverage is a measure of how far the point is from the center of the X data.

The effect of any point on the robust fit also depends on the weight assigned to the point. Points far from the line get lower weight.

You can use the right mouse button to click on any point and see its least squares leverage and robust weight.
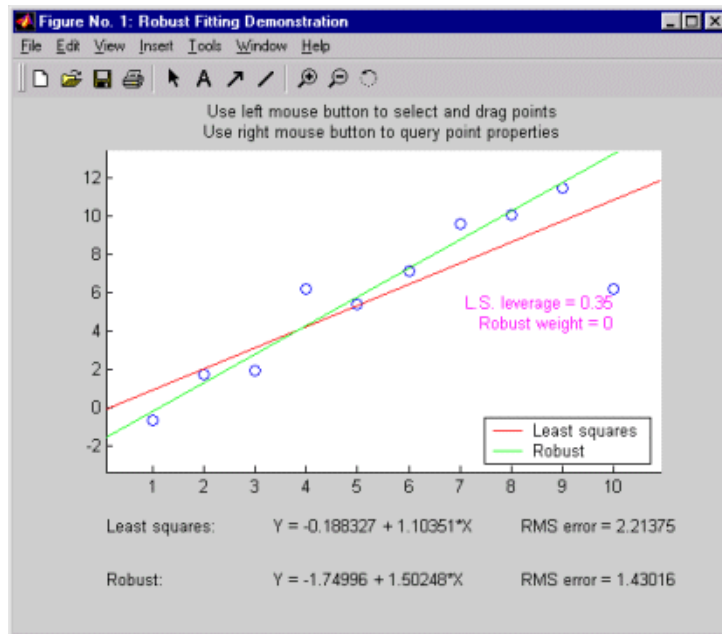
In this example, the rightmost point has a leverage value of 0.35. It is also far from the line, so it exerts a large influence on the least squares fit. It has a small weight, though, so it is effectively excluded from the robust fit.

Using the left mouse button, you can experiment to see how changes in the data affect the two fits. Select any point, and drag it to a new location while holding the left button down. When you release the point, both fits update.

Bringing the rightmost point closer to the line makes the two fitted lines nearly identical. Now, the point has nearly full weight in the robust fit.
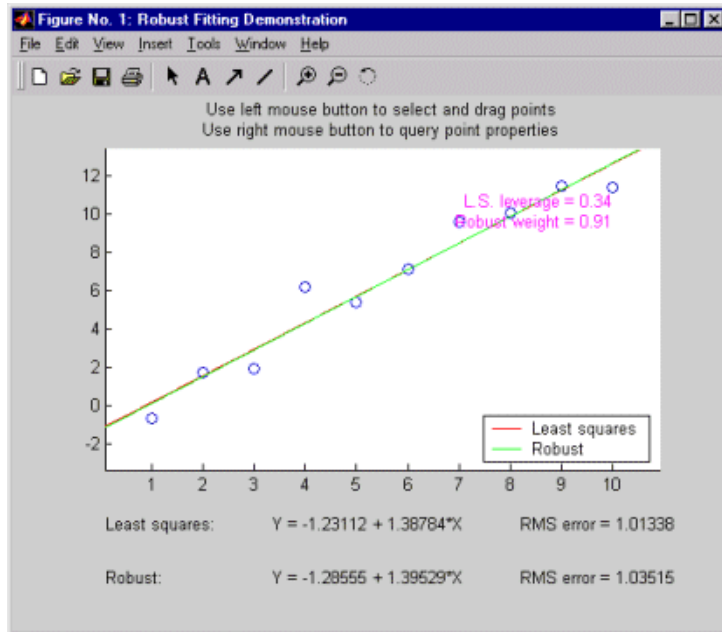
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# Reference

This chapter contains detailed descriptions of all the Statistics Toolbox functions. It is divided into two sections:

- "Function Category List" – a list of functions, grouped by subject area
- "Alphabetical List of Functions" – reference pages in alphabetical order

# Function Category List

The Statistics Toolbox provides several categories of functions.

| The Statistics Toolbox's Main Categories of Functions | |
| --- | --- |
| Probability Distributions | Parameter Estimation |
| | Cumulative Distribution Functions (cdf) |
| | Probability Density Functions (pdf) |
| | Inverse Cumulative Distribution Functions |
| | Random Number Generators |
| | Moments of Distribution Functions |
| Descriptive Statistics | Descriptive statistics for data samples |
| Statistical Plotting | Statistical plots |
| Statistical Process Control | Statistical Process Control |
| Cluster Analysis | Grouping items with similar characteristics into clusters |
| Linear Models | Fitting linear models to data |
| Nonlinear Regression | Fitting nonlinear regression models |
| Design of Experiments | Design of Experiments |
| Principal Components Analysis | Principal Components Analysis |
| Hypothesis Tests | Statistical tests of hypotheses |
| File I/O | Reading data from and writing data to operating-system files |
| Demonstrations | Demonstrations |
| Data | Data for examples |

The following tables list the functions in each of these specific areas. The first seven tables contain probability distribution functions. The remaining tables describe the other categories of functions.

| Parameter Estimation | |
| --- | --- |
| betafit | Parameter estimation for the beta distribution |
| betalike | Beta log-likelihood function |
| binofit | Parameter estimation for the binomial distribution |
| expfit | Parameter estimation for the exponential distribution |
| gamfit | Parameter estimation for the gamma distribution |
| gamlike | Gamma log-likelihood function |
| mle | Maximum likelihood estimation |
| normlike | Normal log-likelihood function |
| normfit | Parameter estimation for the normal distribution |
| poissfit | Parameter estimation for the Poisson distribution |
| unifit | Parameter estimation for the uniform distribution |

| Cumulative Distribution Functions (cdf) | |
| --- | --- |
| betacdf | Beta cdf |
| binocdf | Binomial cdf |
| cdf | Parameterized cdf routine |
| chi2cdf | Chi-square cdf |
| expcdf | Exponential cdf |

| Cumulative Distribution Functions (cdf) (Continued) | |
|---|---|
| fcdf | F cdf |
| gamcdf | Gamma cdf |
| geocdf | Geometric cdf |
| hygecdf | Hypergeometric cdf |
| logncdf | Lognormal cdf |
| nbincdf | Negative binomial cdf |
| ncfcdf | Noncentral F cdf |
| nctcdf | Noncentral t cdf |
| ncx2cdf | Noncentral Chi-square cdf |
| normcdf | Normal (Gaussian) cdf |
| poisscdf | Poisson cdf |
| raylcdf | Rayleigh cdf |
| tcdf | Student's t cdf |
| unidcdf | Discrete uniform cdf |
| unifcdf | Continuous uniform cdf |
| weibcdf | Weibull cdf |

| Probability Density Functions (pdf) | |
|---|---|
| betapdf | Beta pdf |
| binopdf | Binomial pdf |
| chi2pdf | Chi-square pdf |
| exppdf | Exponential pdf |

| Probability Density Functions (pdf) (Continued) | |
|---|---|
| fpdf | F pdf |
| gampdf | Gamma pdf |
| geopdf | Geometric pdf |
| hygepdf | Hypergeometric pdf |
| normpdf | Normal (Gaussian) pdf |
| lognpdf | Lognormal pdf |
| nbinpdf | Negative binomial pdf |
| ncfpdf | Noncentral F pdf |
| nctpdf | Noncentral t pdf |
| ncx2pdf | Noncentral Chi-square pdf |
| pdf | Parameterized pdf routine |
| poisspdf | Poisson pdf |
| raylpdf | Rayleigh pdf |
| tpdf | Student's t pdf |
| unidpdf | Discrete uniform pdf |
| unifpdf | Continuous uniform pdf |
| weibpdf | Weibull pdf |

| Inverse Cumulative Distribution Functions | |
|---|---|
| betainv | Beta critical values |
| binoinv | Binomial critical values |
| chi2inv | Chi-square critical values |

| Inverse Cumulative Distribution Functions (Continued) | |
|---|---|
| `expinv` | Exponential critical values |
| `finv` | F critical values |
| `gaminv` | Gamma critical values |
| `geoinv` | Geometric critical values |
| `hygeinv` | Hypergeometric critical values |
| `logninv` | Lognormal critical values |
| `nbininv` | Negative binomial critical values |
| `ncfinv` | Noncentral F critical values |
| `nctinv` | Noncentral t critical values |
| `ncx2inv` | Noncentral Chi-square critical values |
| `icdf` | Parameterized inverse distribution routine |
| `norminv` | Normal (Gaussian) critical values |
| `poissinv` | Poisson critical values |
| `raylinv` | Rayleigh critical values |
| `tinv` | Student's t critical values |
| `unidinv` | Discrete uniform critical values |
| `unifinv` | Continuous uniform critical values |
| `weibinv` | Weibull critical values |

| Random Number Generators | |
|---|---|
| `betarnd` | Beta random numbers |
| `binornd` | Binomial random numbers |

| Random Number Generators (Continued) | |
|---|---|
| chi2rnd | Chi-square random numbers |
| exprnd | Exponential random numbers |
| frnd | F random numbers |
| gamrnd | Gamma random numbers |
| geornd | Geometric random numbers |
| hygernd | Hypergeometric random numbers |
| lognrnd | Lognormal random numbers |
| nbinrnd | Negative binomial random numbers |
| ncfrnd | Noncentral F random numbers |
| nctrnd | Noncentral t random numbers |
| ncx2rnd | Noncentral Chi-square random numbers |
| normrnd | Normal (Gaussian) random numbers |
| poissrnd | Poisson random numbers |
| raylrnd | Rayleigh random numbers |
| random | Parameterized random number routine |
| trnd | Student's t random numbers |
| unidrnd | Discrete uniform random numbers |
| unifrnd | Continuous uniform random numbers |
| weibrnd | Weibull random numbers |

**Moments of Distribution Functions**

| | |
|---|---|
| betastat | Beta mean and variance |
| binostat | Binomial mean and variance |
| chi2stat | Chi-square mean and variance |
| expstat | Exponential mean and variance |
| fstat | F mean and variance |
| gamstat | Gamma mean and variance |
| geostat | Geometric mean and variance |
| hygestat | Hypergeometric mean and variance |
| lognstat | Lognormal mean and variance |
| nbinstat | Negative binomial mean and variance |
| ncfstat | Noncentral F mean and variance |
| nctstat | Noncentral t mean and variance |
| ncx2stat | Noncentral Chi-square mean and variance |
| normstat | Normal (Gaussian) mean and variance |
| poisstat | Poisson mean and variance |
| raylstat | Rayleigh mean and variance |
| tstat | Student's t mean and variance |
| unidstat | Discrete uniform mean and variance |
| unifstat | Continuous uniform mean and variance |
| weibstat | Weibull mean and variance |

| Descriptive Statistics | |
|---|---|
| corrcoef | Correlation coefficients (in MATLAB) |
| cov | Covariance matrix (in MATLAB) |
| geomean | Geometric mean |
| harmmean | Harmonic mean |
| iqr | Interquartile range |
| kurtosis | Sample kurtosis |
| mad | Mean absolute deviation |
| mean | Arithmetic average (in MATLAB) |
| median | 50th percentile (in MATLAB) |
| moment | Central moments of all orders |
| nanmax | Maximum ignoring missing data |
| nanmean | Average ignoring missing data |
| nanmedian | Median ignoring missing data |
| nanmin | Minimum ignoring missing data |
| nanstd | Standard deviation ignoring missing data |
| nansum | Sum ignoring missing data |
| prctile | Empirical percentiles of a sample |
| range | Sample range |
| skewness | Sample skewness |
| std | Standard deviation (in MATLAB) |
| trimmean | Trimmed mean |
| var | Variance |

**Statistical Plotting**

| | |
|---|---|
| boxplot | Box plots |
| errorbar | Error bar plot |
| fsurfht | Interactive contour plot of a function |
| gline | Interactive line drawing |
| gname | Interactive point labeling |
| lsline | Add least-squares fit line to plotted data |
| normplot | Normal probability plots |
| pareto | Pareto charts |
| qqplot | Quantile-Quantile plots |
| rcoplot | Regression case order plot |
| refcurve | Reference polynomial |
| refline | Reference line |
| surfht | Interactive interpolating contour plot |
| weibplot | Weibull plotting |

**Statistical Process Control**

| | |
|---|---|
| capable | Quality capability indices |
| capaplot | Plot of process capability |
| ewmaplot | Exponentially weighted moving average plot |
| histfit | Histogram and normal density curve |
| normspec | Plot normal density between limits |

**Statistical Process Control (Continued)**

| | |
|---|---|
| schart | Time plot of standard deviation |
| xbarplot | Time plot of means |

**Cluster Analysis**

| | |
|---|---|
| cluster | Create clusters from linkage output |
| clusterdata | Create clusters from a dataset |
| cophenet | Calculate the cophenetic correlation coefficient |
| dendrogram | Plot a hierarchical tree in a dendrogram graph |
| inconsistent | Calculate the inconsistency values of objects in a cluster hierarchy tree |
| linkage | Link objects in a dataset into a hierarchical tree of binary clusters |
| pdist | Calculate the pairwise distance between objects in a dataset |
| squareform | Reformat output of pdist function from vector to square matrix |
| zscore | Normalize a dataset before calculating the distance |

**Linear Models**

| | |
|---|---|
| anova1 | One-way Analysis of Variance (ANOVA) |
| anova2 | Two-way Analysis of Variance |
| lscov | Regression given a covariance matrix (in MATLAB) |

**Linear Models (Continued)**

| | |
|---|---|
| polyconf | Polynomial prediction with confidence intervals |
| polyfit | Polynomial fitting (in MATLAB) |
| polyval | Polynomial prediction (in MATLAB) |
| regress | Multiple linear regression |
| ridge | Ridge regression |
| rstool | Response surface tool |
| stepwise | Stepwise regression GUI |

**Nonlinear Regression**

| | |
|---|---|
| nlinfit | Nonlinear least-squares fitting |
| nlintool | Prediction graph for nonlinear fits |
| nlparci | Confidence intervals on parameters |
| nlpredci | Confidence intervals for prediction |
| nnls | Nonnegative least squares (in MATLAB) |

**Design of Experiments**

| | |
|---|---|
| cordexch | D-optimal design using coordinate exchange |
| daugment | D-optimal augmentation of designs |
| dcovary | D-optimal design with fixed covariates |
| ff2n | Two-level full factorial designs |
| fullfact | Mixed level full factorial designs |

| Design of Experiments (Continued) | |
| --- | --- |
| hadamard | Hadamard designs (in MATLAB) |
| rowexch | D-optimal design using row exchange |

| Principal Components Analysis | |
| --- | --- |
| barttest | Bartlett's test |
| pcacov | PCA from covariance matrix |
| pcares | Residuals from PCA |
| princomp | PCA from raw data matrix |

| Hypothesis Tests | |
| --- | --- |
| ranksum | Wilcoxon rank sum test |
| signrank | Wilcoxon signed rank test |
| signtest | Sign test for paired samples |
| ttest | One sample t-test |
| ttest2 | Two sample t-test |
| ztest | Z-test |

| File I/O | |
| --- | --- |
| caseread | Read casenames from a file |
| casewrite | Write casenames from a string matrix to a file |

**File I/O (Continued)**

| | |
|---|---|
| tblread | Retrieve tabular data from the file system |
| tblwrite | Write data in tabular form to the file system |

**Demonstrations**

| | |
|---|---|
| disttool | Interactive exploration of distribution functions |
| randtool | Interactive random number generation |
| polytool | Interactive fitting of polynomial models |
| rsmdemo | Interactive process experimentation and analysis |

**Data**

| | |
|---|---|
| census.mat | U. S. Population 1790 to 1980 |
| cities.mat | Names of U.S. metropolitan areas |
| discrim.mat | Classification data |
| gas.mat | Gasoline prices |
| hald.mat | Hald data |
| hogg.mat | Bacteria counts from milk shipments |
| lawdata.mat | GPA versus LSAT for 15 law schools |
| mileage.mat | Mileage data for three car models from two factories |
| moore.mat | Five factor – one response regression data |
| parts.mat | Dimensional runout on 36 circular parts |
| popcorn.mat | Data for popcorn example (anova2, friedman) |

| Data (Continued) | |
| --- | --- |
| polydata.mat | Data for polytool demo |
| reaction.mat | Reaction kinetics data |
| sat.dat | ASCII data for tblread example |

**Purpose**    One-way Analysis of Variance (ANOVA).

**Syntax**     p = anova1(X)
               p = anova1(X, group)
               p = anova1(X, group, '*displayopt*')
               [p, table] = anova1(...)
               [p, table, stats] = anova1(...)

**Description**    p = anova1(X) performs a balanced one-way ANOVA for comparing the
               means of two or more columns of data in the *m*-by-*n* matrix X, where each
               column represents an independent sample containing *m* mutually independent
               observations. The function returns the p-value for the null hypothesis that all
               samples in X are drawn from the same population (or from different
               populations with the same mean).

               If the p-value is near zero, this casts doubt on the null hypothesis and suggests
               that at least one sample mean is significantly different than the other sample
               means. The choice of a critical p-value to determine whether the result is
               judged "statistically significant" is left to the researcher. It is common to
               declare a result significant if the p-value is less than 0.05 or 0.01.

               The anova1 function displays two figures. The first figure is the standard
               ANOVA table, which divides the variability of the data in X into two parts:

               • Variability due to the differences among the column means (variability
                 *between* groups)

               • Variability due to the differences between the data in each column and the
                 column mean (variability *within* groups)

               The ANOVA table has six columns:

               • The first shows the source of the variability.

               • The second shows the Sum of Squares (SS) due to each source.

               • The third shows the degrees of freedom (df) associated with each source.

               • The fourth shows the Mean Squares (MS) for each source, which is the ratio
                 SS/df.

               • The fifth shows the *F* statistic, which is the ratio of the MS's.

               • The sixth shows the p-value, which is derived from the cdf of *F*. As *F*
                 increases, the p-value decreases.

The second figure displays box plots of each column of X. Large differences in the center lines of the box plots correspond to large values of $F$ and correspondingly small p-values.

p = anova1(X, group) uses the values in group (a character array or cell array) as labels for the box plot of the samples in X, when X is a matrix. Each row of group contains the label for the data in the corresponding column of X, so group must have length equal to the number of columns in X.

When X is a vector, anova1 performs a one-way ANOVA on the samples contained in X, as indexed by input group (a vector, character array, or cell array). Each element in group identifies the group (i.e., sample) to which the corresponding element in vector X belongs, so group must have the same length as X. The labels contained in group are also used to annotate the box plot. The vector-input form of anova1 does not require equal numbers of observations in each sample, so it is appropriate for unbalanced data.

It is not necessary to label samples sequentially (1, 2, 3, ...). For example, if X contains measurements taken at three different temperatures, -27°, 65°, and 110°, you could use these numbers as the sample labels in group. If a row of group contains an empty cell or empty string, that row and the corresponding observation in X are disregarded. NaNs in either input are similarly ignored.

p = anova1(X, group, '*displayopt*') enables the ANOVA table and box plot displays when '*displayopt*' is 'on' (default) and suppresses the displays when '*displayopt*' is 'off'.

[p, table] = anova1(...) returns the ANOVA table (including column and row labels) in cell array table. (You can copy a text version of the ANOVA table to the clipboard by using the **Copy Text** item on the **Edit** menu.)

[p, table, stats] = anova1(...) returns a stats structure that you can use to perform a follow-up multiple comparison test. The anova1 test evaluates the hypothesis that the samples all have the same mean against the alternative that the means are not all the same. Sometimes it is preferable to perform a test to determine *which pairs* of means are significantly different, and which are not. You can use the multcompare function to perform such tests by supplying the stats structure as input.

### Assumptions

The ANOVA test makes the following assumptions about the data in X:

- All sample populations are normally distributed.
- All sample populations have equal variance.
- All observations are mutually independent.

The ANOVA test is known to be robust to modest violations of the first two assumptions.

**Examples**    **Example 1**

The five columns of X are the constants one through five plus a random normal disturbance with mean zero and standard deviation one.

```
X = meshgrid(1:5)

X =

    1    2    3    4    5
    1    2    3    4    5
    1    2    3    4    5
    1    2    3    4    5
    1    2    3    4    5

X = X + normrnd(0, 1, 5, 5)

X =

    2.1650    3.6961    1.5538    3.6400    4.9551
    1.6268    2.0591    2.2988    3.8644    4.2011
    1.0751    3.7971    4.2460    2.6507    4.2348
    1.3516    2.2641    2.3610    2.7296    5.8617
    0.3035    2.8717    3.5774    4.9846    4.9438

p = anova1(X)

p =

    5.9952e-005
```

```
                        ANOVA Table
Source      SS      df      MS          F      Prob>F
Columns     32.93   4       8.232       11.26  5.995e-005
Error       14.62   20      0.7312
Total       47.55   24
```
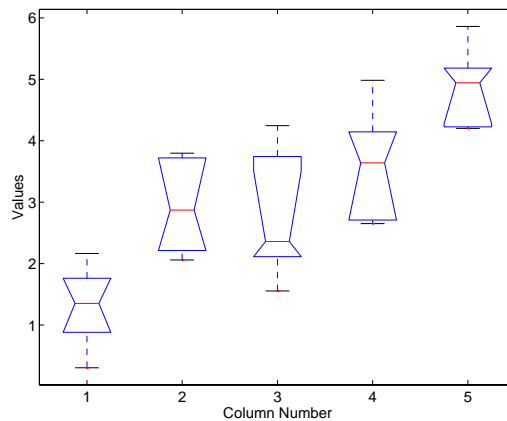


The very small p-value of 6e-5 indicates that differences between the column means are highly significant. The probability of this outcome under the null hypothesis (i.e., the probability that samples actually drawn from the same population would have means differing by the amounts seen in X) is less than 6 in 100,000. The test therefore strongly supports the alternate hypothesis, that one or more of the samples are drawn from populations with different means.

### Example 2

The following example comes from a study of the material strength of structural beams in Hogg (1987). The vector strength measures the deflection of a beam in thousandths of an inch under 3,000 pounds of force. Stronger beams deflect less. The civil engineer performing the study wanted to determine whether the strength of steel beams was equal to the strength of two more expensive alloys. Steel is coded 'st' in the vector alloy. The other materials are coded 'al1' and 'al2'.

```
strength = [82 86 79 83 84 85 86 87 74 82 78 75 76 77 79 ...
            79 77 78 82 79];

alloy = {'st','st','st','st','st','st','st','st',...
         'al1','al1','al1','al1','al1','al1',...
         'al2','al2','al2','al2','al2','al2'};
```

Though alloy is sorted in this example, you do not need to sort the grouping variable.

```
p = anova1(strength,alloy)

p =

   1.5264e-004
```
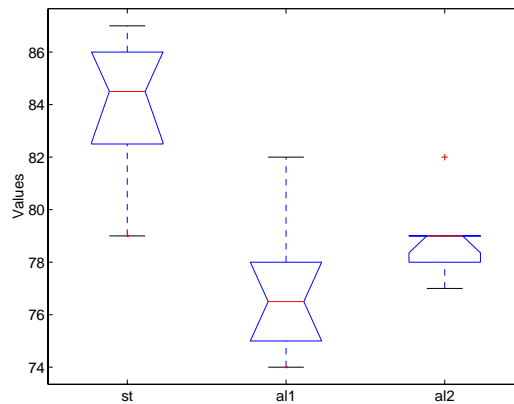




The p-value indicates that the three alloys are significantly different. The box plot confirms this graphically and shows that the steel beams deflect more than the more expensive alloys.

# anova1

**References**  Hogg, R. V., and J. Ledolter. *Engineering Statistics.* MacMillan Publishing Company, 1987.

**See Also**  anova2, anovan, boxplot, ttest

**Purpose**        Two-way Analysis of Variance (ANOVA).

**Syntax**         p = anova2(X, reps)
                   p = anova2(X, reps, '*displayopt*')
                   [p, table] = anova2(...)
                   [p, table, stats] = anova2(...)

**Description**    anova2(X, reps) performs a balanced two-way ANOVA for comparing the
                   means of two or more columns and two or more rows of the observations in X.
                   The data in different columns represent changes in factor A. The data in
                   different rows represent changes in factor B. If there is more than one
                   observation for each combination of factors, input reps indicates the number of
                   replicates in each "cell," which much be constant. (For unbalanced designs, use
                   anovan.)

                   The matrix below shows the format for a set-up where column factor A has two
                   levels, row factor B has three levels, and there are two replications (reps=2).
                   The subscripts indicate row, column, and replicate, respectively.

$$
\begin{array}{cc}
A=1 & A=2
\end{array}
$$

$$
\left.\begin{bmatrix}
x_{111} & x_{121} \\
x_{112} & x_{122}
\end{bmatrix}\right\} B=1
$$

$$
\left.\begin{bmatrix}
x_{211} & x_{221} \\
x_{212} & x_{222}
\end{bmatrix}\right\} B=2
$$

$$
\left.\begin{bmatrix}
x_{311} & x_{321} \\
x_{312} & x_{322}
\end{bmatrix}\right\} B=3
$$

                   When reps is 1 (default), anova2 returns two p-values in vector p:

                   **1**  The p-value for the null hypothesis, $H_{0A}$, that all samples from factor A
                        (i.e., all column-samples in X) are drawn from the same population

                   **2**  The p-value for the null hypothesis, $H_{0B}$, that all samples from factor B
                        (i.e., all row-samples in X) are drawn from the same population

When reps is greater than 1, anova2 returns a third p-value in vector p:

**3** The p-value for the null hypothesis, $H_{0AB}$, that the effects due to factors A and B are *additive* (i.e., that there is no interaction between factors A and B)

If any p-value is near zero, this casts doubt on the associated null hypothesis. A sufficiently small p-value for $H_{0A}$ suggests that at least one column-sample mean is significantly different that the other column-sample means; i.e., there is a main effect due to factor A. A sufficiently small p-value for $H_{0B}$ suggests that at least one row-sample mean is significantly different than the other row-sample means; i.e., there is a main effect due to factor B. A sufficiently small p-value for $H_{0AB}$ suggests that there is an interaction between factors A and B. The choice of a limit for the p-value to determine whether a result is "statistically significant" is left to the researcher. It is common to declare a result significant if the p-value is less than 0.05 or 0.01.

anova2 also displays a figure showing the standard ANOVA table, which divides the variability of the data in X into three or four parts depending on the value of reps:

- The variability due to the differences among the column means
- The variability due to the differences among the row means
- The variability due to the interaction between rows and columns (if reps is greater than its default value of one)
- The remaining variability not explained by any systematic source

The ANOVA table has five columns:

- The first shows the source of the variability.
- The second shows the Sum of Squares (SS) due to each source.
- The third shows the degrees of freedom (df) associated with each source.
- The fourth shows the Mean Squares (MS), which is the ratio SS/df.
- The fifth shows the F statistics, which is the ratio of the mean squares.

p = anova2(X, reps, '*displayopt*') enables the ANOVA table display when '*displayopt*' is 'on' (default) and suppresses the display when '*displayopt*' is 'off'.

[p, table] = anova2(...) returns the ANOVA table (including column and row labels) in cell array table. (You can copy a text version of the ANOVA table to the clipboard by using the **Copy Text** item on the **Edit** menu.)

[p, table, stats] = anova2(...) returns a stats structure that you can use to perform a follow-up multiple comparison test.

The anova2 test evaluates the hypothesis that the row, column, and interaction effects are all the same, against the alternative that they are not all the same. Sometimes it is preferable to perform a test to determine *which pairs* of effects are significantly different, and which are not. You can use the multcompare function to perform such tests by supplying the stats structure as input.

**Examples**

The data below come from a study of popcorn brands and popper type (Hogg 1987). The columns of the matrix popcorn are brands (Gourmet, National, and Generic). The rows are popper type (Oil and Air.) The study popped a batch of each brand three times with each popper. The values are the yield in cups of popped popcorn.

```
load popcorn

popcorn

popcorn =

    5.5000    4.5000    3.5000
    5.5000    4.5000    4.0000
    6.0000    4.0000    3.0000
    6.5000    5.0000    4.0000
    7.0000    5.5000    5.0000
    7.0000    5.0000    4.5000

p = anova2(popcorn, 3)

p =

    0.0000    0.0001    0.7462
```

```
                          ANOVA Table
         Source       SS      df     MS        F
         Columns     15.75     2    7.875     56.7
         Rows         4.5      1     4.5      32.4
         Interaction 0.08333   2    0.04167   0.3
         Error        1.667   12    0.1389
         Total          22    17
```

The vector p shows the p-values for the three brands of popcorn, 0. 0000, the two popper types, 0. 0001, and the interaction between brand and popper type, 0. 7462. These values indicate that both popcorn brand and popper type affect the yield of popcorn, but there is no evidence of a synergistic (interaction) effect of the two.

The conclusion is that you can get the greatest yield using the Gourmet brand and an Air popper (the three values popcorn(4: 6, 1)).

**Reference**      Hogg, R. V. and J. Ledolter. *Engineering Statistics.* MacMillan Publishing Company, 1987.

**See Also**       anova1, anovan

**Purpose**       N-way Analysis of Variance (ANOVA).

**Syntax**        p = anovan(X, group)
                  p = anovan(X, group, '*model*')
                  p = anovan(X, group, '*model*', sstype)
                  p = anovan(X, group, '*model*', sstype, gnames)
                  p = anovan(X, group, '*model*', sstype, gnames, '*displayopt*')
                  [p, table] = anovan(...)
                  [p, table, stats] = anovan(...)
                  [p, table, stats, terms] = anovan(...)

**Description**   p = anovan(X, group) performs a balanced or unbalanced multi-way ANOVA
                  for comparing the means of the observations in vector X with respect to N
                  different factors. The factors and factor levels of the observations in X are
                  assigned by the cell array group. Each of the N cells in group contains a list of
                  factor levels identifying the observations in X with respect to one of the N
                  factors. The list within each cell can be a vector, character array, or cell array
                  of strings, and must have the same number of elements as X.

As an example, consider the X and group inputs below.

```
X = [x1 x2 x3 x4 x5 x6 x7 x8];

group = {[1 2 1 2 1 2 1 2];...
         ['hi';'hi';'lo';'lo';'hi';'hi';'lo';'lo'];...
         {'may' 'may' 'may' 'may' 'june' 'june' 'june' 'june'}};
```

In this case, anovan(X, group) is a three-way ANOVA with two levels of each
factor. Every observation in X is identified by a combination of factor levels in
group. If the factors are A, B, and C, then observation x1 is associated with:

- Level 1 of factor A
- Level 'hi' of factor B
- Level 'may' of factor C

Similarly, observation x6 is associated with:

- Level 2 of factor A
- Level 'hi' of factor B
- Level 'june' of factor C

Output vector p contains p-values for the null hypotheses on the N main effects. Element p(1) contains the p-value for the null hypotheses, $H_{0A}$, that samples at all levels of factor A are drawn from the same population, element p(2) contains the p-value for the null hypotheses, $H_{0B}$, that samples at all levels of factor B are drawn from the same population, and so on.

If any p-value is near zero, this casts doubt on the associated null hypothesis. For example, a sufficiently small p-value for $H_{0A}$ suggests that at least one A-sample mean is significantly different that the other A-sample means; i.e., there is a main effect due to factor A. The choice of a limit for the p-value to determine whether a result is "statistically significant" is left to the researcher. It is common to declare a result significant if the p-value is less than 0.05 or 0.01.

anovan also displays a figure showing the standard ANOVA table, which by default divides the variability of the data in X into:

• The variability due to differences between the levels of each factor accounted for in the model (one row for each factor)
• The remaining variability not explained by any systematic source

The ANOVA table has six columns:

• The first shows the source of the variability.
• The second shows the Sum of Squares (SS) due to each source.
• The third shows the degrees of freedom (df) associated with each source.
• The fourth shows the Mean Squares (MS), which is the ratio SS/df.
• The fifth shows the F statistics, which is the ratio of the mean squares.
• The sixth shows the p-values for the F statistics.

p = anovan(X, group, '*model*') performs the ANOVA using the model specified by '*model*', where '*model*' can be 'linear', 'interaction', 'full', or an integer or vector. The default 'linear' model computes only the p-values for the null hypotheses on the N main effects. The 'interaction' model computes the p-values for null hypotheses on the N main effects and the $\binom{N}{2}$ two-factor interactions. The 'full' model computes the p-values for null hypotheses on the N main effects and interactions at all levels.

For an integer value of '*model*', k (k ≤ N), anovan computes all interaction levels through the kth level. The values k=1 and k=2 are equivalent to the 'linear' and 'interaction' specifications, respectively, while the value k=N is equivalent to the 'full' specification.

For more precise control over the main and interaction terms that anovan computes, '*model*' can specify a vector containing one element for each main or interaction term to include in the ANOVA model. Each vector element encodes the corresponding ANOVA term as the decimal equivalent of an N-bit number, where N is the number of factors. The table below illustrates the coding for a 3-factor ANOVA.

| 3-bit Code | Decimal Value | Corresponding ANOVA Terms |
|:----------:|:-------------:|---------------------------|
| [0 0 1] | 1 | Main term A |
| [0 1 0] | 2 | Main term B |
| [1 0 0] | 4 | Main term C |
| [0 1 1] | 3 | Interaction term AB |
| [1 1 0] | 6 | Interaction term BC |
| [1 0 1] | 5 | Interaction term AC |
| [1 1 1] | 7 | Interaction term ABC |

For example, if '*model*' is the vector [2 4 6], then output vector p contains the p-values for the null hypotheses on the main effects B and C and the interaction effect BC, in that order. A simple way to generate the '*model*' vector is to modify the terms output, which codes the terms in the current model using the format described above. If anovan returned [2 4 6] for terms, for example, and there was no significant result for interaction BC, you could recompute the ANOVA on just the main effects B and C by specifying [2 4] for '*model*'.

p = anovan(X, group, '*model*', sstype) computes the ANOVA using the type of sum-of-squares specified by sstype, which can be 1, 2, or 3 to designate Type 1, Type 2, or Type 3 sum-of-squares, respectively. The default is 3. The value of sstype only influences computations on unbalanced data.

The sum of squares for any term is determined by comparing two models. The Type 1 sum of squares for a term is the reduction in residual sum of squares obtained by adding that term to a fit that already includes the terms listed before it. The Type 2 sum of squares is the reduction in residual sum of squares obtained by adding that term to a model consisting of all other terms that do not contain the term in question. The Type 3 sum of squares is the reduction in residual sum of squares obtained by adding that term to a model containing all other terms, but with their effects constrained to obey the usual "sigma restrictions" that make models estimable.

Suppose we are fitting a model with two factors and their interaction, and that the terms appear in the order A, B, AB. Let R(·) represent the residual sum of squares for a model, so for example R(A,B,AB) is the residual sum of squares fitting the whole model, R(A) is the residual sum of squares fitting just the main effect of A, and R(1) is the residual sum of squares fitting just the mean. The three types of sums of squares are as follows:

| Term | Type 1 SS | Type 2 SS | Type 3 SS |
|------|-----------|-----------|-----------|
| A    | R(1)-R(A) | R(B)-R(A,B) | R(B,AB)-R(A,B,AB) |
| B    | R(A)-R(A,B) | R(A)-R(A,B) | R(A,AB)-R(A,B,AB) |
| AB   | R(A,B)-R(A,B,AB) | R(A,B)-R(A,B,AB) | R(A,B)-R(A,B,AB) |

The models for Type 3 sum of squares have sigma restrictions imposed. This means, for example, that in fitting R(B,AB), the array of AB effects is constrained to sum to 0 over A for each value of B, and over B for each value of A.

p = anovan(X, group, '*model*', sstype, gnames) uses the string values in character array gnames to label the N experimental factors in the ANOVA table. The array can be a string matrix with one row per observation, or a cell array of strings with one element per observation. When gnames is not specified, the default labels 'X1', 'X2', 'X3', ..., 'XN' are used.

p = anovan(X, group, '*model*', sstype, gnames, '*displayopt*') enables the ANOVA table display when '*displayopt*' is 'on' (default) and suppresses the display when '*displayopt*' is 'off'.

[p, table] = anovan(...) returns the ANOVA table (including factor labels) in cell array table. (You can copy a text version of the ANOVA table to the clipboard by using the **Copy Text** item on the **Edit** menu.)

[p, table, stats] = anovan(...) returns a stats structure that you can use to perform a follow-up multiple comparison test.

The anovan test evaluates the hypothesis that the different levels of a factor (or more generally, a term) have the same effect, against the alternative that they do not all have the same effect. Sometimes it is preferable to perform a test to determine *which pairs* of levels are significantly different, and which are not. You can use the multcompare function to perform such tests by supplying the stats structure as input.

[p, table, stats, terms] = anovan(...) returns the main and interaction terms used in the ANOVA computations. The terms are encoded in output vector terms using the same format described above for input '*model*'. When '*model*' itself is specified in this vector format, the vector returned in terms is identical.

**Examples**        In the previous section we used anova2 to analyze the effects of two factors on a response in a balanced design. For a design that is not balanced, we can use anovan instead.
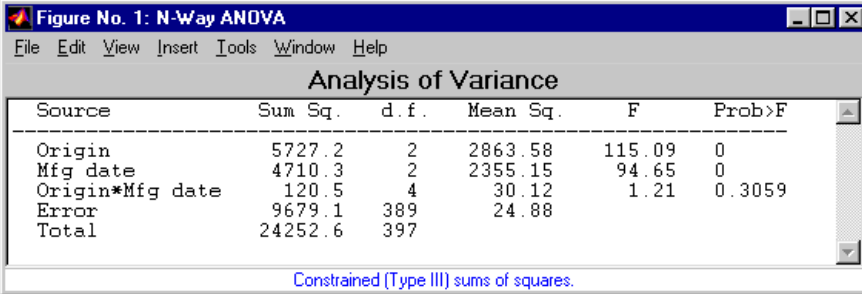
The dataset carbig contains a number of measurements on 406 cars. Let's study how the mileage depends on where and when the cars were made.

```
load carbig
anovan(MPG, {org when}, 2, 3, {'Origin';'Mfg date'})

ans =
          0
          0
     0.30587
```

The p-value for the interaction term is not small, indicating little evidence that the effect of the car's year or manufacture (when) depends on where the car was made (org). The linear effects of those two factors, though, are significant.

```
┌──────────────────────────────────────────────────────────────────┐
│ ◆ Figure No. 1: N-Way ANOVA                              _ □ ×    │
├──────────────────────────────────────────────────────────────────┤
│ File  Edit  View  Insert  Tools  Window  Help                     │
│                    Analysis of Variance                           │
│ ┌────────────────────────────────────────────────────────────┐ ▲ │
│ │ Source          Sum Sq.   d.f.   Mean Sq.     F     Prob>F  │ │ │
│ │ ──────────────────────────────────────────────────────────  │ │ │
│ │ Origin          5727.2      2    2863.58   115.09   0        │ │ │
│ │ Mfg date        4710.3      2    2355.15    94.65   0        │ │ │
│ │ Origin*Mfg date  120.5      4      30.12     1.21   0.3059   │ │ │
│ │ Error           9679.1    389      24.88                     │ │ │
│ │ Total          24252.6    397                               │ │ │
│ │                                                            │ ▼ │
│ └────────────────────────────────────────────────────────────┘   │
│              Constrained (Type III) sums of squares.              │
└──────────────────────────────────────────────────────────────────┘
```

**Reference**    Hogg, R. V. and J. Ledolter. *Engineering Statistics.* MacMillan Publishing Company, 1987.

**See Also**    anova1, anova2, multcompare

**Purpose**        Interactive plot for fitting and predicting analysis of covariance models.

**Syntax**         aoctool(x, y, g)
                   aoctool(x, y, g, alpha)
                   aoctool(x, y, g, alpha, xname, yname, gname)
                   aoctool(x, y, g, alpha, xname, yname, gname, '*displayopt*')
                   aoctool(x, y, g, alpha, xname, yname, gname, '*displayopt*', '*model*')
                   h = aoctool(...)
                   [h, atab, ctab] = aoctool(...)
                   [h, atab, ctab, stats] = aoctool(...)

**Description**    aoctool(x, y, g) fits a separate line to the column vectors, x and y, for each
                   group defined by the values in the array g. These types of models are known as
                   one-way analysis of covariance (ANOCOVA) models. The output consists of
                   three figures:

                   • An interactive graph of the data and prediction curves
                   • An ANOVA table
                   • A table of parameter estimates

                   You can use the figures to change models and to test different parts of the
                   model. More information about interactive use of the aoctool function appears
                   on "The aoctool Demo" on page 1-161.

                   aoctool(x, y, g, alpha) determines the confidence levels of the prediction
                   intervals. The confidence level is 100*(1-alpha)%. The default value of alpha
                   is 0.05.

                   aoctool(x, y, g, alpha, xname, yname, gname) specifies the name to use for the
                   x, y, and g variables in the graph and tables. If you enter simple variable names
                   for the x, y, and g arguments, the aoctool function uses those names. If you
                   enter an expression for one of these arguments, you can specify a name to use
                   in place of that expression by supplying these arguments. For example, if you
                   enter m(:, 2) as the x argument, you might choose to enter 'Col 2' as the
                   xname argument.

                   aoctool(x, y, g, alpha, xname, yname, gname, '*displayopt*') enables the
                   graph and table displays when '*displayopt*' is 'on' (default) and suppresses
                   those displays when '*displayopt*' is 'off'.

aoctool(x, y, g, alpha, xname, yname, gname, '*displayopt*', '*model*') specifies the initial model to fit. The value of '*model*' can be any of the following:

- 'same mean' – fit a single mean, ignoring grouping
- 'separate means' – fit a separate mean to each group
- 'same line' – fit a single line, ignoring grouping
- 'parallel lines' – fit a separate line to each group, but constrain the lines to be parallel
- 'separate lines' – fit a separate line to each group, with no constraints

h = aoctool(...) returns a vector of handles to the line objects in the plot.

[h, atab, ctab] = aoctool(...) returns cell arrays containing the entries in ANOVA table (atab) and the table of coefficient estimates (ctab). (You can copy a text version of either table to the clipboard by using the **Copy Text** item on the **Edit** menu.)

[h, atab, ctab, stats] = aoctool(...) returns a stats structure that you can use to perform a follow-up multiple comparison test. The ANOVA table output includes tests of the hypotheses that the slopes or intercepts are all the same, against a general alternative that they are not all the same. Sometimes it is preferable to perform a test to determine which pairs of values are significantly different, and which are not. You can use the multcompare function to perform such tests by supplying the stats structure as input. You can test either the slopes, the intercepts, or population marginal means (the heights of the curves at the mean x value).

**Example**    This example illustrates how to fit different models non-interactively. First, we load the smaller car dataset and fit a separate-slopes model, then examine the coefficient estimates.

```
[h, a, c, s] = aoctool(Weight, MPG, Model_Year, 0.05, ...
                        '','','','off','separate lines');
c(:, 1:2)
```

```
ans =
    'Term'          'Estimate'
    'Intercept'     [45.97983716833132]
    '    70'        [-8.58050531454973]
    '    76'        [-3.89017396094922]
    '    82'        [12.47067927549897]
    'Slope'         [-0.00780212907455]
    '    70'        [ 0.00195840368824]
    '    76'        [ 0.00113831038418]
    '    82'        [-0.00309671407243]
```

Roughly speaking, the lines relating MPG to Weight have an intercept close to 45.98 and a slope close to -0.0078. Each group's coefficients are offset from these values somewhat. For instance, the intercept for the cars made in 1970 is 45.98-8.58 = 37.40.

Next, we try a fit using parallel lines. (If we had examined the ANOVA table, we would have found that the parallel-lines fit is significantly worse than the separate-lines fit.)

```
[h, a, c, s] = aoctool(Weight, MPG, Model_Year, 0.05, ...
                       '','','','off','parallel lines');
c(:, 1:2)

ans =

    'Term'          'Estimate'
    'Intercept'     [43.38984085130596]
    '    70'        [-3.27948192983761]
    '    76'        [-1.35036234809006]
    '    82'        [ 4.62984427792768]
    'Slope'         [-0.00664751826198]
```

Here we again have separate intercepts for each group, but this time the slopes are constrained to be the same.

**See Also**     anova1, multcompare, polytool

# barttest

| | |
|---|---|
| **Purpose** | Bartlett's test for dimensionality. |

**Syntax**

ndim = barttest(x, alpha)
[ndim, prob, chisquare] = barttest(x, alpha)

**Description**

ndim = barttest(x, alpha) returns the number of dimensions necessary to explain the nonrandom variation in the data matrix x, using the significance probability alpha. The dimension is determined by a series of hypothesis tests. The test for ndim=1 tests the hypothesis that the variances of the data values along each principal component are equal, the test for ndim=2 tests the hypothesis that the variances along the second through last components are equal, and so on.

[ndim, prob, chisquare] = barttest(x, alpha) returns the number of dimensions, the significance values for the hypothesis tests, and the $\chi^2$ values associated with the tests.

**Example**

```
x = mvnrnd([0 0], [1 0.99; 0.99 1], 20);
x(:, 3:4) = mvnrnd([0 0], [1 0.99; 0.99 1], 20);
x(:, 5:6) = mvnrnd([0 0], [1 0.99; 0.99 1], 20);
[ndim, prob] = barttest(x, 0.05)

ndim =

     3

prob =
          0
          0
          0
     0.5081
     0.6618
```

**See Also**    princomp, pcacov, pcares

2-36

**Purpose**        Beta cumulative distribution function (cdf).

**Syntax**         p = betacdf(X, A, B)

**Description**    p = betacdf(X, A, B) computes the beta cdf at each of the values in X using the corresponding parameters in A and B. Vector or matrix inputs for X, A, and B must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in A and B must all be positive, and the values in X must lie on the interval [0 1].

The beta cdf for a given value x and given pair of parameters a and b is

$$p = F(x|a, b) = \frac{1}{B(a, b)} \int_0^x t^{a-1} (1-t)^{b-1} dt$$

where $B(\cdot)$ is the Beta function. The result, p, is the probability that a single observation from a beta distribution with parameters a and b will fall in the interval [0 x].

**Examples**
```
x = 0.1:0.2:0.9;
a = 2;
b = 2;
p = betacdf(x, a, b)

p =

    0.0280    0.2160    0.5000    0.7840    0.9720

a = [1 2 3];
p = betacdf(0.5, a, a)

p =

    0.5000    0.5000    0.5000
```

**See Also**      betafit, betainv, betalike, betapdf, betarnd, betastat, cdf

# betafit

**Purpose**        Parameter estimates and confidence intervals for beta distributed data.

**Syntax**         phat = betafit(x)
                   [phat, pci] = betafit(x, alpha)

**Description**    phat = betafit(x) computes the maximum likelihood estimates of the beta
                   distribution parameters $a$ and $b$ from the data in vector x, where the beta cdf
                   is given by

$$F(x|a, b) = \frac{1}{B(a, b)} \int_0^x t^{a-1}(1-t)^{b-1} dt$$

and $B(\cdot)$ is the Beta function. The elements of x must lie in the interval $(0\ 1)$.

[phat, pci] = betafit(x, alpha) returns confidence intervals on the $a$ and $b$
parameters in the 2-by-2 matrix pci. The first column of the matrix contains
the lower and upper confidence bounds for parameter $a$, and the second column
contains the confidence bounds for parameter $b$. The optional input argument
alpha is a value in the range $[0\ 1]$ specifying the width of the confidence
intervals. By default, alpha is 0.05, which corresponds to 95% confidence
intervals.

**Example**        This example generates 100 beta distributed observations. The true $a$ and $b$
                   parameters are 4 and 3, respectively. Compare these to the values returned
                   in p. Note that the columns of ci both bracket the true parameters.

```
r = betarnd(4, 3, 100, 1);
[p, ci] = betafit(r, 0.01)

p =

    3.9010     2.6193

ci =

    2.5244     1.7488
    5.2776     3.4898
```

**Reference**    Hahn, Gerald J., & Shapiro, Samuel, S. *Statistical Models in Engineering.* John Wiley & Sons, New York. 1994. p. 95.

**See Also**    betalike, mle

# betainv

**Purpose**       Inverse of the beta cumulative distribution function.

**Syntax**        X = betainv(P, A, B)

**Description**   X = betainv(P, A, B) computes the inverse of the beta cdf with parameters specified by A and B for the corresponding probabilities in P. Vector or matrix inputs for P, A, and B must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in A and B must all be positive, and the values in P must lie on the interval [0 1].

The inverse beta cdf for a given probability $p$ and a given pair of parameters $a$ and $b$ is

$$x = F^{-1}(p|a, b) = \{x:F(x|a, b) = p\}$$

where

$$p = F(x|a, b) = \frac{1}{B(a, b)} \int_0^x t^{a-1}(1-t)^{b-1} dt$$

and $B(\cdot)$ is the Beta function. Each element of output X is the value whose cumulative probability under the beta cdf defined by the corresponding parameters in A and B is specified by the corresponding value in P.

**Algorithm**    The betainv function uses Newton's method with modifications to constrain steps to the allowable range for $x$, i.e., [0 1].

**Examples**
```
p = [0.01 0.5 0.99];
x = betainv(p, 10, 5)

x =

    0.3726    0.6742    0.8981
```

According to this result, for a beta cdf with $a$=10 and $b$=5, a value less than or equal to 0.3726 occurs with probability 0.01. Similarly, values less than or equal to 0.6742 and 0.8981 occur with respective probabilities 0.5 and 0.99.

**See Also**     betafit, icdf

**Purpose**        Negative beta log-likelihood function.

**Syntax**         logL = betalike(params, data)
                   [logL, avar] = betalike(params, data)

**Description**    logL = betalike(params, data) returns the negative of the beta
                   log-likelihood function for the beta parameters *a* and *b* specified in vector
                   params and the observations specified in column vector data. The length of
                   logL is the length of data.

                   [logL, avar] = betalike(params, data) also returns avar, which is the
                   asymptotic variance-covariance matrix of the parameter estimates if the
                   values in params are the maximum likelihood estimates. avar is the inverse of
                   Fisher's information matrix. The diagonal elements of avar are the asymptotic
                   variances of their respective parameters.

                   betalike is a utility function for maximum likelihood estimation of the beta
                   distribution. The likelihood assumes that all the elements in the data sample
                   are mutually independent. Since betalike returns the negative beta
                   log-likelihood function, minimizing betalike using fminsearch is the same as
                   maximizing the likelihood.

**Example**        This example continues the betafit example where we calculated estimates of
                   the beta parameters for some randomly generated beta distributed data.

```
r = betarnd(4, 3, 100, 1);
[logl, avar] = betalike([3.9010 2.6193], r)

logl =

  -33.0514

avar =

    0.2856    0.1528
    0.1528    0.1142
```

**See Also**       betafit, fminsearch, gamlike, mle, weiblike

# betapdf

**Purpose**        Beta probability density function (pdf).

**Syntax**        Y = betapdf(X, A, B)

**Description**        Y = betapdf(X, A, B) computes the beta pdf at each of the values in X using the corresponding parameters in A and B. Vector or matrix inputs for X, A, and B must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions of the other inputs. The parameters in A and B must all be positive, and the values in X must lie on the interval [0 1].

The beta probability density function for a given value $x$ and given pair of parameters $a$ and $b$ is

$$y = f(x|a, b) = \frac{1}{B(a, b)} x^{a-1} (1-x)^{b-1} I_{(0, 1)}(x)$$

where $B(\cdot)$ is the Beta function. The result, $y$, is the probability that a single observation from a beta distribution with parameters $a$ and $b$ will have value $x$. The indicator function $I_{(0,1)}(x)$ ensures that only values of $x$ in the range (0 1) have nonzero probability. The uniform distribution on (0 1) is a degenerate case of the beta pdf where $a = 1$ and $b = 1$.

A *likelihood function* is the pdf viewed as a function of the parameters. Maximum likelihood estimators (MLEs) are the values of the parameters that maximize the likelihood function for a fixed value of $x$.

**Examples**
```
a = [0.5 1; 2 4]

a =

    0.5000    1.0000
    2.0000    4.0000

y = betapdf(0.5, a, a)

y =
    0.6366    1.0000
    1.5000    2.1875
```

**See Also**        betacdf, betafit, betainv, betalike, betarnd, betastat, pdf

**Purpose**     Random numbers from the beta distribution.

**Syntax**      R = betarnd(A, B)
                R = betarnd(A, B, m)
                R = betarnd(A, B, m, n)

**Description**  R = betarnd(A, B) generates random numbers from the beta distribution with
                parameters specified by A and B. Vector or matrix inputs for A and B must have
                the same size, which is also the size of R. A scalar input for A or B is expanded
                to a constant matrix with the same dimensions as the other input.

                R = betarnd(A, B, m) generates a matrix of size m containing random numbers
                from the beta distribution with parameters A and B, where m is a 1-by-2 vector
                containing the row and column dimensions of R.

                R = betarnd(A, B, m, n) generates an m-by-n matrix containing random
                numbers from the beta distribution with parameters A and B.

**Examples**        a = [1 1; 2 2];
                    b = [1 2; 1 2];

                    r = betarnd(a, b)

                    r =
                        0.6987      0.6139
                        0.9102      0.8067

                    r = betarnd(10, 10, [1 5])

                    r =
                        0.5974      0.4777      0.5538      0.5465      0.6327

                    r = betarnd(4, 2, 2, 3)

                    r =
                        0.3943      0.6101      0.5768
                        0.5990      0.2760      0.5474

**See Also**    betacdf, betafit, betainv, betalike, betapdf, betastat, rand, randtool

# betastat

| | |
|---|---|
| **Purpose** | Mean and variance for the beta distribution. |
| **Syntax** | [M, V] = betastat(A, B) |

**Description**    [M, V] = betastat(A, B) returns the mean and variance for the beta distribution with parameters specified by A and B. Vector or matrix inputs for A and B must have the same size, which is also the size of M and V. A scalar input for A or B is expanded to a constant matrix with the same dimensions as the other input.

The mean of the beta distribution with parameters $a$ and $b$ is $a/(a + b)$ and the variance is

$$\frac{ab}{(a + b + 1)(a + b)^2}$$

**Examples**    If parameters $a$ and $b$ are equal, the mean is 1/2.

```
a = 1:6;
[m, v] = betastat(a, a)

m =
    0.5000    0.5000    0.5000    0.5000    0.5000    0.5000

v =
    0.0833    0.0500    0.0357    0.0278    0.0227    0.0192
```

**See Also**    betacdf, betafit, betainv, betalike, betapdf, betarnd

**Purpose**          Binomial cumulative distribution function (cdf).

**Syntax**           Y = binocdf(X, N, P)

**Description**      binocdf(X, N, P) computes a binomial cdf at each of the values in X using the corresponding parameters in N and P. Vector or matrix inputs for X, N, and P must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions of the other inputs. The values in N must all be positive integers, and the values in X and P must lie on the interval [0 1].

The binomial cdf for a given value x and given pair of parameters n and p is

$$y = F(x|n, p) = \sum_{i=0}^{x} \binom{n}{i} p^i q^{(1-i)} I_{(0, 1, \dots, n)}(i)$$

The result, y, is the probability of observing up to x successes in n independent trials, where the probability of success in any given trial is p. The indicator function $I_{(0, 1, \dots, n)}(i)$ ensures that x only adopts values of 0, 1, ..., n.

**Examples**        If a baseball team plays 162 games in a season and has a 50-50 chance of winning any game, then the probability of that team winning more than 100 games in a season is:

    1 - binocdf(100, 162, 0.5)

The result is 0.001 (i.e., 1-0.999). If a team wins 100 or more games in a season, this result suggests that it is likely that the team's true probability of winning any game is greater than 0.5.

**See Also**        binofit, binoinv, binopdf, binornd, binostat, cdf

# binofit

**Purpose**    Parameter estimates and confidence intervals for binomial data.

**Syntax**    phat = binofit(x, n)
[phat, pci] = binofit(x, n)
[phat, pci] = binofit(x, n, alpha)

**Description**    phat = binofit(x, n) returns a maximum likelihood estimate of the
probability of success in a *given* binomial trial based on the number of
successes, x, observed in n independent trials. A scalar value for x or n is
expanded to the same size as the other input.

[phat, pci] = binofit(x, n) returns the probability estimate, phat, and the
95% confidence intervals, pci.

[phat, pci] = binofit(x, n, alpha) returns the 100(1-alpha)% confidence
intervals. For example, alpha = 0.01 yields 99% confidence intervals.

**Example**    First we generate a binomial sample of 100 elements, where the probability of
success in a given trial is 0.6. Then, we estimate this probability from the
outcomes in the sample.

    r = binornd(100, 0.6);
    [phat, pci] = binofit(r, 100)

    phat =

        0.5800

    pci =

        0.4771      0.6780

The 95% confidence interval, pci, contains the true value, 0.6.

**Reference**    Johnson, N. L., S. Kotz, and A.W. Kemp, "*Univariate Discrete Distributions,
Second Edition,*" Wiley 1992. pp. 124–130.

**See Also**    binocdf, binoinv, binopdf, binornd, binostat, mle

**Purpose**       Inverse of the binomial cumulative distribution function (cdf).

**Syntax**        X = binoinv(Y, N, P)

**Description**   X = binoinv(Y, N, P) returns the smallest integer X such that the binomial cdf
                  evaluated at X is equal to or exceeds Y. You can think of Y as the probability of
                  observing X successes in N independent trials where P is the probability of
                  success in each trial. Each X is a positive integer less than or equal to N.

                  Vector or matrix inputs for Y, N, and P must all have the same size. A scalar
                  input is expanded to a constant matrix with the same dimensions as the other
                  inputs. The parameters in N must be positive integers, and the values in both
                  P and Y must lie on the interval [0 1].

**Examples**      If a baseball team has a 50-50 chance of winning any game, what is a
                  reasonable range of games this team might win over a season of 162 games? We
                  assume that a surprising result is one that occurs by chance once in a decade.

                      binoinv([0.05 0.95], 162, 0.5)

                      ans =

                          71      91

                  This result means that in 90% of baseball seasons, a .500 team should win
                  between 71 and 91 games.

**See Also**      binocdf, binofit, binopdf, binornd, binostat, icdf

# binopdf

**Purpose**      Binomial probability density function (pdf).

**Syntax**       Y = binopdf(X, N, P)

**Description**  Y = binopdf(X, N, P) computes the binomial pdf at each of the values in X
using the corresponding parameters in N and P. Vector or matrix inputs for X,
N, and P must all have the same size. A scalar input is expanded to a constant
matrix with the same dimensions of the other inputs.

The parameters in N must be positive integers, and the values in P must lie on
the interval [0 1].

The binomial probability density function for a given value $x$ and given pair of
parameters $n$ and $p$ is

$$y = f(x|n, p) = \binom{n}{x} p^x q^{(1-x)} I_{(0, 1, ..., n)}(x)$$

where $q = 1-p$. The result, $y$, is the probability of observing $x$ successes in $n$
independent trials, where the probability of success in any *given* trial is $p$. The
indicator function $I_{(0,1,...,n)}(x)$ ensures that $x$ only adopts values of 0, 1, ..., $n$.

**Examples**     A Quality Assurance inspector tests 200 circuit boards a day. If 2% of the
boards have defects, what is the probability that the inspector will find no
defective boards on any given day?

```
binopdf(0, 200, 0.02)
ans =

    0.0176
```

What is the most likely number of defective boards the inspector will find?

```
y = binopdf([0:200], 200, 0.02);
[x, i] = max(y);

i
i =
     5
```

**See Also**     binocdf, binofit, binoinv, binornd, binostat, pdf

**Purpose**        Random numbers from the binomial distribution.

**Syntax**         R = binornd(N, P)
                   R = binornd(N, P, mm)
                   R = binornd(N, P, mm, nn)

**Description**    R = binornd(N, P) generates random numbers from the binomial distribution
                   with parameters specified by N and P. Vector or matrix inputs for N and P must
                   have the same size, which is also the size of R. A scalar input for N or P is
                   expanded to a constant matrix with the same dimensions as the other input.

                   R = binornd(N, P, mm) generates a matrix of size mm containing random
                   numbers from the binomial distribution with parameters N and P, where mm is
                   a 1-by-2 vector containing the row and column dimensions of R.

                   R = binornd(N, p, mm, nn) generates an mm-by-nn matrix containing random
                   numbers from the binomial distribution with parameters N and P.

**Algorithm**      The binornd function uses the direct method using the definition of the
                   binomial distribution as a sum of Bernoulli random variables.

**Examples**       n = 10:10:60;

                   r1 = binornd(n, 1./n)
                   r1 =
                        2      1      0      1      1      2

                   r2 = binornd(n, 1./n, [1 6])
                   r2 =
                        0      1      2      1      3      1

                   r3 = binornd(n, 1./n, 1, 6)
                   r3 =
                        0      1      1      1      0      3

**See Also**       binocdf, binofit, binoinv, binopdf, binostat, rand, randtool

# binostat

| | |
|---|---|
| **Purpose** | Mean and variance for the binomial distribution. |
| **Syntax** | [M, V] = binostat(N, P) |
| **Description** | [M, V] = binostat(N, P) returns the mean and variance for the binomial distribution with parameters specified by N and P. Vector or matrix inputs for N and P must have the same size, which is also the size of M and V. A scalar input for N or P is expanded to a constant matrix with the same dimensions as the other input. |

The mean of the binomial distribution with parameters *n* and *p* is *np*. The variance is *npq*, where *q = 1-p*.

**Examples**

```
n = logspace(1, 5, 5)
n =
          10         100        1000       10000      100000

[m, v] = binostat(n, 1./n)

m =
     1     1     1     1     1

v =
     0.9000    0.9900    0.9990    0.9999    1.0000

[m, v] = binostat(n, 1/2)

m =
          5          50         500        5000       50000

v =

   1.0e+04 *
     0.0003    0.0025    0.0250    0.2500    2.5000
```

**See Also**    binocdf, binofit, binoinv, binopdf, binornd

**Purpose**      Bootstrap statistics through resampling of data.

**Syntax**      bootstat = bootstrp(nboot, 'bootfun', d1, d2, ...)
                [bootstat, bootsam] = bootstrp(...)

**Description**  bootstat = bootstrp(nboot, 'bootfun', d1, d2, ...) draws nboot bootstrap
                samples from each of the input data sets, d1, d2, etc., and passes the bootstrap
                samples to function bootfun for analysis. nboot must be a positive integer, and
                each input data set must contain the same number of rows, n. Each bootstrap
                sample contains n rows chosen randomly (with replacement) from the
                corresponding input data set (d1, d2, etc.).

                Each row of the output, bootstat, contains the results of applying bootfun to
                one set of bootstrap samples. If bootfun returns multiple outputs, only the first
                is stored in bootstat. If the first output from bootfun is a matrix, the matrix
                is reshaped to a row vector for storage in bootstat.

                [bootstat, bootsam] = bootstrp(...) returns a matrix of bootstrap
                indices, bootsam. Each of the nboot columns in bootsam contains indices of the
                values that were drawn from the original data sets to constitute the
                corresponding bootstrap sample. For example, if d1, d2, etc., each contain 16
                values, and nboot = 4, then bootsam is a 16-by-4 matrix. The first column
                contains the indices of the 16 values drawn from d1, d2, etc., for the first of the
                four bootstrap samples, the second column contains the indices for the second
                of the four bootstrap samples, and so on. (The bootstrap indices are the same
                for all input data sets.)

**Example**     Correlate the LSAT scores and law-school GPA for 15 students. These 15 data
                points are resampled to create 1000 different data sets, and the correlation
                between the two variables is computed for each dataset.

```
load lawdata
[bootstat, bootsam] = bootstrp(1000, 'corrcoef', lsat, gpa);
```

```
bootstat(1:5,:)

ans =

    1.0000    0.3021    0.3021    1.0000
    1.0000    0.6869    0.6869    1.0000
    1.0000    0.8346    0.8346    1.0000
    1.0000    0.8711    0.8711    1.0000
    1.0000    0.8043    0.8043    1.0000

bootsam(:,1:5)

ans =

     4     7     5    12     8
     1    11    10     8     4
    11     9    12     4     2
    11    14    15     5    15
    15    13     6     6     2
     6     8     4     3     8
     8     2    15     8     6
    13    10    11    14     5
     1     7    12    14    14
     1    11    10     1     8
     8    14     2    14     7
    11    12    10     8    15
     1     4    14     8     1
     6     1     5     5    12
     2    12     7    15    12

hist(bootstat(:,2))
```
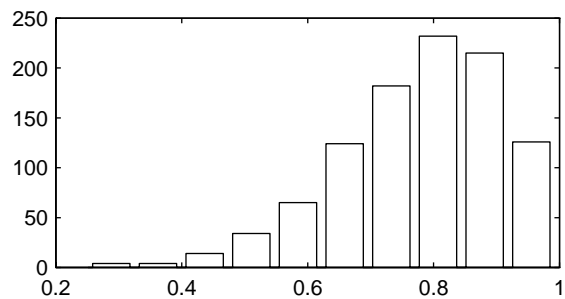
The histogram shows the variation of the correlation coefficient across all the bootstrap samples. The sample minimum is positive, indicating that the relationship between LSAT score and GPA is not accidental.

# boxplot

**Purpose**        Box plots of a data sample.

**Syntax**         boxplot(X)
                   boxplot(X, notch)
                   boxplot(X, notch, '*sym*')
                   boxplot(X, notch, '*sym*', vert)
                   boxplot(X, notch, '*sym*', vert, whis)

**Description**    boxplot(X) produces a box and whisker plot for each column of X. The box has lines at the lower quartile, median, and upper quartile values. The whiskers are lines extending from each end of the box to show the extent of the rest of the data. Outliers are data with values beyond the ends of the whiskers. If there is no data outside the whisker, a dot is placed at the bottom whisker.

boxplot(X, notch) with notch = 1 produces a notched-box plot. Notches graph a robust estimate of the uncertainty about the means for box-to-box comparison. The default, notch = 0, produces a rectangular box plot.

boxplot(X, notch, '*sym*') where *sym* is a plotting symbol, affords control of the symbol for outliers. The default is '+'. See MATLAB's LineSpec property for information about the available marker symbols.

boxplot(X, notch, '*sym*', vert) with vert = 0 creates horizontal boxes rather than the default vertical boxes (vert = 1).

boxplot(X, notch, '*sym*', vert, whis) enables you to specify the length of the "whiskers." whis defines the length of the whiskers as a function of the inter-quartile range (default = 1.5 ∗ IQR). If whis = 0, then boxplot displays all data values outside the box using the plotting symbol, '*sym*'.

**Examples**       x1 = normrnd(5, 1, 100, 1);
                   x2 = normrnd(6, 1, 100, 1);
                   x = [x1 x2];
                   boxplot(x, 1)
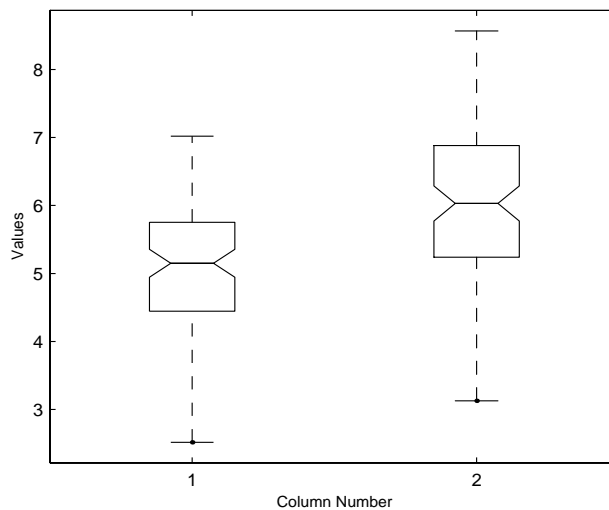
The difference between the means of the two columns of x is 1. We can detect this difference graphically by observing that the notches in the boxplot do not overlap.

**See Also**    anova1, kruskalwallis

# capable

**Purpose**        Process capability indices.

**Syntax**         p = capable(data, specs)
                   [p, Cp, Cpk] = capable(data, specs)

**Description**    p = capable(data, specs) computes the probability that a sample, data, from
                   some process falls outside the bounds specified in specs, a 2-element vector of
                   the form [lower upper].

                   The assumptions are that the measured values in the vector data are normally
                   distributed with constant mean and variance and that the measurements are
                   statistically independent.

                   [p, Cp, Cpk] = capable(data, specs) additionally returns the capability
                   indices Cp and Cpk.

                   $C_p$ is the ratio of the range of the specifications to six times the estimate of the
                   process standard deviation:

                   $$C_p = \frac{USL - LSL}{6\sigma}$$

                   For a process that has its average value on target, a $C_p$ of 1 translates to a little
                   more than one defect per thousand. Recently, many industries have set a
                   quality goal of one part per million. This would correspond to $C_p = 1.6$. The
                   higher the value of $C_p$, the more capable the process.

                   $C_{pk}$ is the ratio of difference between the process mean and the closer
                   specification limit to three times the estimate of the process standard
                   deviation:

                   $$C_{pk} = min\left(\frac{USL - \mu}{3\sigma}, \frac{\mu - LSL}{3\sigma}\right)$$

                   where the process mean is $\mu$. For processes that do not maintain their average
                   on target, $C_{pk}$ is a more descriptive index of process capability.

**Example**        Imagine a machined part with specifications requiring a dimension to be
                   within three thousandths of an inch of nominal. Suppose that the machining
                   process cuts too thick by one thousandth of an inch on average and also has a

standard deviation of one thousandth of an inch. What are the capability indices of this process?

```
data = normrnd(1, 1, 30, 1);
[p, Cp, Cpk] = capable(data, [-3 3]);

indices = [p Cp Cpk]
indices =

    0.0172    1.1144    0.7053
```

We expect 17 parts out of a thousand to be out-of-specification. Cpk is less than Cp because the process is not centered.

**Reference**     Montgomery, D., *"Introduction to Statistical Quality Control,"* John Wiley & Sons 1991. pp. 369–374.

**See Also**      capaplot, histfit

# capaplot

**Purpose**  Process capability plot.

**Syntax**  p = capaplot(data, specs)
[p, h] = capaplot(data, specs)

**Description**  p = capaplot(data, specs) estimates the mean and variance of the observations in input vector data, and plots the pdf of the resulting T distribution. The observations in data are assumed to be normally distributed. The output, p, is the probability that a new observation from the estimated distribution will fall within the range specified by the two-element vector specs. The portion of the distribution between the lower and upper bounds specified in specs is shaded in the plot.

[p, h] = capaplot(data, specs) additionally returns handles to the plot elements in h.

**Example**  Imagine a machined part with specifications requiring a dimension to be within 3 thousandths of an inch of nominal. Suppose that the machining process cuts too thick by one thousandth of an inch on average and also has a standard deviation of one thousandth of an inch.

```
data = normrnd(1, 1, 30, 1);
p = capaplot(data, [-3 3])
p =

    0.9784
```

The probability of a new observation being within specs is 97.84%.



Probability Between Limits is 0.9784
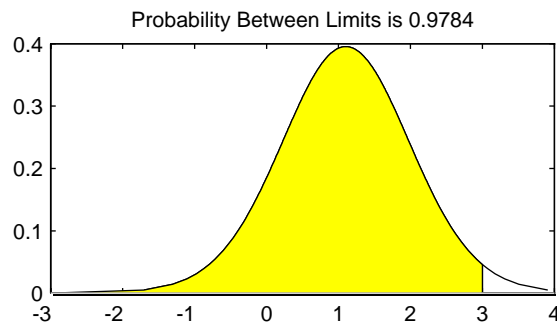
**See Also**     capable, histfit

# caseread

**Purpose**      Read casenames from a file.

**Syntax**       names = caseread('filename')
                 names = caseread

**Description**  names = caseread('filename') reads the contents of filename and returns a
                 string matrix of names. filename is the name of a file in the current directory,
                 or the complete pathname of any file elsewhere. caseread treats each line as a
                 separate case.

                 names = caseread displays the **Select File to Open** dialog box for interactive
                 selection of the input file.

**Example**      Read the file months.dat created using the function casewrite on the next
                 page.

    type months.dat

    January
    February
    March
    April
    May

    names = caseread('months.dat')
    names =

    January
    February
    March
    April
    May

**See Also**     tblread, gname, casewrite, tdfread

**Purpose**        Write casenames from a string matrix to a file.

**Syntax**         casewrite(strmat,'filename')
                   casewrite(strmat)

**Description**    casewrite(strmat,'filename') writes the contents of string matrix strmat
                   to filename. Each row of strmat represents one casename. filename is the
                   name of a file in the current directory, or the complete pathname of any file
                   elsewhere. casewrite writes each name to a separate line in filename.

                   casewrite(strmat) displays the **Select File to Write** dialog box for interactive
                   specification of the output file.

**Example**        strmat = str2mat('January','February','March','April','May')

                   strmat =

                   January
                   February
                   March
                   April
                   May

                   casewrite(strmat,'months.dat')
                   type months.dat

                   January
                   February
                   March
                   April
                   May

**See Also**       gname, caseread, tblwrite, tdfread

# cdf

**Purpose**     Computes a chosen cumulative distribution function (cdf).

**Syntax**     P = cdf('*name*', X, A1, A2, A3)

**Description**     P = cdf('*name*', X, A1, A2, A3) returns a matrix of probabilities, where name is
a string containing the name of the distribution, X is a matrix of values, and A,
A2, and A3 are matrices of distribution parameters. Depending on the
distribution, some of these parameters may not be necessary.

Vector or matrix inputs for X, A1, A2, and A3 must have the same size, which is
also the size of P. A scalar input for X, A1, A2, or A3 is expanded to a constant
matrix with the same dimensions as the other inputs.

cdf is a utility routine allowing you to access all the cdfs in the Statistics
Toolbox by using the name of the distribution as a parameter. See "Overview
of the Distributions" on page 1-12 for the list of available distributions.

**Examples**
```
p = cdf('Normal', -2:2, 0, 1)
p =

    0.0228    0.1587    0.5000    0.8413    0.9772

p = cdf('Poisson', 0:5, 1:6)
p =

    0.3679    0.4060    0.4232    0.4335    0.4405    0.4457
```

**See Also**     betacdf, binocdf, chi2cdf, expcdf, fcdf, gamcdf, geocdf, hygecdf, icdf,
logncdf, mle, nbincdf, ncfcdf, nctcdf, ncx2cdf, normcdf, pdf, poisscdf,
random, raylcdf, tcdf, unidcdf, unifcdf, weibcdf

**Purpose**            Plot of empirical cumulative distribution function.

**Syntax**             cdfplot(X)
                       h = cdfplot(X)
                       [h, stats] = cdfplot(X)

**Description**        cdfplot(X) displays a plot of the empirical cumulative distribution function
                       (cdf) for the data in the vector X. The empirical cdf $F(x)$ is defined as the
                       proportion of X values less than or equal to *x*.

                       This plot, like those produced by hist and normplot, is useful for examining
                       the distribution of a sample of data. You can overlay a theoretical cdf on the
                       same plot to compare the empirical distribution of the sample to the theoretical
                       distribution.

                       The kstest, kstest2, and lillietest functions compute test statistics that
                       are derived from the empirical cdf. You may find the empirical cdf plot
                       produced by cdfplot useful in helping you to understand the output from those
                       functions.

                       H = cdfplot(X) returns a handle to the cdf curve.

                       [h, stats] = cdfplot(X) also returns a stats structure with the following
                       fields.

| Field | Contents |
|-------|----------|
| stats.min | Minimum value |
| stats.max | Maximum value |
| stats.mean | Sample mean |
| stats.median | Sample median (50th percentile) |
| stats.std | Sample standard deviation |

**Examples**           Generate a normal sample and an empirical cdf plot of the data.

                       x = normrnd(0, 1, 50, 1);
                       cdfplot(x)

# cdfplot
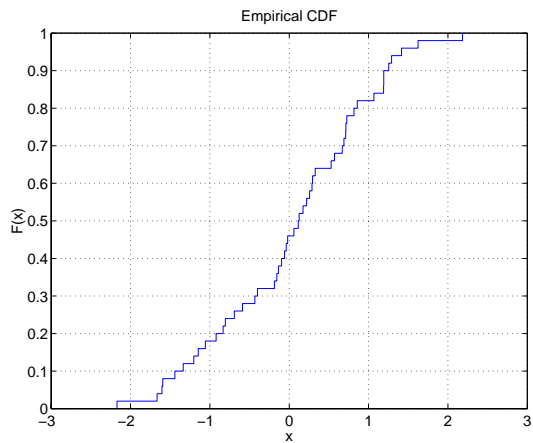


**See Also**        hist, kstest, kstest2, lillietest, normplot

**Purpose**        Chi-square ($\chi^2$) cumulative distribution function (cdf).

**Syntax**         P = chi2cdf(X, V)

**Description**    P = chi2cdf(X, V) computes the $\chi^2$ cdf at each of the values in X using the corresponding parameters in V. Vector or matrix inputs for X and V must have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other input. The degrees of freedom parameters in V must be positive integers, and the values in X must lie on the interval [0 1].

The $\chi^2$ cdf for a given value $x$ and degrees-of-freedom $\nu$ is

$$p = F(x|\nu) = \int_0^x \frac{t^{(\nu-2)/2}e^{-t/2}}{2^{\nu/2}\,\Gamma(\nu/2)}dt$$

where $\Gamma(\cdot)$ is the Gamma function. The result, p, is the probability that a single observation from a $\chi^2$ distribution with $\nu$ degrees of freedom will fall in the interval [0 $x$].

The $\chi^2$ density function with $\nu$ degrees-of-freedom is the same as the gamma density function with parameters $\nu/2$ and 2.

**Examples**       probability = chi2cdf(5, 1:5)
                   probability =

                       0.9747    0.9179    0.8282    0.7127    0.5841

                   probability = chi2cdf(1:5, 1:5)
                   probability =

                       0.6827    0.6321    0.6084    0.5940    0.5841

**See Also**       cdf, chi2inv, chi2pdf, chi2rnd, chi2stat

# chi2inv

**Purpose**      Inverse of the chi-square ($\chi^2$) cumulative distribution function (cdf).

**Syntax**       X = chi2inv(P, V)

**Description**  X = chi2inv(P, V) computes the inverse of the $\chi^2$ cdf with parameters specified by V for the corresponding probabilities in P. Vector or matrix inputs for P and V must have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

The degrees of freedom parameters in V must be positive integers, and the values in P must lie in the interval [0 1].

The inverse $\chi^2$ cdf for a given probability $p$ and $\nu$ degrees of freedom is

$$x = F^{-1}(p|\nu) = \{x : F(x|\nu) = p\}$$

where

$$p = F(x|\nu) = \int_0^x \frac{t^{(\nu-2)/2} e^{-t/2}}{2^{\nu/2}\, \Gamma(\nu/2)} dt$$

and $\Gamma(\cdot)$ is the Gamma function. Each element of output X is the value whose cumulative probability under the $\chi^2$ cdf defined by the corresponding degrees of freedom parameter in V is specified by the corresponding value in P.

**Examples**     Find a value that exceeds 95% of the samples from a $\chi^2$ distribution with 10 degrees of freedom.

    x = chi2inv(0.95, 10)
    x =

        18.3070

You would observe values greater than 18.3 only 5% of the time by chance.

**See Also**     chi2cdf, chi2pdf, chi2rnd, chi2stat, icdf

**Purpose**       Chi-square ($\chi^2$) probability density function (pdf).

**Syntax**        Y = chi2pdf(X, V)

**Description**   Y = chi2pdf(X, V) computes the $\chi^2$ pdf at each of the values in X using the corresponding parameters in V. Vector or matrix inputs for X and V must have the same size, which is also the size of output Y. A scalar input is expanded to a constant matrix with the same dimensions as the other input.

The degrees of freedom parameters in V must be positive integers, and the values in X must lie on the interval [0 1].

The $\chi^2$ pdf for a given value $x$ and $\nu$ degrees of freedom is

$$y = f(x|\nu) = \frac{x^{(\nu-2)/2}e^{-x/2}}{2^{\nu/2}\,\Gamma(\nu/2)}$$

where $\Gamma(\cdot)$ is the Gamma function. The result, $y$, is the probability that a single observation from a $\chi^2$ distribution with $\nu$ degrees of freedom will have value $x$.

If $x$ is standard normal, then $x^2$ is distributed $\chi^2$ with one degree of freedom. If $x_1$, $x_2$, ..., $x_n$ are $n$ independent standard normal observations, then the sum of the squares of the $x$'s is distributed $\chi^2$ with $n$ degrees of freedom (and is equivalent to the gamma density function with parameters $\nu/2$ and 2).

**Examples**      nu = 1:6;
                  x = nu;
                  y = chi2pdf(x, nu)

                  y =

                      0.2420    0.1839    0.1542    0.1353    0.1220    0.1120

The mean of the $\chi^2$ distribution is the value of the degrees of freedom parameter, nu. The above example shows that the probability density of the mean falls as nu increases.

**See Also**      chi2cdf, chi2inv, chi2rnd, chi2stat, pdf

# chi2rnd

**Purpose**　Random numbers from the chi-square ($\chi^2$) distribution.

**Syntax**　R = chi2rnd(V)
R = chi2rnd(V, m)
R = chi2rnd(V, m, n)

**Description**　R = chi2rnd(V) generates random numbers from the $\chi^2$ distribution with degrees of freedom parameters specified by V. R is the same size as V.

R = chi2rnd(V, m) generates a matrix of size m containing random numbers from the $\chi^2$ distribution with degrees of freedom parameter V, where m is a 1-by-2 vector containing the row and column dimensions of R.

R = chi2rnd(V, m, n) generates an m-by-n matrix containing random numbers from the $\chi^2$ distribution with degrees of freedom parameter V.

**Examples**　Note that the first and third commands are the same, but are different from the second command.

```
r = chi2rnd(1: 6)
r =

    0.0037    3.0377    7.8142    0.9021    3.2019    9.0729

r = chi2rnd(6, [1  6])
r =

    6.5249    2.6226   12.2497    3.0388    6.3133    5.0388

r = chi2rnd(1: 6, 1, 6)
r =

    0.7638    6.0955    0.8273    3.2506    1.5469   10.9197
```

**See Also**　chi2cdf, chi2inv, chi2pdf, chi2stat

**Purpose**      Mean and variance for the chi-square ($\chi^2$) distribution.

**Syntax**       [M, V] = chi2stat(NU)

**Description**  [M, V] = chi2stat(NU) returns the mean and variance for the $\chi^2$ distribution with degrees of freedom parameters specified by NU.

The mean of the $\chi^2$ distribution is $\nu$, the degrees of freedom parameter, and the variance is $2\nu$.

**Example**
```
nu = 1:10;
nu = nu'*nu;
[m, v] = chi2stat(nu)

m =
```

| 1  | 2  | 3  | 4  | 5  | 6  | 7  | 8  | 9  | 10  |
|----|----|----|----|----|----|----|----|----|-----|
| 2  | 4  | 6  | 8  | 10 | 12 | 14 | 16 | 18 | 20  |
| 3  | 6  | 9  | 12 | 15 | 18 | 21 | 24 | 27 | 30  |
| 4  | 8  | 12 | 16 | 20 | 24 | 28 | 32 | 36 | 40  |
| 5  | 10 | 15 | 20 | 25 | 30 | 35 | 40 | 45 | 50  |
| 6  | 12 | 18 | 24 | 30 | 36 | 42 | 48 | 54 | 60  |
| 7  | 14 | 21 | 28 | 35 | 42 | 49 | 56 | 63 | 70  |
| 8  | 16 | 24 | 32 | 40 | 48 | 56 | 64 | 72 | 80  |
| 9  | 18 | 27 | 36 | 45 | 54 | 63 | 72 | 81 | 90  |
| 10 | 20 | 30 | 40 | 50 | 60 | 70 | 80 | 90 | 100 |

```
v =
```

| 2  | 4  | 6  | 8  | 10  | 12  | 14  | 16  | 18  | 20  |
|----|----|----|----|-----|-----|-----|-----|-----|-----|
| 4  | 8  | 12 | 16 | 20  | 24  | 28  | 32  | 36  | 40  |
| 6  | 12 | 18 | 24 | 30  | 36  | 42  | 48  | 54  | 60  |
| 8  | 16 | 24 | 32 | 40  | 48  | 56  | 64  | 72  | 80  |
| 10 | 20 | 30 | 40 | 50  | 60  | 70  | 80  | 90  | 100 |
| 12 | 24 | 36 | 48 | 60  | 72  | 84  | 96  | 108 | 120 |
| 14 | 28 | 42 | 56 | 70  | 84  | 98  | 112 | 126 | 140 |
| 16 | 32 | 48 | 64 | 80  | 96  | 112 | 128 | 144 | 160 |
| 18 | 36 | 54 | 72 | 90  | 108 | 126 | 144 | 162 | 180 |
| 20 | 40 | 60 | 80 | 100 | 120 | 140 | 160 | 180 | 200 |

**See Also**     chi2cdf, chi2inv, chi2pdf, chi2rnd

# classify

| | |
|---|---|
| **Purpose** | Linear discriminant analysis. |
| **Syntax** | class = classify(sample, training, group) |

**Description**   class = classify(sample, training, group) assigns each row of the data in
sample to one of the groups into which the training set, training, is already
divided. sample and training must have the same number of columns.

The vector group contains integers, from one to the number of groups, that
identify the group to which each row of the training set belongs. group and
training must have the same number of rows.

The function returns class, a vector with the same number of rows as sample.
Each element of class identifies the group to which the corresponding element
of sample has been assigned. The classify function determines the group into
which each row in sample is classified by computing the Mahalanobis distance
between each row in sample and each row in training.

**Example**
```
load discrim
sample = ratings(idx,:);
training = ratings(1:200,:);
g = group(1:200);
class = classify(sample, training, g);
first5 = class(1:5)

first5 =

    2
    2
    2
    2
    2
```

**See Also**   mahal

**Purpose**        Construct clusters from linkage output.

**Syntax**        T = cluster(Z, cutoff)
                  T = cluster(Z, cutoff, depth, flag)

**Description**   T = cluster(Z, cutoff) constructs clusters from the hierarchical cluster
                  tree, Z, generated by the linkage function. Z is a matrix of size ($m$-1)-by-3,
                  where $m$ is the number of observations in the original data.

                  cutoff is a threshold value that determines how the cluster function creates
                  clusters. The value of cutoff determines how cluster interprets it.

| Value | Meaning |
|-------|---------|
| 0 < cutoff < 2 | cutoff is interpreted as the threshold for the inconsistency coefficient. The inconsistency coefficient quantifies the degree of difference between objects in the hierarchical cluster tree. If the inconsistency coefficient of a link is greater than the threshold, the cluster function uses the link as a boundary for a cluster grouping. For more information about the inconsistency coefficient, see the inconsistent function. |
| cutoff >= 2 | cutoff is interpreted as the maximum number of clusters to retain in the hierarchical tree. |

T = cluster(Z, cutoff, depth, flag) constructs clusters from cluster tree Z.
The depth argument specifies the number of levels in the hierarchical cluster
tree to include in the inconsistency coefficient computation. (The inconsistency
coefficient compares a link between two objects in the cluster tree with
neighboring links up to a specified depth. See the inconsistent function for
more information.) When the depth argument is specified, cutoff is always
interpreted as the inconsistency coefficient threshold.

The flag argument overrides the default meaning of the cutoff argument. If
flag is 'inconsistent', then cutoff is interpreted as a threshold for the
inconsistency coefficient. If flag is 'clusters', then cutoff is the maximum
number of clusters.

The output, T, is a vector of size $m$ that identifies, by number, the cluster in which each object was grouped. To find out which objects from the original dataset are contained in cluster $i$, use find(T==i).

**Example**    The example uses the pdist function to calculate the distance between items in a matrix of random numbers and then uses the linkage function to compute the hierarchical cluster tree based on the matrix. The output of the linkage function is passed to the cluster function. The cutoff value 3 indicates that you want to group the items into three clusters. The example uses the find function to list all the items grouped into cluster 2.

```
rand('seed', 0);
X = [rand(10, 3); rand(10, 3)+1; rand(10, 3)+2];
Y = pdist(X);
Z = linkage(Y);
T = cluster(Z, 3);
find(T==3)

ans =
    11
    12
    13
    14
    15
    16
    17
    18
    19
    20
```

**See Also**    clusterdata, cophenet, dendrogram, inconsistent, linkage, pdist, squareform

**Purpose**     Construct clusters from data.

**Syntax**      T = clusterdata(X, cutoff)

**Description**   T = clusterdata(X, cutoff) constructs clusters from the data matrix X. X is a matrix of size *m* by *n*, interpreted as *m* observations of *n* variables.

cutoff is a threshold value that determines how the cluster function creates clusters. The value of cutoff determines how clusterdata interprets it.

| Value | Meaning |
|-------|---------|
| 0 < cutoff < 1 | cutoff is interpreted as the threshold for the inconsistency coefficient. The inconsistency coefficient quantifies the degree of difference between objects in the hierarchical cluster tree. If the inconsistency coefficient of a link is greater than the threshold, the cluster function uses the link as a boundary for a cluster grouping. For more information about the inconsistency coefficient, see the inconsistent function. |
| cutoff >= 1 | cutoff is interpreted as the maximum number of clusters to retain in the hierarchical tree. |

The output, T, is a vector of size *m* that identifies, by number, the cluster in which each object was grouped.

T = clusterdata(X, cutoff) is the same as

```
Y = pdist(X, 'euclid');
Z = linkage(Y, 'single');
T = cluster(Z, cutoff);
```

Follow this sequence to use nondefault parameters for pdist and linkage.

**Example**      The example first creates a sample dataset of random numbers. The example then uses the clusterdata function to compute the distances between items in the dataset and create a hierarchical cluster tree from the dataset. Finally, the clusterdata function groups the items in the dataset into three clusters. The example uses the find function to list all the items in cluster 2.

```
rand('seed', 12);
X = [rand(10, 3); rand(10, 3)+1.2; rand(10, 3)+2.5;
T = clusterdata(X, 3);
find(T==2)

ans =
    21
    22
    23
    24
    25
    26
    27
    28
    29
    30
```

**See Also**      cluster, cophenet, dendrogram, inconsistent, linkage, pdist, squareform

**Purpose**     Enumeration of all combinations of *n* objects *k* at a time.

**Syntax**      C = combnk(v, k)

**Description**  C = combnk(v, k) returns all combinations of the *n* elements in v taken k at a time.

C = combnk(v, k) produces a matrix C with k columns and *n*! / *k*!(*n-k*)! rows, where each row contains k of the elements in the vector v.

It is not practical to use this function if v has more than about 15 elements.

**Example**     Combinations of characters from a string.

```
C = combnk('tendril', 4);
last5 = C(31:35,:)

last5 =

tedr
tenl
teni
tenr
tend
```

Combinations of elements from a numeric vector.

```
c = combnk(1:4, 2)

c =
     3     4
     2     4
     2     3
     1     4
     1     3
     1     2
```

# cophenet

**Purpose**        Cophenetic correlation coefficient.

**Syntax**        c = cophenet(Z, Y)

**Description**    c = cophenet(Z, Y) computes the cophenetic correlation coefficient which
compares the distance information in Z, generated by linkage, and the
distance information in Y, generated by pdist. Z is a matrix of size ($m$-1)-by-3,
with distance information in the third column. Y is a vector of size
$m \cdot (m - 1)/2$.

For example, given a group of objects {1, 2, ..., $m$} with distances Y, the function
linkage produces a hierarchical cluster tree. The cophenet function measures
the distortion of this classification, indicating how readily the data fits into the
structure suggested by the classification.

The output value, c, is the cophenetic correlation coefficient. The magnitude of
this value should be very close to 1 for a high-quality solution. This measure
can be used to compare alternative cluster solutions obtained using different
algorithms.

The cophenetic correlation between $Z(:, 3)$ and Y is defined as

$$c = \frac{\Sigma_{i<j}(Y_{ij} - y)(Z_{ij} - z)}{\sqrt{\Sigma_{i<j}(Y_{ij} - y)^2 \Sigma_{i<j}(Z_{ij} - z)^2}}$$

where:

- $Y_{ij}$ is the distance between objects $i$ and $j$ in Y.
- $Z_{ij}$ is the distance between objects $i$ and $j$ in $Z(:, 3)$.
- $y$ and $z$ are the average of Y and $Z(:, 3)$, respectively.

**Example**
```
rand('seed', 12);
X = [rand(10, 3); rand(10, 3)+1; rand(10, 3)+2];
Y = pdist(X);
Z = linkage(Y, 'centroid');
c = cophenet(Z, Y)

c =
    0.6985
```

**See Also**     cluster, dendrogram, inconsistent, linkage, pdist, squareform

# cordexch

**Purpose**     D-optimal design of experiments – coordinate exchange algorithm.

**Syntax**      settings = cordexch(nfactors, nruns)
                [settings, X] = cordexch(nfactors, nruns)
                [settings, X] = cordexch(nfactors, nruns, '*model*')

**Description**  settings = cordexch(nfactors, nruns) generates the factor settings matrix, settings, for a D-optimal design using a linear additive model with a constant term. settings has nruns rows and nfactors columns.

[settings, X] = cordexch(nfactors, nruns) also generates the associated design matrix X.

[settings, X] = cordexch(nfactors, nruns, '*model*') produces a design for fitting a specified regression model. The input, '*model*', can be one of these strings:

- 'interaction' – includes constant, linear, and cross-product terms.
- 'quadratic' – includes interactions and squared terms.
- 'purequadratic' – includes constant, linear and squared terms.

**Example**     The D-optimal design for two factors in nine run using a quadratic model is the $3^2$ factorial as shown below:

    settings = cordexch(2, 9, 'quadratic')

    settings =

        -1      1
         1      1
         0      1
         1     -1
        -1     -1
         0     -1
         1      0
         0      0
        -1      0

**See Also**    rowexch, daugment, dcovary, hadamard, fullfact, ff2n

**Purpose**        Correlation coefficients.

**Syntax**         R = corrcoef(X)

**Description**    R = corrcoef(X) returns a matrix of correlation coefficients calculated from
                   an input matrix whose rows are observations and whose columns are variables.
                   Element *i,j* of the matrix R is related to the corresponding element of the
                   covariance matrix C = cov(X) by

$$R(i,j) = \frac{C(i,j))}{\sqrt{C(i,i)C(j,j)}}$$

The corrcoef function is part of the standard MATLAB language.

**See Also**       cov, mean, std, var

# cov

| | |
|---|---|
| **Purpose** | Covariance matrix. |
| **Syntax** | C = cov(X)<br>C = cov(x, y) |
| **Description** | C = cov(X) computes the covariance matrix. For a single vector, cov(x) returns a scalar containing the variance. For matrices, where each row is an observation, and each column a variable, cov(X) is the covariance matrix.<br><br>The variance function, var(X) is the same as diag(cov(X)).<br><br>The standard deviation function, std(X) is equivalent to sqrt(diag(cov(X))).<br><br>cov(x, y), where x and y are column vectors of equal length, gives the same result as cov([x y]).<br><br>The cov function is part of the standard MATLAB language. |
| **Algorithm** | The algorithm for cov is<br><br>`[n, p] = size(X);`<br>`X = X - ones(n, 1) * mean(X);`<br>`Y = X'*X/(n-1);` |
| **See Also** | corrcoef, mean, std, var<br><br>xcov, xcorr (Signal Processing Toolbox) |

| | |
|---|---|
| **Purpose** | Cross-tabulation of several vectors. |
| **Syntax** | table = crosstab(col1, col2)<br>table = crosstab(col1, col2, col3, ...)<br>[table, chi2, p] = crosstab(col1, col2)<br>[table, chi2, p, label] = crosstab(col1, col2) |

**Description**

table = crosstab(col1, col2) takes two vectors of positive integers and returns a matrix, table, of cross-tabulations. The *ij*th element of table contains the count of all instances where col1 = *i* and col2 = *j*.

Alternatively, col1 and col2 can be vectors containing noninteger values, character arrays, or cell arrays of strings. crosstab implicitly assigns a positive integer group number to each distinct value in col1 and col2, and creates a cross-tabulation using those numbers.

table = crosstab(col1, col2, col3, ...) returns table as an *n*-dimensional array, where *n* is the number of arguments you supply. The value of table(i, j, k, ...) is the count of all instances where col1 = *i*, col2 = *j*, col3 = *k*, and so on.

[table, chi2, p] = crosstab(col1, col2) also returns the chi-square statistic, chi2, for testing the independence of the rows and columns of table. The scalar p is the significance level of the test. Values of p near zero cast doubt on the assumption of independence of the rows and columns of table.

[table, chi2, p, label] = crosstab(col1, col2) also returns a cell array label that has one column for each input argument. The value in label(*i*, *j*) is the value of col*j* that defines group *i* in the *j*th dimension.

**Example**

**Example 1**

We generate 2 columns of 50 discrete uniform random numbers. The first column has numbers from 1 to 3. The second has only the numbers 1 and 2. The two columns are independent so we would be surprised if p were near zero.

```
r1 = unidrnd(3, 50, 1);
r2 = unidrnd(2, 50, 1);
[table, chi2, p] = crosstab(r1, r2)
```

```
table =

    10      5
     8      8
     6     13

chi2 =

    4.1723

p =

    0.1242
```

The result, 0.1242, is not a surprise. A very small value of p would make us suspect the "randomness" of the random number generator.

### Example 2

We have data collected on several cars over a period of time. How many four-cylinder cars were made in the USA during the late part of this period?

```
[t, c, p, l] = crosstab(cyl4, when, org);

l
l =
    'Other'      'Early'      'USA'
    'Four'       'Mid'        'Europe'
         []      'Late'       'Japan'

t(2, 3, 1)

ans =
    38
```

**See Also**     tabulate

**Purpose**    D-optimal augmentation of an experimental design.

**Syntax**    settings = daugment(startdes, nruns)
[settings, X] = daugment(startdes, nruns, '*model*')

**Description**    settings = daugment(startdes, nruns) augments an initial experimental
design, startdes, with nruns new tests.

[settings, X] = daugment(startdes, nruns, '*model*') also supplies the
design matrix, X. The input, 'model', controls the order of the regression
model. By default, daugment assumes a linear additive model. Alternatively,
'model' can be any of these:

- 'interaction' – includes constant, linear, and cross product terms.
- 'quadratic' – includes interactions plus squared terms.
- 'purequadratic' – includes constant, linear, and squared terms.

daugment uses the coordinate exchange algorithm.

**Example**    We add 5 runs to a $2^2$ factorial design to allow us to fit a quadratic model.

    startdes = [-1 -1; 1 -1; -1 1; 1 1];
    settings = daugment(startdes, 5, 'quadratic')

    settings =

         -1     -1
          1     -1
         -1      1
          1      1
          1      0
         -1      0
          0      1
          0      0
          0     -1

The result is a $3^2$ factorial design.

**See Also**    cordexch, dcovary, rowexch

# dcovary

**Purpose**        D-optimal design with specified fixed covariates.

**Syntax**        settings = dcovary(factors, covariates)
[settings, X] = dcovary(factors, covariates, '*model*')

**Description**    settings = dcovary(factors, covariates, '*model*') creates a D-optimal design subject to the constraint of fixed covariates for each run. factors is the number of experimental variables you want to control.

[settings, X] = dcovary(factors, covariates, '*model*') also creates the associated design matrix, X. The input, '*model*', controls the order of the regression model. By default, dcovary assumes a linear additive model. Alternatively, '*model*' can be any of these:

- 'interaction' – includes constant, linear, and cross product terms.
- 'quadratic' – includes interactions plus squared terms.
- 'purequadratic' – includes constant, linear, and squared terms.

**Example**     Suppose we want to block an eight run experiment into 4 blocks of size 2 to fit a linear model on two factors.

```
covariates = dummyvar([1 1 2 2 3 3 4 4]);
settings = dcovary(2, covariates(:, 1:3), 'linear')
settings =
```

| | | | | |
|---|---|---|---|---|
| 1 | 1 | 1 | 0 | 0 |
| -1 | -1 | 1 | 0 | 0 |
| -1 | 1 | 0 | 1 | 0 |
| 1 | -1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 0 | 1 |
| -1 | -1 | 0 | 0 | 1 |
| -1 | 1 | 0 | 0 | 0 |
| 1 | -1 | 0 | 0 | 0 |

The first two columns of the output matrix contain the settings for the two factors. The last three columns are *dummy variable* codings for the four blocks.

**See Also**     daugment, cordexch

**Purpose**     Plot dendrogram graphs.

**Syntax**     H = dendrogram(Z)
               H = dendrogram(Z, p)
               [H, T] = dendrogram(...)

**Description**     H = dendrogram(Z) generates a dendrogram plot of the hierarchical, binary
                    cluster tree, Z. Z is an (*m*-1)-by-3 matrix, generated by the linkage function,
                    where *m* is the number of objects in the original dataset.

                    A dendrogram consists of many upside-down, U-shaped lines connecting
                    objects in a hierarchical tree. Except for the Ward linkage (see linkage), the
                    height of each U represents the distance between the two objects being
                    connected. The output, H, is a vector of line handles.

                    H = dendrogram(Z, p) generates a dendrogram with only the top *p* nodes. By
                    default, dendrogram uses 30 as the value of *p*. When there are more than 30
                    initial nodes, a dendrogram may look crowded. To display every node, set p = 0.

                    [H, T] = dendrogram(...) generates a dendrogram and returns T, a vector of
                    size *m* that contains the cluster number for each object in the original dataset.
                    T provides access to the nodes of a cluster hierarchy that are not displayed in
                    the dendrogram because they fall below the cutoff value *p*. For example, to find
                    out which objects are contained in leaf node k of the dendrogram, use
                    find(T==k). Leaf nodes are the nodes at the bottom of the dendrogram that
                    have no other nodes below them.

                    When there are fewer than *p* objects in the original data, all objects are
                    displayed in the dendrogram. In this case, T is the identical map, i.e.,
                    T = (1:m)', where each node contains only itself.

**Example**          rand('seed', 12);
                     X= rand(100, 2);
                     Y= pdist(X, 'citiblock');
                     Z= linkage(Y, 'average');
                     [H, T] = dendrogram(Z);
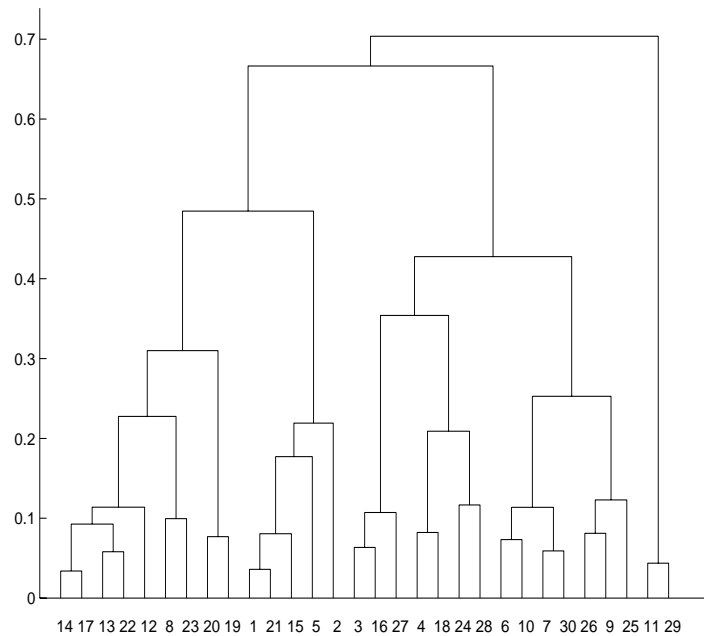
```
find(T==20)

ans =

    20
    49
    62
    65
    73
    96
```

This output indicates that leaf node 20 in the dendrogram contains the original data points 20, 49, 62, 65, 73, and 96.

**See Also**      cluster, clusterdata, cophenet, inconsistent, linkage, pdist, squareform

**Purpose**     Interactive graph of cdf (or pdf) for many probability distributions.

**Syntax**      disttool

**Description** The disttool command displays a graphic user interface for exploring the
effects of changing parameters on the plot of a cdf or pdf. Clicking and dragging
a vertical line on the plot allows you to interactively evaluate the function over
its entire domain.

Evaluate the plotted function by typing a value in the *x*-axis edit box or
dragging the vertical reference line on the plot. For cdfs, you can evaluate the
inverse function by typing a value in the *y*-axis edit box or dragging the
horizontal reference line on the plot. The shape of the pointer changes from an
arrow to a crosshair when it is over the vertical or horizontal line to indicate
that the reference line is draggable.

To change the distribution function, choose an option from the menu of
functions at the top left of the figure. To change from cdfs to pdfs, choose an
option from the menu at the top right of the figure.

To change the parameter settings, move the sliders or type a value in the edit
box under the name of the parameter. To change the limits of a parameter, type
a value in the edit box at the top or bottom of the parameter slider.

To close the tool, press the **Close** button.

**See Also**    randtool

# dummyvar

| | |
|---|---|
| **Purpose** | Matrix of 0-1 "dummy" variables. |
| **Syntax** | D = dummyvar(group) |
| **Description** | D = dummyvar(group) generates a matrix, D, of 0-1 columns. D has one column for each unique value in each column of the matrix group. Each column of group contains positive integers that indicate the group membership of an individual row. |
| **Example** | Suppose we are studying the effects of two machines and three operators on a process. The first column of group would have the values 1 or 2 depending on which machine was used. The second column of group would have the values 1, 2, or 3 depending on which operator ran the machine. |

```
group = [1  1; 1  2; 1  3; 2  1; 2  2; 2  3];
D = dummyvar(group)

D =
     1     0     1     0     0
     1     0     0     1     0
     1     0     0     0     1
     0     1     1     0     0
     0     1     0     1     0
     0     1     0     0     1
```

**See Also**     pinv, regress

**Purpose**          Plot error bars along a curve.

**Syntax**           errorbar(X, Y, L, U, symbol)
                     errorbar(X, Y, L)
                     errorbar(Y, L)

**Description**      errorbar(X, Y, L, U, symbol) plots X versus Y with error bars specified by L
                     and U. X, Y, L, and U must be the same length. If X, Y, L, and U are matrices, then
                     each column produces a separate line. The error bars are each drawn a distance
                     of U(i) above and L(i) below the points in (X, Y). symbol is a string that
                     controls the line type, plotting symbol, and color of the error bars.

                     errorbar(X, Y, L) plots X versus Y with symmetric error bars about Y.

                     errorbar(Y, L) plots Y with error bars [Y–L Y+L].

                     The errorbar function is a part of the standard MATLAB language.

**Example**          lambda = (0.1:0.2:0.5);
                     r = poissrnd(lambda(ones(50, 1), :));
                     [p, pci] = poissfit(r, 0.001);
                     L = p - pci(1, :)
                     U = pci(2, :) - p
                     errorbar(1:3, p, L, U, '+')

                     L =
                         0.1200      0.1600      0.2600

                     U =
                         0.2000      0.2200      0.3400
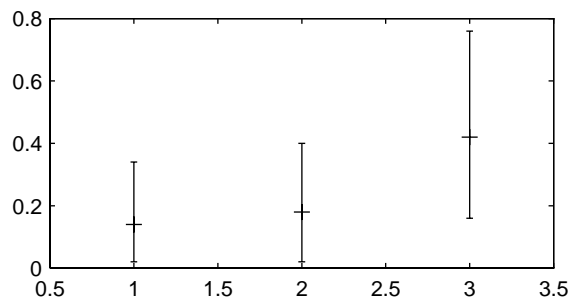
# ewmaplot

| | |
|---|---|
| **Purpose** | Exponentially Weighted Moving Average (EWMA) chart for Statistical Process Control (SPC). |
| **Syntax** | ewmaplot(data) |
| | ewmaplot(data, lambda) |
| | ewmaplot(data, lambda, alpha) |
| | ewmaplot(data, lambda, alpha, specs) |
| | h = ewmaplot(...) |
| **Description** | ewmaplot(data) produces an EWMA chart of the grouped responses in data. The rows of data contain replicate observations taken at a given time. The rows should be in time order. |

ewmaplot(data, lambda) produces an EWMA chart of the grouped responses in data, and specifies how much the current prediction is influenced by past observations. Higher values of lambda give more weight to past observations. By default, lambda = 0.4; lambda must be between 0 and 1.

ewmaplot(data, lambda, alpha) produces an EWMA chart of the grouped responses in data, and specifies the significance level of the upper and lower plotted confidence limits. alpha is 0.0027 by default. This value produces three-sigma limits:

```
norminv(1-0.0027/2)

ans =
      3
```

To get *k*-sigma limits, use the expression 2*(1-normcdf(k)). For example, the correct alpha value for 2-sigma limits is 0.0455, as shown below.

```
k = 2;
2*(1-normcdf(k))

ans =
      0.0455
```

ewmaplot(data, lambda, alpha, specs) produces an EWMA chart of the grouped responses in data, and specifies a two-element vector, specs, for the lower and upper specification limits of the response.

$h = ewmaplot(...)$ returns a vector of handles to the plotted lines.

**Example**     Consider a process with a slowly drifting mean. An EWMA chart is preferable to an x-bar chart for monitoring this kind of process. The simulation below demonstrates an EWMA chart for a slow linear drift.

```
t = (1:28)';
r = normrnd(10+0.02*t(:,ones(4,1)),0.5);
ewmaplot(r,0.4,0.01,[9.75 10.75])
```
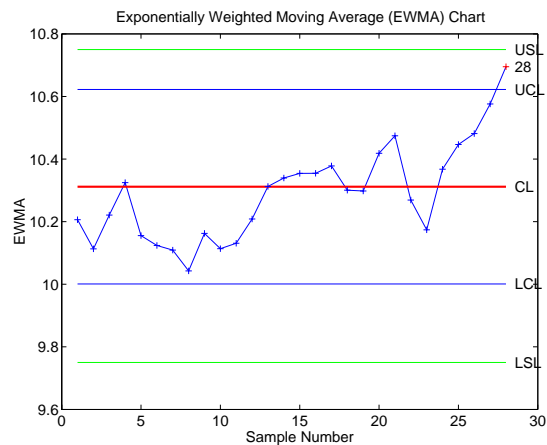


The EWMA value for group 28 is higher than would be expected purely by chance. If we had been monitoring this process continuously, we would have detected the drift when group 28 was collected, and we would have had an opportunity to investigate its cause.

**Reference**     Montgomery, D., *Introduction to Statistical Quality Control,* John Wiley & Sons 1991. p. 299.

**See Also**     xbarplot, schart

# expcdf

**Purpose**        Exponential cumulative distribution function (cdf).

**Syntax**         P = expcdf(X, MU)

**Description**    P = expcdf(X, MU) computes the exponential cdf at each of the values in X
                   using the corresponding parameters in MU. Vector or matrix inputs for X and MU
                   must have the same size. A scalar input is expanded to a constant matrix with
                   the same dimensions as the other input. The parameters in MU must be positive.

The exponential cdf is

$$p = F(x|\mu) = \int_0^x \frac{1}{\mu} e^{-\frac{t}{\mu}} dt = 1 - e^{-\frac{x}{\mu}}$$

The result, $p$, is the probability that a single observation from an exponential
distribution will fall in the interval [0 $x$].

**Examples**      The median of the exponential distribution is $\mu*\log(2)$. Demonstrate this fact.

```
mu = 10: 10: 60;
p = expcdf(log(2)*mu, mu)

p =
   0.5000    0.5000    0.5000    0.5000    0.5000    0.5000
```

What is the probability that an exponential random variable will be less than
or equal to the mean, $\mu$?

```
mu = 1: 6;
x = mu;
p = expcdf(x, mu)

p =
   0.6321    0.6321    0.6321    0.6321    0.6321    0.6321
```

**See Also**      cdf, expfit, expinv, exppdf, exprnd, expstat

**Purpose**          Parameter estimates and confidence intervals for exponential data.

**Syntax**           muhat = expfit(x)
                     [muhat, muci] = expfit(x)
                     [muhat, muci] = expfit(x, alpha)

**Description**      muhat = expfit(x) returns the estimate of the parameter, μ, of the
                     exponential distribution given data x.

                     [muhat, muci] = expfit(x) also returns the 95% confidence interval in muci.

                     [muhat, muci] = expfit(x, alpha) gives 100(1-alpha)% confidence
                     intervals. For example, alpha = 0.01 yields 99% confidence intervals.

**Example**          We generate 100 independent samples of exponential data with μ = 3. muhat is
                     an estimate of true_mu and muci is a 99% confidence interval around muhat.
                     Notice that muci contains true_mu.

                         true_mu = 3;
                         [muhat, muci] = expfit(r, 0.01)

                         muhat =

                             2.8835

                         muci =

                             2.1949
                             3.6803

**See Also**        expcdf, expinv, exppdf, exprnd, expstat, betafit, binofit, gamfit, normfit,
                     poissfit, unifit, weibfit

# expinv

**Purpose**         Inverse of the exponential cumulative distribution function (cdf).

**Syntax**          X = expinv(P, MU)

**Description**     X = expinv(P, MU) computes the inverse of the exponential cdf with
                    parameters specified by MU for the corresponding probabilities in P. Vector or
                    matrix inputs for P and MU must have the same size. A scalar input is expanded
                    to a constant matrix with the same dimensions as the other input. The
                    parameters in MU must be positive and the values in P must lie on the interval
                    [0 1].

                    The inverse of the exponential cdf is

$$x = F(p|\mu) = -\mu \ln(1 - p)$$

                    The result, *x*, is the value such that an observation from an exponential
                    distribution with parameter $\mu$ will fall in the range [0 *x*] with probability *p*.

**Examples**        Let the lifetime of light bulbs be exponentially distributed with $\mu$ = 700 hours.
                    What is the median lifetime of a bulb?

                    expinv(0.50, 700)

                    ans =

                       485.2030

                    So, suppose you buy a box of "700 hour" light bulbs. If 700 hours is the mean
                    life of the bulbs, then half them will burn out in less than 500 hours.

**See Also**        expcdf, expfit, exppdf, exprnd, expstat, icdf

**Purpose**      Exponential probability density function (pdf).

**Syntax**       Y = exppdf(X, MU)

**Description**  exppdf(X, MU) computes the exponential pdf at each of the values in X using the corresponding parameters in MU. Vector or matrix inputs for X and MU must be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other input. The parameters in MU must be positive.

The exponential pdf is

$$y = f(x|\mu) = \frac{1}{\mu}e^{-\frac{x}{\mu}}$$

The exponential pdf is the gamma pdf with its first parameter equal to 1.

The exponential distribution is appropriate for modeling waiting times when the probability of waiting an additional period of time is independent of how long you've already waited. For example, the probability that a light bulb will burn out in its next minute of use is relatively independent of how many minutes it has already burned.

**Examples**    y = exppdf(5, 1: 5)

y =
    0.0067    0.0410    0.0630    0.0716    0.0736

y = exppdf(1: 5, 1: 5)

y =
    0.3679    0.1839    0.1226    0.0920    0.0736

**See Also**    expcdf, expfit, expinv, exprnd, expstat, pdf

# exprnd

| | |
|---|---|
| **Purpose** | Random numbers from the exponential distribution. |
| **Syntax** | R = exprnd(MU) |
| | R = exprnd(MU, m) |
| | R = exprnd(MU, m, n) |

**Description**  R = exprnd(MU) generates exponential random numbers with mean MU. The size of R is the size of MU.

R = exprnd(MU, m) generates exponential random numbers with mean MU, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = exprnd(MU, m, n) generates exponential random numbers with mean MU, where scalars m and n are the row and column dimensions of R.

**Examples**
```
n1 = exprnd(5: 10)

n1 =
    7. 5943    18. 3400     2. 7113     3. 0936     0. 6078     9. 5841

n2 = exprnd(5: 10, [1  6])

n2 =
    3. 2752     1. 1110    23. 5530    23. 4303     5. 7190     3. 9876

n3 = exprnd(5, 2, 3)

n3 =
   24. 3339    13. 5271     1. 8788
    4. 7932     4. 3675     2. 6468
```

**See Also**  expcdf, expfit, expinv, exppdf, expstat

**Purpose**      Mean and variance for the exponential distribution.

**Syntax**       [M, V] = expstat(MU)

**Description**  [M, V] = expstat(MU) returns the mean and variance for the exponential
distribution with parameters MU. The mean of the exponential distribution is $\mu$,
and the variance is $\mu^2$.

**Examples**      [m, v] = expstat([1 10 100 1000])

m =
                   1            10           100          1000

v =
                   1           100         10000       1000000

**See Also**     expcdf, expfit, expinv, exppdf, exprnd

# fcdf

**Purpose**       F cumulative distribution function (cdf).

**Syntax**        P = fcdf(X, V1, V2)

**Description**   P = fcdf(X, V1, V2) computes the F cdf at each of the values in X using the
corresponding parameters in V1 and V2. Vector or matrix inputs for X, V1, and
V2 must all be the same size. A scalar input is expanded to a constant matrix
with the same dimensions as the other inputs. The parameters in V1 and V2
must be positive integers.

The F cdf is

$$p = F(x|\nu_1,\nu_2) = \int_0^x \frac{\Gamma\left[\frac{(\nu_1 + \nu_2)}{2}\right]}{\Gamma\left(\frac{\nu_1}{2}\right)\Gamma\left(\frac{\nu_2}{2}\right)} \left(\frac{\nu_1}{\nu_2}\right)^{\frac{\nu_1}{2}} \frac{t^{\frac{\nu_1 - 2}{2}}}{\left[1 + \left(\frac{\nu_1}{\nu_2}\right)t\right]^{\frac{\nu_1 + \nu_2}{2}}} dt$$

The result, $p$, is the probability that a single observation from an F distribution
with parameters $\nu_1$ and $\nu_2$ will fall in the interval [0 $x$].

**Examples**      This example illustrates an important and useful mathematical identity for the
F distribution.

```
nu1 = 1: 5;
nu2 = 6: 10;
x = 2: 6;
F1 = fcdf(x, nu1, nu2)

F1 =

    0. 7930    0. 8854    0. 9481    0. 9788    0. 9919

F2 = 1 - fcdf(1. /x, nu2, nu1)

F2 =

    0. 7930    0. 8854    0. 9481    0. 9788    0. 9919
```

**See Also**      cdf, finv, fpdf, frnd, fstat

**Purpose**        Two-level full-factorial designs.

**Syntax**         X = ff2n(n)

**Description**    X = ff2n(n) creates a two-level full-factorial design, X, where n is the desired number of columns of X. The number of rows in X is $2^n$.

**Example**            X = ff2n(3)

                       X =
                            0        0        0
                            0        0        1
                            0        1        0
                            0        1        1
                            1        0        0
                            1        0        1
                            1        1        0
                            1        1        1

                   X is the binary representation of the numbers from 0 to $2^n$-1.

**See Also**       fracfact, fullfact

# finv

**Purpose**      Inverse of the F cumulative distribution function (cdf).

**Syntax**       X = finv(P, V1, V2)

**Description**  X = finv(P, V1, V2) computes the inverse of the F cdf with numerator degrees of freedom V1 and denominator degrees of freedom V2 for the corresponding probabilities in P. Vector or matrix inputs for P, V1, and V2 must all be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

The parameters in V1 and V2 must all be positive integers, and the values in P must lie on the interval [0 1].

The F inverse function is defined in terms of the F cdf as

$$x = F^{-1}(p|\nu_1, \nu_2) = \{x : F(x|\nu_1, \nu_2) = p\}$$

where

$$p = F(x|\nu_1, \nu_2) = \int_0^x \frac{\Gamma\left[\dfrac{(\nu_1 + \nu_2)}{2}\right]}{\Gamma\left(\dfrac{\nu_1}{2}\right)\Gamma\left(\dfrac{\nu_2}{2}\right)} \left(\dfrac{\nu_1}{\nu_2}\right)^{\frac{\nu_1}{2}} \frac{t^{\frac{\nu_1 - 2}{2}}}{\left[1 + \left(\dfrac{\nu_1}{\nu_2}\right)t\right]^{\frac{\nu_1 + \nu_2}{2}}} dt$$

**Examples**     Find a value that should exceed 95% of the samples from an F distribution with 5 degrees of freedom in the numerator and 10 degrees of freedom in the denominator.

    x = finv(0.95, 5, 10)

    x =
        3.3258

You would observe values greater than 3.3258 only 5% of the time by chance.

**See Also**     fcdf, fpdf, frnd, fstat, icdf

**Purpose**         F probability density function (pdf).

**Syntax**          Y = fpdf(X, V1, V2)

**Description**     Y = fpdf(X, V1, V2) computes the F pdf at each of the values in X using the corresponding parameters in V1 and V2. Vector or matrix inputs for X, V1, and V2 must all be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in V1 and V2 must all be positive integers, and the values in X must lie on the interval $[0\ \infty)$.

The probability density function for the F distribution is

$$y = f(x|\nu_1,\nu_2) = \frac{\Gamma\left[\dfrac{(\nu_1+\nu_2)}{2}\right]}{\Gamma\left(\dfrac{\nu_1}{2}\right)\Gamma\left(\dfrac{\nu_2}{2}\right)}\left(\frac{\nu_1}{\nu_2}\right)^{\frac{\nu_1}{2}}\frac{x^{\frac{\nu_1-2}{2}}}{\left[1+\left(\dfrac{\nu_1}{\nu_2}\right)x\right]^{\frac{\nu_1+\nu_2}{2}}}$$

**Examples**        y = fpdf(1:6, 2, 2)

y =
  0.2500    0.1111    0.0625    0.0400    0.0278    0.0204

z = fpdf(3, 5:10, 5:10)

z =
  0.0689    0.0659    0.0620    0.0577    0.0532    0.0487

**See Also**        fcdf, finv, frnd, fstat, pdf

# fracfact

**Purpose**          Generate fractional factorial design from generators.

**Syntax**          x = fracfact('gen')
                    [x, conf] = fracfact('gen')

**Description**     x = fracfact('gen') generates a fractional factorial design as specified by
                    the generator string gen, and returns a matrix x of design points. The input
                    string gen is a generator string consisting of "words" separated by spaces. Each
                    word describes how a column of the output design should be formed from
                    columns of a full factorial. Typically gen will include single-letter words for the
                    first few factors, plus additional multiple-letter words describing how the
                    remaining factors are confounded with the first few.

                    The output matrix x is a fraction of a two-level full-factorial design. Suppose
                    there are $m$ words in gen, and that each word is formed from a subset of the
                    first $n$ letters of the alphabet. The output matrix x has $2^n$ rows and $m$ columns.
                    Let F represent the two-level full-factorial design as produced by ff2n(n). The
                    values in column $j$ of x are computed by multiplying together the columns of F
                    corresponding to letters that appear in the $j$th word of the generator string.

                    [x, conf] = fracfact('*gen*') also returns a cell array, conf, that describes
                    the confounding pattern among the main effects and all two-factor
                    interactions.

**Examples**        Example 1
                    We want to run an experiment to study the effects of four factors on a response,
                    but we can only afford eight runs. (A run is a single repetition of the experiment
                    at a specified combination of factor values.) Our goal is to determine which
                    factors affect the response. There may be interactions between some pairs of
                    factors.

                    A total of sixteen runs would be required to test all factor combinations.
                    However, if we are willing to assume there are no three-factor interactions, we
                    can estimate the main factor effects in just eight runs.

                        [x, conf] = fracfact('a b c abc')

```
x =
    -1    -1    -1    -1
    -1    -1     1     1
    -1     1    -1     1
    -1     1     1    -1
     1    -1    -1     1
     1    -1     1    -1
     1     1    -1    -1
     1     1     1     1

conf =

    'Term'      'Generator'    'Confounding'
    'X1'        'a'            'X1'
    'X2'        'b'            'X2'
    'X3'        'c'            'X3'
    'X4'        'abc'          'X4'
    'X1*X2'     'ab'           'X1*X2 + X3*X4'
    'X1*X3'     'ac'           'X1*X3 + X2*X4'
    'X1*X4'     'bc'           'X1*X4 + X2*X3'
    'X2*X3'     'bc'           'X1*X4 + X2*X3'
    'X2*X4'     'ac'           'X1*X3 + X2*X4'
    'X3*X4'     'ab'           'X1*X2 + X3*X4'
```

The first three columns of the x matrix form a full-factorial design. The final column is formed by multiplying the other three. The confounding pattern shows that the main effects for all four factors are estimable, but the two-factor interactions are not. For example, the X1*X2 and X3*X4 interactions are confounded, so it is not possible to estimate their effects separately.

After conducting the experiment, we may find out that the 'ab' effect is significant. In order to determine whether this effect comes from X1*X2 or X3*X4 we would have to run the remaining eight runs. We can obtain those runs by reversing the sign of the final generator.

```
fracfact('a b c -abc')
```

```
ans =
    -1    -1    -1     1
    -1    -1     1    -1
    -1     1    -1    -1
    -1     1     1     1
     1    -1    -1    -1
     1    -1     1     1
     1     1    -1     1
     1     1     1    -1
```

### Example 2

Suppose now we need to study the effects of eight factors. A full factorial would require 256 runs. By clever choice of generators, we can find a sixteen-run design that can estimate those eight effects with no confounding from two-factor interactions.

```
[x,c] = fracfact('a b c d abc acd abd bcd');
c(1:10,:)

ans =

    'Term'       'Generator'       'Confounding'
    'X1'         'a'               'X1'
    'X2'         'b'               'X2'
    'X3'         'c'               'X3'
    'X4'         'd'               'X4'
    'X5'         'abc'             'X5'
    'X6'         'acd'             'X6'
    'X7'         'abd'             'X7'
    'X8'         'bcd'             'X8'
    'X1*X2'      'ab'              'X1*X2 + X3*X5 + X4*X7 + X6*X8'
```

This confounding pattern shows that the main effects are not confounded with two-factor interactions. The final row shown reveals that a group of four two-factor interactions is confounded. Other choices of generators would not have the same desirable property.

```
[x,c] = fracfact('a b c d ab cd ad bc');
c(1:10,:)
```

```
ans =

    'Term'      'Generator'    'Confounding'
    'X1'        'a'            'X1 + X2*X5 + X4*X7'
    'X2'        'b'            'X2 + X1*X5 + X3*X8'
    'X3'        'c'            'X3 + X2*X8 + X4*X6'
    'X4'        'd'            'X4 + X1*X7 + X3*X6'
    'X5'        'ab'           'X5 + X1*X2'
    'X6'        'cd'           'X6 + X3*X4'
    'X7'        'ad'           'X7 + X1*X4'
    'X8'        'bc'           'X8 + X2*X3'
    'X1*X2'     'ab'           'X5 + X1*X2'
```

Here all the main effects are confounded with one or more two-factor interactions.

**References**    Box, G. A. F., W. G. Hunter, and J. S. Hunter (1978), *Statistics for Experimenters*, Wiley, New York.

**See Also**    ff2n, fullfact, hadamard

# friedman

**Purpose**          Friedman's nonparametric two-way Analysis of Variance (ANOVA).

**Syntax**           p = friedman(X, reps)
                     p = friedman(X, reps, '*displayopt*')
                     [p, table] = friedman(...)
                     [p, table, stats] = friedman(...)

**Description**      p = friedman(X, reps) performs the nonparametric Friedman's test to
                     compare the means of the columns of X. Friedman's test is similar to classical
                     two-way ANOVA, but it tests only for column effects after adjusting for possible
                     row effects. It does not test for row effects or interaction effects. Friedman's test
                     is appropriate when columns represent treatments that are under study, and
                     rows represent nuisance effects (blocks) that need to be taken into account but
                     are not of any interest.

                     The different columns represent changes in factor A. The different rows
                     represent changes in the blocking factor B. If there is more than one
                     observation for each combination of factors, input reps indicates the number of
                     replicates in each "cell," which must be constant.

                     The matrix below illustrates the format for a set-up where column factor A has
                     three levels, row factor B has two levels, and there are two replicates (reps=2).
                     The subscripts indicate row, column, and replicate, respectively.

$$\begin{bmatrix} x_{111} & x_{121} & x_{131} \\ x_{112} & x_{122} & x_{132} \\ x_{211} & x_{221} & x_{231} \\ x_{212} & x_{222} & x_{232} \end{bmatrix}$$

                     Friedman's test assumes a model of the form

$$x_{ijk} = \mu + \alpha_i + \beta_j + \varepsilon_{ijk}$$

                     where $\mu$ is an overall location parameter, $\alpha_i$ represents the column effect, $\beta_j$
                     represents the row effect, and $\varepsilon_{ijk}$ represents the error. This test ranks the
                     data within each level of B, and tests for a difference across levels of A. The p
                     that friedman returns is the p-value for the null hypothesis that $\alpha_i = 0$. If the
                     p-value is near zero, this casts doubt on the null hypothesis. A sufficiently

small p-value suggests that at least one column-sample mean is significantly different than the other column-sample means; i.e., there is a main effect due to factor A. The choice of a limit for the p-value to determine whether a result is "statistically significant" is left to the researcher. It is common to declare a result significant if the p-value is less than 0.05 or 0.01.

friedman also displays a figure showing an ANOVA table, which divides the variability of the ranks into two or three parts:

- The variability due to the differences among the column means
- The variability due to the interaction between rows and columns (if reps is greater than its default value of 1)
- The remaining variability not explained by any systematic source

The ANOVA table has six columns:

- The first shows the source of the variability.
- The second shows the Sum of Squares (SS) due to each source.
- The third shows the degrees of freedom (df) associated with each source.
- The fourth shows the Mean Squares (MS), which is the ratio SS/df.
- The fifth shows Friedman's chi-square statistic.
- The sixth shows the p-value for the chi-square statistic.

p = friedman(X, reps, '*displayopt*') enables the ANOVA table display when '*displayopt*' is 'on' (default) and suppresses the display when '*displayopt*' is 'off'.

[p, table] = friedman(...) returns the ANOVA table (including column and row labels) in cell array table. (You can copy a text version of the ANOVA table to the clipboard by selecting **Copy Text** from the **Edit** menu.

[p, table, stats] = friedman(...) returns a stats structure that you can use to perform a follow-up multiple comparison test. The friedman test evaluates the hypothesis that the column effects are all the same against the alternative that they are not all the same. Sometimes it is preferable to perform a test to determine which pairs of column effects are significantly different, and which are not. You can use the multcompare function to perform such tests by supplying the stats structure as input.

# friedman

**Examples**    Let's repeat the example from the anova2 function, this time applying
Friedman's test. Recall that the data below come from a study of popcorn
brands and popper type (Hogg 1987). The columns of the matrix popcorn are
brands (Gourmet, National, and Generic). The rows are popper type (Oil and
Air). The study popped a batch of each brand three times with each popper. The
values are the yield in cups of popped popcorn.

```
load popcorn
popcorn

popcorn =

    5.5000    4.5000    3.5000
    5.5000    4.5000    4.0000
    6.0000    4.0000    3.0000
    6.5000    5.0000    4.0000
    7.0000    5.5000    5.0000
    7.0000    5.0000    4.5000

p = friedman(popcorn, 3)
p =
    0.0010
```
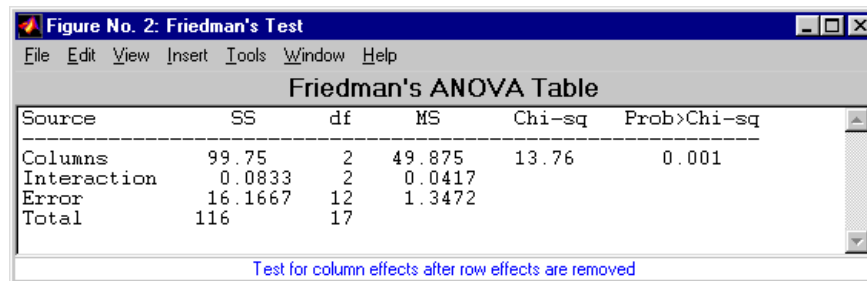


The small p-value of 0.001 indicates the popcorn brand affects the yield of
popcorn. This is consistent with the results from anova2.

We could also test popper type by permuting the popcorn array as described on
"Friedman's Test" on page 1-97 and repeating the test.

**References**     Hogg, R. V. and J. Ledolter. *Engineering Statistics.* MacMillan Publishing Company, 1987.

Hollander, M. and D. A. Wolfe. *Nonparametric Statistical Methods.* Wiley, 1973.

**See Also**     anova2, multcompare

# frnd

| Purpose | Random numbers from the F distribution. |
|---|---|

**Syntax**

R = frnd(V1, V2)
R = frnd(V1, V2, m)
R = frnd(V1, V2, m, n)

**Description**

R = frnd(V1, V2) generates random numbers from the F distribution with numerator degrees of freedom V1 and denominator degrees of freedom V2. Vector or matrix inputs for V1 and V2 must have the same size, which is also the size of R. A scalar input for V1 or V2 is expanded to a constant matrix with the same dimensions as the other input.

R = frnd(V1, V2, m) generates random numbers from the F distribution with parameters V1 and V2, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = frnd(V1, V2, m, n) generates random numbers from the F distribution with parameters V1 and V2, where scalars m and n are the row and column dimensions of R.

**Examples**

```
n1 = frnd(1:6, 1:6)

n1 =
    0.0022    0.3121    3.0528    0.3189    0.2715    0.9539

n2 = frnd(2, 2, [2 3])

n2 =
    0.3186      0.9727    3.0268
    0.2052    148.5816    0.2191

n3 = frnd([1 2 3; 4 5 6], 1, 2, 3)

n3 =
    0.6233    0.2322    31.5458
    2.5848    0.2121     4.4955
```

**See Also**   fcdf, finv, fpdf, fstat

**Purpose**          Mean and variance for the F distribution.

**Syntax**           [M,V] = fstat(V1,V2)

**Description**      [M,V] = fstat(V1,V2) returns the mean and variance for the F distribution
                     with parameters specified by V1 and V2. Vector or matrix inputs for V1 and V2
                     must have the same size, which is also the size of M and V. A scalar input for V1
                     or V2 is expanded to a constant matrix with the same dimensions as the other
                     input.

                     The mean of the F distribution for values of $v_2$ greater than 2 is

$$\frac{v_2}{v_2-2}$$

                     The variance of the F distribution for values of $v_2$ greater than 4 is

$$\frac{2v_2^2(v_1+v_2-2)}{v_1(v_2-2)^2(v_2-4)}$$

                     The mean of the F distribution is undefined if $v_2$ is less than 3. The variance is
                     undefined for $v_2$ less than 5.

**Examples**         fstat returns NaN when the mean and variance are undefined.

                         [m,v] = fstat(1:5,1:5)

                         m =
                             NaN       NaN     3.0000    2.0000    1.6667

                         v =
                             NaN       NaN       NaN       NaN     8.8889

**See Also**         fcdf, finv, frnd, frnd

# fsurfht

| | |
|---|---|
| **Purpose** | Interactive contour plot of a function. |
| **Syntax** | fsurfht('fun', xlims, ylims)<br>fsurfht('fun', xlims, ylims, p1, p2, p3, p4, p5) |
| **Description** | fsurfht('fun', xlims, ylims) is an interactive contour plot of the function specified by the text variable fun. The *x*-axis limits are specified by xlims in the form [xmin xmax], and the *y*-axis limits are specified by ylims in the form [ymin ymax].<br><br>fsurfht('fun', xlims, ylims, p1, p2, p3, p4, p5) allows for five optional parameters that you can supply to the function fun.<br><br>The intersection of the vertical and horizontal reference lines on the plot defines the current *x*-value and *y*-value. You can drag these reference lines and watch the calculated *z*-values (at the top of the plot) update simultaneously. Alternatively, you can type the *x*-value and *y*-value into editable text fields on the *x*-axis and *y*-axis. |
| **Example** | Plot the Gaussian likelihood function for the gas.mat data.<br><br>`load gas`<br><br>Create a function containing the following commands, and name it gauslike.m. |

```
function z = gauslike(mu, sigma, p1)
n = length(p1);
z = ones(size(mu));
for i = 1:n
z = z .* (normpdf(p1(i), mu, sigma));
end
```

The gauslike function calls normpdf, treating the data sample as fixed and the parameters μ and σ as variables. Assume that the gas prices are normally distributed, and plot the likelihood surface of the sample.

```
fsurfht('gauslike', [112 118], [3 5], price1)
```
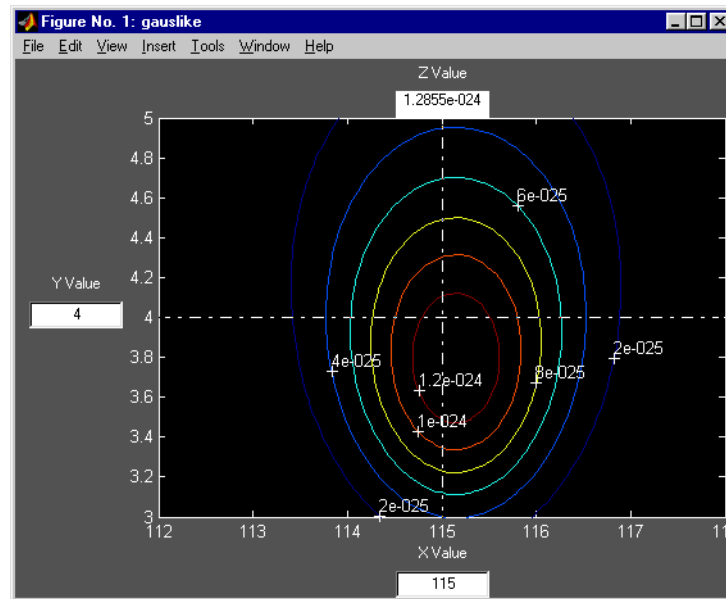
The sample mean is the *x*-value at the maximum, but the sample standard deviation is *not* the *y*-value at the maximum.

```
mumax = mean(price1)

mumax =

    115.1500

sigmamax = std(price1)*sqrt(19/20)

sigmamax =

    3.7719
```

# fullfact

**Purpose**        Full-factorial experimental design.

**Syntax**         design = fullfact(levels)

**Description**    design = fullfact(levels) give the factor settings for a full factorial design. Each element in the vector levels specifies the number of unique values in the corresponding column of design.

For example, if the first element of levels is 3, then the first column of design contains only integers from 1 to 3.

**Example**        If levels = [2 4], fullfact generates an eight-run design with two levels in the first column and four in the second column.

```
d = fullfact([2 4])

d =
    1    1
    2    1
    1    2
    2    2
    1    3
    2    3
    1    4
    2    4
```

**See Also**       ff2n, dcovary, daugment, cordexch

**Purpose**        Gamma cumulative distribution function (cdf).

**Syntax**         P = gamcdf(X, A, B)

**Description**    gamcdf(X, A, B) computes the gamma cdf at each of the values in X using the corresponding parameters in A and B. Vector or matrix inputs for X, A, and B must all be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in A and B must be positive.

The gamma cdf is

$$p = F(x|a, b) = \frac{1}{b^a \Gamma(a)} \int_0^x t^{a-1} e^{-\frac{t}{b}} dt$$

The result, $p$, is the probability that a single observation from a gamma distribution with parameters $a$ and $b$ will fall in the interval [0 $x$].

gammainc is the gamma distribution with $b$ fixed at 1.

**Examples**      a = 1:6;
                  b = 5:10;
                  prob = gamcdf(a.*b, a, b)

                  prob =

                      0.6321    0.5940    0.5768    0.5665    0.5595    0.5543

The mean of the gamma distribution is the product of the parameters, *ab*. In this example, the mean approaches the median as it increases (i.e., the distribution becomes more symmetric).

**See Also**      cdf, gamfit, gaminv, gamlike, gampdf, gamrnd, gamstat

# gamfit

**Purpose**            Parameter estimates and confidence intervals for gamma distributed data.

**Syntax**              phat = gamfit(x)
[phat, pci] = gamfit(x)
[phat, pci] = gamfit(x, alpha)

**Description**     phat = gamfit(x) returns the maximum likelihood estimates (MLEs) for the parameters of the gamma distribution given the data in vector x.

[phat, pci] = gamfit(x) returns MLEs and 95% percent confidence intervals. The first row of pci is the lower bound of the confidence intervals; the last row is the upper bound.

[phat, pci] = gamfit(x, alpha) returns 100(1-alpha)% confidence intervals. For example, alpha = 0.01 yields 99% confidence intervals.

**Example**       Note that the 95% confidence intervals in the example below bracket the true parameter values of 2 and 4.

```
a = 2;  b = 4;
r = gamrnd(a, b, 100, 1);
[p, ci] = gamfit(r)

p =
    2.1990    3.7426

ci =
    1.6840    2.8298
    2.7141    4.6554
```

**Reference**     Hahn, G. J. and S.S. Shapiro. *Statistical Models in Engineering.* John Wiley & Sons, New York. 1994. p. 88.

**See Also**       gamcdf, gaminv, gamlike, gampdf, gamrnd, gamstat, betafit, binofit, expfit, normfit, poissfit, unifit, weibfit

# gaminv

**Purpose**     Inverse of the gamma cumulative distribution function (cdf).

**Syntax**      X = gaminv(P, A, B)

**Description**  X = gaminv(P, A, B) computes the inverse of the gamma cdf with parameters A and B for the corresponding probabilities in P. Vector or matrix inputs for P, A, and B must all be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in A and B must all be positive, and the values in P must lie on the interval [0 1].

The gamma inverse function in terms of the gamma cdf is

$$x = F^{-1}(p|a,b) = \{x : F(x|a,b) = p\}$$

where

$$p = F(x|a, b) = \frac{1}{b^a \Gamma(a)} \int_0^x t^{a-1} e^{-\frac{t}{b}} dt$$

**Algorithm**   There is no known analytical solution to the integral equation above. gaminv uses an iterative approach (Newton's method) to converge on the solution.

**Examples**    This example shows the relationship between the gamma cdf and its inverse function.

```
a = 1:5;
b = 6:10;
x = gaminv(gamcdf(1:5, a, b), a, b)

x =
     1.0000     2.0000     3.0000     4.0000     5.0000
```

**See Also**    gamcdf, gamfit, gamlike, gampdf, gamrnd, gamstat, icdf

# gamlike

| | |
|---|---|
| **Purpose** | Negative gamma log-likelihood function. |
| **Syntax** | logL = gamlike(params, data)<br>[logL, avar] = gamlike(params, data) |
| **Description** | logL = gamlike(params, data) returns the negative of the gamma log-likelihood function for the parameters, params, given data. The length of output vector logL is the length of vector data.<br><br>[logL, avar] = gamlike(params, data) also returns avar, which is the asymptotic variance-covariance matrix of the parameter estimates when the values in params are the maximum likelihood estimates. avar is the inverse of Fisher's information matrix. The diagonal elements of avar are the asymptotic variances of their respective parameters.<br><br>gamlike is a utility function for maximum likelihood estimation of the gamma distribution. Since gamlike returns the negative gamma log-likelihood function, minimizing gamlike using fminsearch is the same as maximizing the likelihood. |
| **Example** | This example continues the example for gamfit.<br><br>`a = 2; b = 3;`<br>`r = gamrnd(a, b, 100, 1);`<br>`[logL, info] = gamlike([2.1990 2.8069], r)`<br><br>`logL =`<br><br>`  267.5585`<br><br>`info =`<br><br>`    0.0690    -0.0790`<br>`   -0.0790     0.1220` |
| **See Also** | betalike, gamcdf, gamfit, gaminv, gampdf, gamrnd, gamstat, mle, weiblike |

**Purpose**        Gamma probability density function (pdf).

**Syntax**        Y = gampdf(X, A, B)

**Description**   gampdf(X, A, B) computes the gamma pdf at each of the values in X using the corresponding parameters in A and B. Vector or matrix inputs for X, A, and B must all be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in A and B must all be positive, and the values in X must lie on the interval [0 ∞).

The gamma pdf is

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

The gamma probability density function is useful in reliability models of lifetimes. The gamma distribution is more flexible than the exponential distribution in that the probability of a product surviving an additional period may depend on its current age. The exponential and $\chi^2$ functions are special cases of the gamma function.

**Examples**     The exponential distribution is a special case of the gamma distribution.

```
mu = 1:5;
y = gampdf(1, 1, mu)

y =
    0.3679    0.3033    0.2388    0.1947    0.1637

y1 = exppdf(1, mu)

y1 =
    0.3679    0.3033    0.2388    0.1947    0.1637
```

**See Also**     gamcdf, gamfit, gaminv, gamlike, gamrnd, gamstat, pdf

# gamrnd

| | |
|---|---|
| **Purpose** | Random numbers from the gamma distribution. |

**Syntax**

R = gamrnd(A, B)
R = gamrnd(A, B, m)
R = gamrnd(A, B, m, n)

**Description**

R = gamrnd(A, B) generates gamma random numbers with parameters A and B. Vector or matrix inputs for A and B must have the same size, which is also the size of R. A scalar input for A or B is expanded to a constant matrix with the same dimensions as the other input.

R = gamrnd(A, B, m) generates gamma random numbers with parameters A and B, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = gamrnd(A, B, m, n) generates gamma random numbers with parameters A and B, where scalars m and n are the row and column dimensions of R.

**Examples**

n1 = gamrnd(1: 5, 6: 10)

n1 =
    9. 1132    12. 8431    24. 8025    38. 5960    106. 4164

n2 = gamrnd(5, 10, [1  5])

n2 =
    30. 9486    33. 5667    33. 6837    55. 2014    46. 8265

n3 = gamrnd(2: 6, 3, 1, 5)

n3 =
    12. 8715    11. 3068    3. 0982    15. 6012    21. 6739

**See Also**

gamcdf, gamfit, gaminv, gamlike, gampdf, gamstat

**Purpose**        Mean and variance for the gamma distribution.

**Syntax**         [M, V] = gamstat(A, B)

**Description**     [M, V] = gamstat(A, B) returns the mean and variance for the gamma
distribution with parameters specified by A and B. Vector or matrix inputs for
A and B must have the same size, which is also the size of M and V. A scalar input
for A or B is expanded to a constant matrix with the same dimensions as the
other input.

The mean of the gamma distribution with parameters *a* and *b* is *ab*. The
variance is $ab^2$.

**Examples**       [m, v] = gamstat(1: 5, 1: 5)

m =
        1       4       9      16      25

v =
        1       8      27      64     125

[m, v] = gamstat(1: 5, 1. /(1: 5))

m =
        1       1       1       1       1

v =
    1. 0000    0. 5000    0. 3333    0. 2500    0. 2000

**See Also**       gamcdf, gamfit, gaminv, gamlike, gampdf, gamrnd

# geocdf

**Purpose**        Geometric cumulative distribution function (cdf).

**Syntax**         Y = geocdf(X, P)

**Description**    geocdf(X, P) computes the geometric cdf at each of the values in X using the
corresponding probabilities in P. Vector or matrix inputs for X and P must be
the same size. A scalar input is expanded to a constant matrix with the same
dimensions as the other input. The parameters in P must lie on the interval
[0 1].

The geometric cdf is

$$y = F(x|p) = \sum_{i=0}^{floor(x)} pq^i$$

where $q = 1 - p$.

The result, $y$, is the probability of observing up to $x$ trials before a success, when
the probability of success in any given trial is $p$.

**Examples**       Suppose you toss a fair coin repeatedly. If the coin lands face up (heads), that
is a success. What is the probability of observing three or fewer tails before
getting a heads?

    p = geocdf(3, 0. 5)

    p =
        0. 9375

**See Also**       cdf, geoinv, geopdf, geornd, geostat

**Purpose**    Inverse of the geometric cumulative distribution function (cdf).

**Syntax**    X = geoinv(Y, P)

**Description**    X = geoinv(Y, P) returns the smallest positive integer X such that the geometric cdf evaluated at X is equal to or exceeds Y. You can think of Y as the probability of observing X successes in a row in independent trials where P is the probability of success in each trial.

Vector or matrix inputs for P and Y must have the same size, which is also the size of X. A scalar input for P and Y is expanded to a constant matrix with the same dimensions as the other input. The values in P and Y must lie on the interval [0 1].

**Examples**    The probability of correctly guessing the result of 10 coin tosses in a row is less than 0.001 (unless the coin is not fair).

    psychic = geoinv(0.999, 0.5)

    psychic =

        9

The example below shows the inverse method for generating random numbers from the geometric distribution.

    rndgeo = geoinv(rand(2, 5), 0.5)

    rndgeo =

        0    1    3    1    0
        0    1    0    2    0

**See Also**    geocdf, geopdf, geornd, geostat, icdf

# geomean

| | |
|---|---|
| **Purpose** | Geometric mean of a sample. |

**Syntax**        m = geomean(X)

**Description**   geomean calculates the geometric mean of a sample. For vectors, geomean(x) is the geometric mean of the elements in x. For matrices, geomean(X) is a row vector containing the geometric means of each column.

The geometric mean is

$$m = \left[ \prod_{i=1}^{n} x_i \right]^{\frac{1}{n}}$$

**Examples**     The sample average is greater than or equal to the geometric mean.

```
x = exprnd(1, 10, 6);
geometric = geomean(x)

geometric =

    0.7466    0.6061    0.6038    0.2569    0.7539    0.3478

average = mean(x)

average =

    1.3509    1.1583    0.9741    0.5319    1.0088    0.8122
```

**See Also**     mean, median, harmmean, trimmean

**Purpose**        Geometric probability density function (pdf).

**Syntax**         Y = geopdf(X, P)

**Description**    geocdf(X, P) computes the geometric pdf at each of the values in X using the corresponding probabilities in P. Vector or matrix inputs for X and P must be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other input. The parameters in P must lie on the interval [0 1].

The geometric pdf is

$$y = f(x|p) = pq^{x}I_{(0, 1, K)}(x)$$

where $q = 1 - p$.

**Examples**       Suppose you toss a fair coin repeatedly. If the coin lands face up (heads), that is a success. What is the probability of observing exactly three tails before getting a heads?

    p = geopdf(3, 0. 5)

    p =
        0. 0625

**See Also**       geocdf, geoinv, geornd, geostat, pdf

# geornd

| | |
|---|---|
| **Purpose** | Random numbers from the geometric distribution. |
| **Syntax** | R = geornd(P)<br>R = geornd(P, m)<br>R = geornd(P, m, n) |

**Description**   The geometric distribution is useful when you want to model the number of successive failures preceding a success, where the probability of success in any given trial is the constant P.

R = geornd(P) generates geometric random numbers with probability parameter P. The size of R is the size of P.

R = geornd(P, m) generates geometric random numbers with probability parameter P, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = geornd(P, m, n) generates geometric random numbers with probability parameter P, where scalars m and n are the row and column dimensions of R.

The parameters in P must lie on the interval [0 1].

**Examples**
```
r1 = geornd(1 ./ 2.^(1:6))

r1 =
     2    10     2     5     2    60

r2 = geornd(0.01, [1 5])

r2 =
    65    18   334   291    63

r3 = geornd(0.5, 1, 6)

r3 =
     0     7     1     3     1     0
```

**See Also**   geocdf, geoinv, geopdf, geostat

**Purpose**     Mean and variance for the geometric distribution.

**Syntax**      [M, V] = geostat(P)

**Description**  [M, V] = geostat(P) returns the mean and variance for the geometric distribution with parameters specified by P.

The mean of the geometric distribution with parameter $p$ is $q/p$, where $q = 1-p$. The variance is $q/p^2$.

**Examples**
```
[m, v] = geostat(1./(1:6))

m =
     0    1.0000    2.0000    3.0000    4.0000    5.0000

v =
     0    2.0000    6.0000   12.0000   20.0000   30.0000
```

**See Also**    geocdf, geoinv, geopdf, geornd

# gline

| | |
|---|---|
| **Purpose** | Interactively draw a line in a figure. |
| **Syntax** | gline(fig) |
| | h = gline(fig) |
| | gline |
| **Description** | gline(fig) allows you to draw a line segment in the figure fig by clicking the pointer at the two end-points. A rubber band line tracks the pointer movement. |
| | h = gline(fig) returns the handle to the line in h. |
| | gline with no input arguments draws in the current figure. |
| **See Also** | refline, gname |

**Purpose**        Demo of generalized linear models.

**Syntax**         glmdemo

**Description**     glmdemo begins a slide show demonstration of generalized linear models. The
                   slides indicate when generalized linear models are useful, how to fit
                   generalized linear models using the glmfit function, and how to make
                   predictions using the glmval function.

**See Also**       glmfit, glmval

# glmfit

| | |
|---|---|
| **Purpose** | Generalized linear model fitting. |
| **Syntax** | b = glmfit(X, Y, '*distr*') <br> b = glmfit(X, Y, '*distr*', '*link*', '*estdisp*', offset, pwts, '*const*') <br> [b, dev, stats] = glmfit(...) |
| **Description** | b = glmfit(x, y, '*distr*') fits the generalized linear model for response Y, predictor variable matrix X, and distribution '*distr*'. The following distributions are available: 'binomial', 'gamma', 'inverse gaussian', 'lognormal', 'normal' (the default), and 'poisson'. In most cases Y is a vector of response measurements, but for the binomial distribution Y is a two-column array having the measured number of counts in the first column and the number of trials (the binomial N parameter) in the second column. X is a matrix having the same number of rows as Y and containing the values of the predictor variables for each observation. The output b is a vector of coefficient estimates. This syntax uses the canonical link (see below) to relate the distribution parameter to the predictors. <br><br> b = glmfit(x, y, '*distr*', '*link*', '*estdisp*', offset, pwts, '*const*') provides additional control over the fit. The '*link*' argument specifies the relationship between the distribution parameter (μ) and the fitted linear combination of predictor variables (*xb*). In most cases '*link*' is one of the following: |

| 'link' | Meaning | Default (Canonical) Link |
|---|---|---|
| 'identity' | $\mu = xb$ | 'normal' |
| 'log' | $\log(\mu) = xb$ | 'poisson' |
| 'logit' | $\log(\mu / (1-\mu)) = xb$ | 'binomial' |
| 'probit' | $\text{norminv}(\mu) = xb$ | |
| 'comploglog' | $\log(-\log(1-\mu)) = xb$ | |
| 'logloglink' | $\log(-\log(\mu)) = xb$ | |
| 'reciprocal' | $1/\mu = xb$ | 'gamma' |
| p (a number) | $\mu^p = xb$ | 'inverse gaussian' (with *p*=-2) |

Alternatively, you can write functions to define your own custom link. You specify the link argument as a three-element cell array containing functions that define the link function, its derivative, and its inverse. For example, suppose you want to define a reciprocal square root link using inline functions. You could define the variable mylinks to use as your 'link' argument by writing:

```
FL = inline('x.^-.5')
FD = inline('-.5*x.^-1.5')
FI = inline('x.^-2')
mylinks = {FL FI FD}
```

Alternatively, you could define functions named FL, FD, and FI in their own M-files, and then specify mylinks in the form

```
mylinks = {@FL @FD @FI}
```

The 'estdisp' argument can be 'on' to estimate a dispersion parameter for the binomial or Poisson distribution, or 'off' (the default) to use the theoretical value of 1.0 for those distributions. The glmfit function always estimates dispersion parameters for other distributions.

The offset and pwts parameters can be vectors of the same length as Y, or can be omitted (or specified as an empty vector). The offset vector is a special predictor variable whose coefficient is known to be 1.0. As an example, suppose that you are modeling the number of defects on various surfaces, and you want to construct a model in which the expected number of defects is proportional to the surface area. You might use the number of defects as your response, along with the Poisson distribution, the log link function, and the log surface area as an offset.

The pwts argument is a vector of prior weights. As an example, if the response value Y(i) is the average of f(i) measurements, you could use f as a vector of prior weights.

The 'const' argument can be 'on' (the default) to estimate a constant term, or 'off' to omit the constant term. If you want the constant term, use this argument rather than specifying a column of ones in the X matrix.

[b, dev, stats] = glmfit(...) returns the additional outputs dev and stats. dev is the deviance at the solution vector. The deviance is a generalization of the residual sum of squares. It is possible to perform an analysis of deviance to

compare several models, each a subset of the other, and to test whether the model with more terms is significantly better than the model with fewer terms.

stats is a structure with the following fields:

- stats.dfe = degrees of freedom for error
- stats.s = theoretical or estimated dispersion parameter
- stats.sfit = estimated dispersion parameter
- stats.estdisp = 1 if dispersion is estimated, 0 if fixed
- stats.beta = vector of coefficient estimates (same as b)
- stats.se = vector of standard errors of the coefficient estimates b
- stats.coeffcorr = correlation matrix for b
- stats.t = t statistics for b
- stats.p = p-values for b
- stats.resid = vector of residuals
- stats.residp = vector of Pearson residuals
- stats.residd = vector of deviance residuals
- stats.resida = vector of Anscombe residuals

If you estimate a dispersion parameter for the binomial or Poisson distribution, then stats.s is set equal to stats.sfit. Also, the elements of stats.se differ by the factor stats.s from their theoretical values.

**Example**
We have data on cars weighing between 2100 and 4300 pounds. For each car weight we have the total number of cars of that weight, and the number that can be considered to get "poor mileage" according to some test. For example, 8 out of 21 cars weighing 3100 pounds get poor mileage according to a measurement of the miles they can travel on a gallon of gasoline.

```
w = (2100: 200: 4300)';
poor = [1 2 0 3 8 8 14 17 19 15 17 21]';
total = [48 42 31 34 31 21 23 23 21 16 17 21]';
```

We can compare several fits to these data. First, let's try fitting logit and probit models:

```
[bl, dl, sl] = glmfit(w, [poor total], 'binomial');
[bp, dp, sp] = glmfit(w, [poor total], 'binomial', 'probit');
```

```
dl
dl =
    6.4842

dp
dp =
    7.5693
```

The deviance for the logit model is smaller than for the probit model. Although this is not a formal test, it leads us to prefer the logit model.

We can do a formal test comparing two logit models. We already fit one model using w as a linear predictor. Let's fit another logit model using both linear and squared terms in w. If there is no true effect for the squared term, the difference in their deviances should be small compared with a chi-square distribution having one degree of freedom.

```
[b2,d2,s2] = glmfit([w w.^2],[poor total],'binomial')

dl-d2

ans =
    0.7027

chi2cdf(dl-d2,1)

ans =
    0.5981
```

A difference of 0.7072 is not at all unusual for a chi-square distribution with one degree of freedom, so the quadratic model does not give a significantly better fit than the simpler linear model.

The following are the coefficient estimates, their standard errors, t-statistics, and p-values for the linear model:

```
[b sl.se sl.t sl.p]

ans =

  -13.3801    1.3940   -9.5986    0.0000
    0.0042    0.0004    9.4474    0.0000
```

This shows that we cannot simplify the model any further. Both the intercept and slope coefficients are significantly different from 0, as indicated by p-values that are 0.0000 to four decimal places.

**See Also**    glmval, glmdemo, nlinfit, regress, regstats

**References**    Dobson, A. J. *An Introduction to Generalized Linear Models*. 1990, CRC Press.

MuCullagh, P. and J. A. Nelder. *Generalized Linear Models*. 2nd edition, 1990, Chapman and Hall.

**Purpose**          Compute predictions for generalized linear model.

**Syntax**           yfit = glmval(b, X, '*link*')
                     [yfit, dlo, dhi] = glmval(b, X, '*link*', stats, clev)
                     [yfit, dlo, dhi] = glmval(b, X, '*link*', stats, clev, N, offset, '*const*')

**Description**      yfit = glmval(b, X, '*link*') computes the predicted distribution parameters
                     for observations with predictor values X using the coefficient vector b and link
                     function '*link*'. Typically, b is a vector of coefficient estimates computed by
                     the glmfit function. The value of '*link*' must be the same as that used in
                     glmfit. The result yfit is the value of the inverse of the link function at the
                     linear combination X*b.

                     [yfit, dlo, dhi] = glmval(b, X, '*link*', stats, clev) returns confidence
                     bounds for the predicted values when you supply the stats structure returned
                     from glmfit, and optionally specify a confidence level as the clev argument.
                     (The default confidence level is 0.95 for 95% confidence.) The interval
                     [yfit-dlo, yfit+dhi] is a confidence bound for the true parameter value at
                     the specified X values.

                     [yhat, dlo, dhi] = glmval(beta, X, '*link*', stats, clev, N, offset, '*const*')
                     specifies three additional arguments that may be needed if you used certain
                     arguments to glmfit. If you fit a binomial distribution using glmfit, specify N
                     as the value of the binomial N parameter for the predictions. If you included an
                     offset variable, specify offset as the new value of this variable. Use the same
                     '*const*' value ('on' or 'off') that you used with glmfit.

**Example**          Let's model the number of cars with poor gasoline mileage using the binomial
                     distribution. First we use the binomial distribution with the default logit link
                     to model the probability of having poor mileage as a function of the weight and
                     squared weight of the cars. Then we compute a vector wnew of new car weights
                     at which we want to make predictions. Next we compute the expected number
                     of cars, out of a total of 30 cars of each weight, that would have poor mileage.
                     Finally we graph the predicted values and 95% confidence bounds as a function
                     of weight.

```
w = [2100 2300 2500 2700 2900 3100 3300 3500 3700 3900 4100 4300]';
poor = [1 2 0 3 8 8 14 17 19 15 17 21]';
total = [48 42 31 34 31 21 23 23 21 16 17 21]';
```

```
[b2, d2, s2] = glmfit([w w.^2], [poor total], 'binomial')
wnew = (3000: 100: 4000)';
[yfit, dlo, dhi] = glmval(b2, [wnew wnew.^2], 'logit', s2, 0.95, 30)
errorbar(wnew, yfit, dlo, dhi);
```



**See Also**    glmfit, glmdemo

**Purpose**       Label plotted points with their case names or case number.

**Syntax**        gname('cases')
                  gname
                  h = gname('cases', line_handle)

**Description**   gname('cases') displays a figure window, displays cross-hairs, and waits for
                  a mouse button or keyboard key to be pressed. Position the cross-hair with the
                  mouse and click once near each point to label that point. Input 'cases' is a
                  string matrix with each row the case name of a data point. You can also click
                  and drag a selection rectangle to label all points within the rectangle. When
                  you are done, press the **Enter** or **Escape** key.

                  gname with no arguments labels each case with its case number.

                  h = gname('cases', line_handle) returns a vector of handles to the text
                  objects on the plot. Use the scalar line_handle to identify the correct line if
                  there is more than one line object on the plot.

                  You can use gname to label plots created by the plot, scatter, gscatter,
                  plotmatrix, and gplotmatrix functions.

**Example**       Let's use the city ratings data sets to find out which cities are the best and
                  worst for education and the arts. We create a graph, call the gname function,
                  and click on the points at the extreme left and at the top.

```
load cities
education = ratings(:, 6);
arts = ratings(:, 7);
plot(education, arts, '+')
gname(names)
```
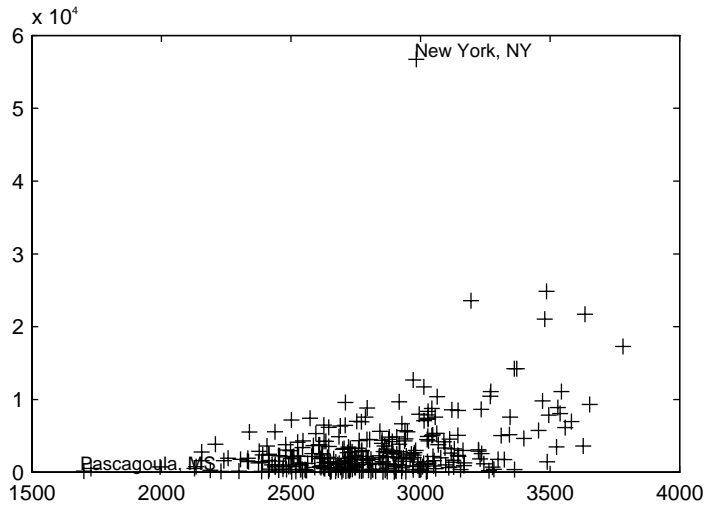
**See Also**     gplotmatrix, gscatter, gtext, plot, plotmatrix, scatter

**Purpose**            Plot matrix of scatter plots by group.

**Syntax**             gplotmatrix(x, y, g)
                       gplotmatrix(x, y, g, '*clr*', '*sym*', siz)
                       gplotmatrix(x, y, g, '*clr*', '*sym*', siz, '*doleg*')
                       gplotmatrix(x, y, g, '*clr*', '*sym*', siz, '*doleg*', '*dispopt*')
                       gplotmatrix(x, y, g, '*clr*', '*sym*', siz, '*doleg*', '*dispopt*', 'xnam', 'ynam')
                       [h, ax, bigax] = gplotmatrix(...)

**Description**        gplotmatrix(x, y, g) creates a matrix of scatter plots. Each individual set of
                       axes in the resulting figure contains a scatter plot of a column of x against a
                       column of y. All plots are grouped by the grouping variable g.

                       x and y are matrices with the same number of rows. If x has p columns and y
                       has q columns, the figure contains a p-by-q matrix of scatter plots. If you omit
                       y or specify it as the empty matrix, [], gplotmatrix creates a square matrix of
                       scatter plots of columns of x against each other.

                       g is a grouping variable that can be a vector, string array, or cell array of
                       strings. g must have the same number of rows as x and y. Points with the same
                       value of g are placed in the same group, and appear on the graph with the same
                       marker and color. Alternatively, g can be a cell array containing several
                       grouping variables (such as {G1 G2 G3}); in that case, observations are in the
                       same group if they have common values of all grouping variables.

                       gplotmatrix(x, y, g, '*clr*', '*sym*', siz) specifies the color, marker type, and
                       size for each group. clr is a string array of colors recognized by the plot
                       function. The default is '*clr*' = 'bgrcmyk'. '*sym*' is a string array of symbols
                       recognized by the plot command, with the default value '.'. siz is a vector of
                       sizes, with the default determined by the 'defaultlinemarkersize' property.
                       If you do not specify enough values for all groups, gplotmatrix cycles through
                       the specified values as needed.

                       gplotmatrix(x, y, g, '*clr*', '*sym*', siz, '*doleg*') controls whether a legend is
                       displayed on the graph ('*doleg*' = 'on', the default) or not ('*doleg*' = 'off').

# gplotmatrix

gplotmatrix(x, y, g, 'clr', 'sym', siz, 'doleg', 'dispopt') controls what appears along the diagonal of a plot matrix of x versus x. Allowable values are 'none' to leave the diagonals blank, 'hist' (the default) to plot histograms, or 'variable' to write the variable names.

gplotmatrix(x, y, g, 'clr', 'sym', siz, 'doleg', 'dispopt', 'xnam', 'ynam') specifies the names of the columns in the x and y arrays. These names are used to label the *x*- and *y*-axes. 'xnam' and 'ynam' must be character arrays with one row for each column of x and y, respectively.

[h, ax, bigax] = gplotmatrix(...) returns three arrays of handles. h is an array of handles to the lines on the graphs. ax is a matrix of handles to the axes of the individual plots. bigax is a handle to big (invisible) axes framing the entire plot matrix. These are left as the current axes, so a subsequent title, xlabel, or ylabel command will produce labels that are centered with respect to the entire plot matrix.

**Example**    Load the cities data. The ratings array has ratings of the cities in nine categories (category names are in the array categories). group is a code whose value is 2 for the largest cities. We can make scatter plots of the first three categories against the other four, grouped by the city size code.

```
load discrim
gplotmatrix(ratings(:, 1:3), ratings(:, 4:7), group)
```

The output figure (not shown) has an array of graphs with each city group represented by a different color. The graphs are a little easier to read if we specify colors and plotting symbols, label the axes with the rating categories, and move the legend off the graphs.

```
gplotmatrix(ratings(:, 1:3), ratings(:, 4:7), group, ...
            'br', '.o', [], 'on', '', categories(1:3, :), ...
             categories(4:7, :))
```
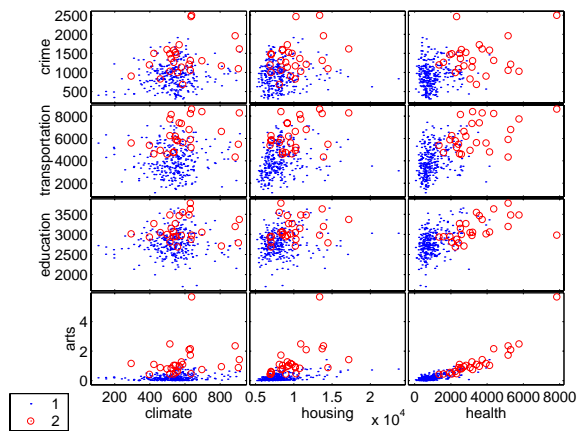
**See Also**          grpstats, gscatter, plotmatrix

# grpstats

**Purpose**        Summary statistics by group.

**Syntax**         means = grpstats(X, group)
                   [means, sem, counts, name] = grpstats(X, group)
                   grpstats(x, group, alpha)

**Description**    means = grpstats(X, group) returns the means of each column of X by group,
                   where X is a matrix of observations. group is an array that defines the grouping
                   such that two elements of X are in the same group if their corresponding group
                   values are the same. The grouping variable group can be a vector, string array,
                   or cell array of strings. It can also be a cell array containing several grouping
                   variables (such as {G1 G2 G3}); in that case observations are in the same group
                   if they have common values of all grouping variables.

                   [means, sem, counts, name] = grpstats(x, group, alpha) supplies the
                   standard error of the mean in sem, the number of elements in each group in
                   counts, and the name of each group in name. name is useful to identify and label
                   the groups when the input group values are not simple group numbers.

                   grpstats(x, group, alpha) plots 100(1-alpha)% confidence intervals around
                   each mean.

**Example**        We assign 100 observations to one of four groups. For each observation we
                   measure five quantities with *true means* from 1 to 5. grpstats allows us to
                   compute the means for each group.

```
group = unidrnd(4, 100, 1);
true_mean = 1:5;
true_mean = true_mean(ones(100, 1), :);
x = normrnd(true_mean, 1);
means = grpstats(x, group)

means =

    0.7947    2.0908    2.8969    3.6749    4.6555
    0.9377    1.7600    3.0285    3.9484    4.8169
    1.0549    2.0255    2.8793    4.0799    5.3740
    0.7107    1.9264    2.8232    3.8815    4.9689
```

**See Also**       tabulate, crosstab

**Purpose**        Scatter plot by group.

**Syntax**         gscatter(x, y, g)
                   gscatter(x, y, g, '*clr*', '*sym*', siz)
                   gscatter(x, y, g, '*clr*', '*sym*', siz, '*doleg*')
                   gscatter(x, y, g, '*clr*', '*sym*', siz, '*doleg*', 'xnam', 'ynam')
                   h = gscatter(...)

**Description**    gscatter(x, y, g) creates a scatter plot of x and y, grouped by g, where x and y
                   are vectors with the same size and g can be a vector, string array, or cell array
                   of strings. Points with the same value of g are placed in the same group, and
                   appear on the graph with the same marker and color. Alternatively, g can be a
                   cell array containing several grouping variables (such as {G1 G2 G3}); in that
                   case, observations are in the same group if they have common values of all
                   grouping variables.

                   gscatter(x, y, g, '*clr*', '*sym*', siz) specifies the color, marker type, and size
                   for each group. '*clr*' is a string array of colors recognized by the plot function.
                   The default is '*clr*' = 'bgrcmyk'. '*sym*' is a string array of symbols recognized
                   by the plot command, with the default value '.'. siz is a vector of sizes, with
                   the default determined by the 'defaultlinemarkersize' property. If you do
                   not specify enough values for all groups, gscatter cycles through the specified
                   values as needed.

                   gscatter(x, y, g, '*clr*', '*sym*', siz, '*doleg*') controls whether a legend is
                   displayed on the graph ('*doleg*' = 'on', the default) or not ('*doleg*' = 'off').

                   gscatter(x, y, g, '*clr*', '*sym*', siz, '*doleg*', 'xnam', 'ynam') specifies the
                   name to use for the *x*-axis and *y*-axis labels. If the x and y inputs are simple
                   variable names and xnam and ynam are omitted, gscatter labels the axes with
                   the variable names.

                   h = gscatter(...) returns an array of handles to the lines on the graph.

**Example**        Load the cities data and look at the relationship between the ratings for
                   climate (first column) and housing (second column) grouped by city size. We'll
                   also specify the colors and plotting symbols.

# gscatter

```
load discrim
gscatter(ratings(:,1),ratings(:,2),group,'br','xo')
```
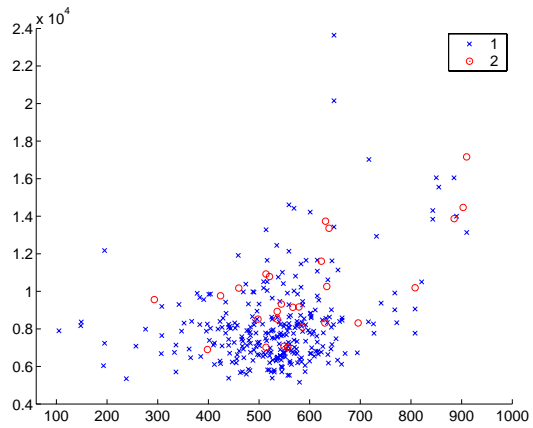


**See Also**     gplotmatrix, grpstats, scatter

**Purpose**        Harmonic mean of a sample of data.

**Syntax**         m = harmmean(X)

**Description**    m = harmmean(X) calculates the harmonic mean of a sample. For vectors,
harmmean(x) is the harmonic mean of the elements in x. For matrices,
harmmean(X) is a row vector containing the harmonic means of each column.

The harmonic mean is

$$m = \frac{n}{\sum_{i=1}^{n} \frac{1}{x_i}}$$

**Examples**      The sample average is greater than or equal to the harmonic mean.

    x = exprnd(1, 10, 6);
    harmonic = harmmean(x)

    harmonic =

        0.3382    0.3200    0.3710    0.0540    0.4936    0.0907

    average = mean(x)

    average =

        1.3509    1.1583    0.9741    0.5319    1.0088    0.8122

**See Also**      mean, median, geomean, trimmean

# hist

**Purpose**      Plot histograms.

**Syntax**       hist(y)
                 hist(y, nb)
                 hist(y, x)
                 [n, x] = hist(y, ...)

**Description**  hist(y) draws a 10-bin histogram for the data in vector y. The bins are equally spaced between the minimum and maximum values in y.

hist(y, nb) draws a histogram with nb bins.

hist(y, x) draws a histogram using the bins in the vector x.

[n, x] = hist(y, ...) do not draw graphs, but return vectors n and x containing the frequency counts and the bin locations such that bar(x, n) plots the histogram. This is useful in situations where more control is needed over the appearance of a graph, for example, to combine a histogram into a more elaborate plot statement.

The hist function is a part of the standard MATLAB language.

**Examples**     Generate bell-curve histograms from Gaussian data.

    x = -2.9: 0.1: 2.9;
    y = normrnd(0, 1, 1000, 1);
    hist(y, x)
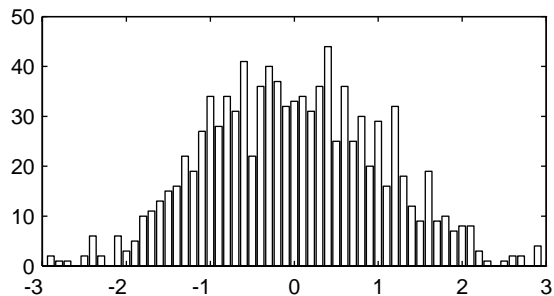
**Purpose**       Histogram with superimposed normal density.

**Syntax**        histfit(data)
                  histfit(data, nbins)
                  h = histfit(data, nbins)

**Description**   histfit(data, nbins) plots a histogram of the values in the vector data using
                  nbins bars in the histogram. With nbins is omitted, its value is set to the
                  square root of the number of elements in data.

                  h = histfit(data, nbins) returns a vector of handles to the plotted lines,
                  where h(1) is the handle to the histogram, h(2) is the handle to the density
                  curve.

**Example**       r = normrnd(10, 1, 100, 1);
                  histfit(r)
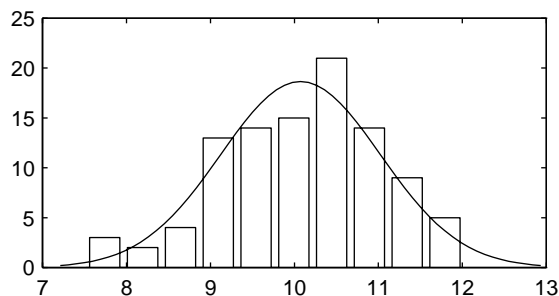


**See Also**      hist, normfit

# hougen

**Purpose**        Hougen-Watson model for reaction kinetics.

**Syntax**         yhat = hougen(beta, x)

**Description**    yhat = hougen(beta, x) returns the predicted values of the reaction rate,
yhat, as a function of the vector of parameters, beta, and the matrix of data, X.
beta must have 5 elements and X must have three columns.

hougen is a utility function for rsmdemo.

The model form is:

$$\hat{y} = \frac{\beta_1 x_2 - x_3 / \beta_5}{1 + \beta_2 x_1 + \beta_3 x_2 + \beta_4 x_3}$$

**Reference**      Bates, D., and D. Watts. *Nonlinear Regression Analysis and Its Applications.*
Wiley 1988. p. 271–272.

**See Also**       rsmdemo

**Purpose**          Hypergeometric cumulative distribution function (cdf).

**Syntax**           P = hygecdf(X, M, K, N)

**Description**      hygecdf(X, M, K, N) computes the hypergeometric cdf at each of the values in X
                     using the corresponding parameters in M, K, and N. Vector or matrix inputs for
                     X, M, K, and N must all have the same size. A scalar input is expanded to a
                     constant matrix with the same dimensions as the other inputs.

                     The hypergeometric cdf is

$$p = F(x|M, K, N) = \sum_{i=0}^{x} \frac{\binom{K}{i}\binom{M-K}{N-i}}{\binom{M}{N}}$$

                     The result, $p$, is the probability of drawing up to $x$ of a possible $K$ items in $N$
                     drawings without replacement from a group of $M$ objects.

**Examples**         Suppose you have a lot of 100 floppy disks and you know that 20 of them are
                     defective. What is the probability of drawing zero to two defective floppies if
                     you select 10 at random?

                         p = hygecdf(2, 100, 20, 10)

                         p =
                             0.6812

**See Also**         cdf, hygeinv, hygepdf, hygernd, hygestat

# hygeinv

**Purpose**      Inverse of the hypergeometric cumulative distribution function (cdf).

**Syntax**       X = hygeinv(P, M, K, N)

**Description**  hygeinv(P, M, K, N) returns the smallest integer X such that the
hypergeometric cdf evaluated at X equals or exceeds P. You can think of P as the
probability of observing X defective items in N drawings without replacement
from a group of M items where K are defective.

**Examples**    Suppose you are the Quality Assurance manager for a floppy disk
manufacturer. The production line turns out floppy disks in batches of 1,000.
You want to sample 50 disks from each batch to see if they have defects. You
want to accept 99% of the batches if there are no more than 10 defective disks
in the batch. What is the maximum number of defective disks should you allow
in your sample of 50?

    x = hygeinv(0.99, 1000, 10, 50)

    x =
          3

What is the median number of defective floppy disks in samples of 50 disks
from batches with 10 defective disks?

    x = hygeinv(0.50, 1000, 10, 50)

    x =
          0

**See Also**    hygecdf, hygepdf, hygernd, hygestat, icdf

**Purpose**      Hypergeometric probability density function (pdf).

**Syntax**       Y = hygepdf(X, M, K, N)

**Description**  Y = hygecdf(X, M, K, N) computes the hypergeometric pdf at each of the values in X using the corresponding parameters in M, K, and N. Vector or matrix inputs for X, M, K, and N must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

The parameters in M, K, and N must all be positive integers, with $N \leq M$. The values in X must be less than or equal to all the parameter values.

The hypergeometric pdf is

$$y = f(x|M, K, N) = \frac{\binom{K}{x}\binom{M-K}{N-x}}{\binom{M}{N}}$$

The result, $y$, is the probability of drawing exactly $x$ of a possible $K$ items in $n$ drawings without replacement from a group of $M$ objects.

**Examples**    Suppose you have a lot of 100 floppy disks and you know that 20 of them are defective. What is the probability of drawing 0 through 5 defective floppy disks if you select 10 at random?

    p = hygepdf(0: 5, 100, 20, 10)

    p =
        0.0951    0.2679    0.3182    0.2092    0.0841    0.0215

**See Also**    hygecdf, hygeinv, hygernd, hygestat, pdf

# hygernd

| | |
|---|---|
| **Purpose** | Random numbers from the hypergeometric distribution. |
| **Syntax** | R = hygernd(M, K, N) |
| | R = hygernd(M, K, N, mm) |
| | R = hygernd(M, K, N, mm, nn) |

**Description**  R = hygernd(M, K, N) generates hypergeometric random numbers with parameters M, K, and N. Vector or matrix inputs for M, K, and N must have the same size, which is also the size of R. A scalar input for M, K, or N is expanded to a constant matrix with the same dimensions as the other inputs.

R = hygernd(M, K, N, mm) generates hypergeometric random numbers with parameters M, K, and N, where mm is a 1-by-2 vector that contains the row and column dimensions of R.

R = hygernd(M, K, N, mm, nn) generates hypergeometric random numbers with parameters M, K, and N, where scalars mm and nn are the row and column dimensions of R.

**Examples**

    numbers = hygernd(1000, 40, 50)

    numbers =

        1

**See Also**  hygecdf, hygeinv, hygepdf, hygestat

**Purpose**      Mean and variance for the hypergeometric distribution.

**Syntax**       [MN, V] = hygestat(M, K, N)

**Description**  [MN, V] = hygestat(M, K, N) returns the mean and variance for the
hypergeometric distribution with parameters specified by M, K, and N. Vector or
matrix inputs for M, K, and N must have the same size, which is also the size of
MN and V. A scalar input for M, K, or N is expanded to a constant matrix with the
same dimensions as the other inputs.

The mean of the hypergeometric distribution with parameters *M*, *K*, and *N* is
*NK*/*M*, and the variance is

$$N\frac{K}{M}\frac{M-K}{M}\frac{M-N}{M-1}$$

**Examples**    The hypergeometric distribution approaches the binomial distribution, where
$p = K / M$ as *M* goes to infinity.

    [m, v] = hygestat(10. ^(1: 4), 10. ^(0: 3), 9)

    m =
        0. 9000      0. 9000      0. 9000      0. 9000

    v =
        0. 0900      0. 7445      0. 8035      0. 8094

    [m, v] = binostat(9, 0. 1)

    m =
        0. 9000

    v =
        0. 8100

**See Also**    hygecdf, hygeinv, hygepdf, hygernd

# icdf

**Purpose**  Inverse of a specified cumulative distribution function (icdf).

**Syntax**  X = icdf('*name*', P, A1, A2, A3)

**Description**  X = icdf('*name*', P, A1, A2, A3) returns a matrix of critical values, X, where '*name*' is a string containing the name of the distribution. P is a matrix of probabilities, and A, B, and C are matrices of distribution parameters. Depending on the distribution some of the parameters may not be necessary.

Vector or matrix inputs for P, A1, A2, and A3 must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

icdf is a utility routine allowing you to access all the inverse cdfs in the Statistics Toolbox using the name of the distribution as a parameter. See "Overview of the Distributions" on page 1-12 for the list of available distributions.

**Examples**
```
x = icdf('Normal', 0.1:0.2:0.9, 0, 1)

x =
   -1.2816   -0.5244        0    0.5244    1.2816

x = icdf('Poisson', 0.1:0.2:0.9, 1:5)

x =
      1      1      3      5      8
```

**See Also**  betainv, binoinv, cdf, chi2inv, expinv, finv, gaminv, geoinv, hygeinv, logninv, nbininv, ncfinv, nctinv, ncx2inv, norminv, pdf, poissinv, random, raylinv, tinv, unidinv, unifinv, weibinv

**Purpose**        Calculate the inconsistency coefficient of a cluster tree.

**Syntax**         Y = inconsistent(Z)
                   Y = inconsistent(Z, d)

**Description**    Y = inconsistent(Z) computes the inconsistency coefficient for each link of
                   the hierarchical cluster tree Z, where Z is an (*m*-1)-by-3 matrix generated by the
                   linkage function. The inconsistency coefficient characterizes each link in a
                   cluster tree by comparing its length with the average length of other links at
                   the same level of the hierarchy. The higher the value of this coefficient, the less
                   similar the objects connected by the link.

                   Y = inconsistent(Z, d) computes the inconsistency coefficient for each link
                   in the hierarchical cluster tree Z to depth d, where d is an integer denoting the
                   number of levels of the cluster tree that are included in the calculation. By
                   default, d=2.

                   The output, Y, is an (*m*-1)-by-4 matrix formatted as follows.

| Column | Description |
|--------|-------------|
| 1 | Mean of the lengths of all the links included in the calculation. |
| 2 | Standard deviation of all the links included in the calculation. |
| 3 | Number of links included in the calculation. |
| 4 | Inconsistency coefficient. |

For each link, $k$, the inconsistency coefficient is calculated as:

$$Y(k, 4) = (z(k, 3) - Y(k, 1)) / Y(k, 2)$$

For leaf nodes, nodes that have no further nodes under them, the inconsistency
coefficient is set to 0.

# inconsistent

**Example**
```
rand('seed', 12);
X = rand(10, 2);
Y = pdist(X);
Z = linkage(Y, 'centroid');
W = inconsistent(Z, 3)

W =

    0.0423         0    1.0000         0
    0.1406         0    1.0000         0
    0.1163    0.1047    2.0000    0.7071
    0.2101         0    1.0000         0
    0.2054    0.0886    3.0000    0.6792
    0.1742    0.1762    3.0000    0.6568
    0.2336    0.1317    4.0000    0.6408
    0.3081    0.2109    5.0000    0.7989
    0.4610    0.3728    4.0000    0.8004
```

**See Also**    cluster, cophenet, clusterdata, dendrogram, linkage, pdist, squareform

**Purpose**        Interquartile range (IQR) of a sample.

**Syntax**        y = iqr(X)

**Description**    y = iqr(X) computes the difference between the 75th and the 25th percentiles of the sample in X. The IQR is a robust estimate of the spread of the data, since changes in the upper and lower 25% of the data do not affect it.

If there are outliers in the data, then the IQR is more representative than the standard deviation as an estimate of the spread of the body of the data. The IQR is less efficient than the standard deviation as an estimate of the spread when the data is all from the normal distribution.

Multiply the IQR by 0.7413 to estimate σ (the second parameter of the normal distribution.)

**Examples**      This Monte Carlo simulation shows the relative efficiency of the IQR to the sample standard deviation for normal data.

```
x = normrnd(0, 1, 100, 100);
s = std(x);
s_IQR = 0.7413 * iqr(x);
efficiency = (norm(s - 1)./norm(s_IQR - 1)).^2

efficiency =

    0.3297
```

**See Also**      std, mad, range

# jbtest

**Purpose**         Jarque-Bera test for goodness-of-fit to a normal distribution.

**Syntax**          H = jbtest(X)
                    H = jbtest(X, alpha)
                    [H, P, JBSTAT, CV] = jbtest(X, alpha)

**Description**     H = jbtest(X) performs the Jarque-Bera test on the input data vector X and returns H, the result of the hypothesis test. The result is H=1 if we can reject the hypothesis that X has a normal distribution, or H=0 if we cannot reject that hypothesis. We reject the hypothesis if the test is significant at the 5% level.

The Jarque-Bera test evaluates the hypothesis that X has a normal distribution with unspecified mean and variance, against the alternative that X does not have a normal distribution. The test is based on the sample skewness and kurtosis of X. For a true normal distribution, the sample skewness should be near 0 and the sample kurtosis should be near 3. The Jarque-Bera test determines whether the sample skewness and kurtosis are unusually different than their expected values, as measured by a chi-square statistic.

The Jarque-Bera test is an asymptotic test, and should not be used with small samples. You may want to use lillietest in place of jbtest for small samples.

H = jbtest(X, alpha) performs the Jarque-Bera test at the 100*alpha% level rather than the 5% level, where alpha must be between 0 and 1.

[H, P, JBSTAT, CV] = jbtest(X, alpha) returns three additional outputs. P is the p-value of the test, JBSTAT is the value of the test statistic, and CV is the critical value for determining whether to reject the null hypothesis.

**Example**         We can use jbtest to determine if car weights follow a normal distribution.

```
load carsmall
[h,p,j] = jbtest(Weight)
```

```
h =
     1

p =
     0.026718

j =
       7.2448
```

With a p-value of 2.67%, we reject the hypothesis that the distribution is normal. With a log transformation, the distribution becomes closer to normal but is still significantly different at the 5% level.

```
[h,p,j] = jbtest(log(Weight))

h =
     1

p =
     0.043474

j =
       6.2712
```

See lillietest for a different test of the same hypothesis.

**Reference**     Judge, G. G., R. C. Hill, W. E. Griffiths, H. Lutkepohl, and T.-C. Lee. *Introduction to the Theory and Practice of Econometrics*. New York, Wiley.

**See Also**     hist, kstest2, lillietest

# kruskalwallis

**Purpose**    Kruskal-Wallis nonparametric one-way Analysis of Variance (ANOVA).

**Syntax**    p = kruskalwallis(X)
p = kruskalwallis(X, group)
p = kruskalwallis(X, group, '*displayopt*')
[p, table] = kruskalwallis(...)
[p, table, stats] = kruskalwallis(...)

**Description**    p = kruskalwallis(X) performs a Kruskal-Wallis test for comparing the means of columns of the *m*-by-*n* matrix X, where each column represents an independent sample containing *m* mutually independent observations. The Kruskal-Wallis test is a nonparametric version of the classical one-way ANOVA. The function returns the p-value for the null hypothesis that all samples in X are drawn from the same population (or from different populations with the same mean).

If the p-value is near zero, this casts doubt on the null hypothesis and suggests that at least one sample mean is significantly different than the other sample means. The choice of a critical p-value to determine whether the result is judged "statistically significant" is left to the researcher. It is common to declare a result significant if the p-value is less than 0.05 or 0.01.

The kruskalwallis function displays two figures. The first figure is a standard ANOVA table, calculated using the ranks of the data rather than their numeric values. Ranks are found by ordering the data from smallest to largest across all groups, and taking the numeric index of this ordering. The rank for a tied observation is equal to the average rank of all observations tied with it. For example, the following table shows the ranks for a small sample.

| X value | 1.4 | 2.7 | 1.6 | 1.6 | 3.3 | 0.9 | 1.1 |
|---------|-----|-----|-----|-----|-----|-----|-----|
| Rank | 3 | 6 | 4.5 | 4.5 | 7 | 1 | 2 |

The entries in the ANOVA table are the usual sums of squares, degrees of freedom, and other quantities calculated on the ranks. The usual F statistic is replaced by a chi-square statistic. The p-value measures the significance of the chi-square statistic.

The second figure displays box plots of each column of X (not the ranks of X).

`p = kruskalwallis(X, group)` uses the values in `group` (a character array or cell array) as labels for the box plot of the samples in X, when X is a matrix. Each row of `group` contains the label for the data in the corresponding column of X, so `group` must have length equal to the number of columns in X.

When X is a vector, `kruskalwallis` performs a Kruskal-Wallis test on the samples contained in X, as indexed by input `group` (a vector, character array, or cell array). Each element in `group` identifies the group (i.e., sample) to which the corresponding element in vector X belongs, so `group` must have the same length as X. The labels contained in `group` are also used to annotate the box plot.

It is not necessary to label samples sequentially (1, 2, 3, ...). For example, if X contains measurements taken at three different temperatures, -27°, 65°, and 110°, you could use these numbers as the sample labels in `group`. If a row of `group` contains an empty cell or empty string, that row and the corresponding observation in X are disregarded. `NaN`s in either input are similarly ignored.

`p = kruskalwallis(X, group, 'displayopt')` enables the table and box plot displays when `'displayopt'` is `'on'` (default) and suppresses the displays when `'displayopt'` is `'off'`.

`[p, table] = kruskalwallis(...)` returns the ANOVA table (including column and row labels) in cell array `table`. (You can copy a text version of the ANOVA table to the clipboard by using the **Copy Text** item on the **Edit** menu.)

`[p, table, stats] = kruskalwallis(...)` returns a `stats` structure that you can use to perform a follow-up multiple comparison test. The `kruskalwallis` test evaluates the hypothesis that all samples have the same mean, against the alternative that the means are not all the same. Sometimes it is preferable to perform a test to determine *which* pairs of means are significantly different, and which are not. You can use the `multcompare` function to perform such tests by supplying the `stats` structure as input.

### Assumptions

The Kruskal-Wallis test makes the following assumptions about the data in X:

- All sample populations have the same continuous distribution, apart from a possibly different location.
- All observations are mutually independent.

The classical one-way ANOVA test replaces the first assumption with the stronger assumption that the populations have normal distributions.

**Example**    Let's revisit the same material strength study that we used with the anova1 function, to see if the nonparametric Kruskal-Wallis procedure leads to the same conclusion. Recall we are studying the strength of beams made from three alloys:

```
strength = [82 86 79 83 84 85 86 87 74 82 78 75 76 77 79 ...
            79 77 78 82 79];

alloy = {'st','st','st','st','st','st','st','st',...
         'al1','al1','al1','al1','al1','al1',...
         'al2','al2','al2','al2','al2','al2'};
```

This time we try both classical and Kruskal-Wallis anova, omitting displays:

```
anova1(strength,alloy,'off')

ans =
  1.5264e-004

kruskalwallis(strength,alloy,'off')

ans =
    0.0018
```

Both tests find that the three alloys are significantly different, though the result is less significant according to the Kruskal-Wallis test. It is typical that when a dataset has a reasonable fit to the normal distribution, the classical ANOVA test will be more sensitive to differences between groups.

To understand when a nonparametric test may be more appropriate, let's see how the tests behave when the distribution is not normal. We can simulate this by replacing one of the values by an extreme value (an outlier).

```
strength(20)=120;
anova1(strength,alloy,'off')

ans =
    0.2501
```

```
kruskalwallis(strength, alloy, 'off')

ans =
    0.0060
```

Now the classical ANOVA test does not find a significant difference, but the nonparametric procedure does. This illustrates one of the properties of nonparametric procedures – they are often not severely affected by changes in a small portion of the data.

**Reference**     Hollander, M., and D. A. Wolfe, *Nonparametric Statistical Methods,* Wiley, 1973.

**See Also**     anova1, boxplot, multcompare

# kstest

**Purpose**     Kolmogorov-Smirnov test of the distribution of one sample.

**Syntax**      H = kstest(X)
H = kstest(X, cdf)
H = kstest(X, cdf, alpha, tail)
[H, P, KSSTAT, CV] = kstest(X, cdf, alpha, *tail*)

**Description** H = kstest(X) performs a Kolmogorov-Smirnov test to compare the values in the data vector X with a standard normal distribution (that is, a normal distribution having mean 0 and variance 1). The null hypothesis for the Kolmogorov-Smirnov test is that X has a standard normal distribution. The alternative hypothesis that X does not have that distribution. The result H is 1 if we can reject the hypothesis that X has a standard normal distribution, or 0 if we cannot reject that hypothesis. We reject the hypothesis if the test is significant at the 5% level.

For each potential value *x*, the Kolmogorov-Smirnov test compares the proportion of values less than *x* with the expected number predicted by the standard normal distribution. The kstest function uses the maximum difference over all *x* values is its test statistic. Mathematically, this can be written as

$$\max(|F(x) - G(x)|)$$

where $F(x)$ is the proportion of X values less than or equal to *x* and $G(x)$ is the standard normal cumulative distribution function evaluated at *x*.

H = kstest(X, cdf) compares the distribution of X to the hypothesized distribution defined by the two-column matrix cdf. Column one contains a set of possible *x* values, and column two contains the corresponding hypothesized cumulative distribution function values $G(x)$. If possible, you should define cdf so that column one contains the values in X. If there are values in X not found in column one of cdf, kstest will approximate $G(X)$ by interpolation. All values in X must lie in the interval between the smallest and largest values in the first column of cdf. If the second argument is empty (cdf = [ ]), kstest uses the standard normal distribution as if there were no second argument.

The Kolmogorov-Smirnov test requires that cdf be predetermined. It is not accurate if cdf is estimated from the data. To test X against a normal distribution without specifying the parameters, use lillietest instead.

H = kstest(X, cdf, alpha, *tail*) specifies the significance level alpha and a code *tail* for the type of alternative hypothesis. If *tail* = 0 (the default), kstest performs a two-sided test with the general alternative $F \neq G$. If *tail* = -1, the alternative is that $F < G$. If *tail* = 1, the alternative is $F > G$. The form of the test statistic depends on the value of *tail* as follows.

$$tail = 0: \quad \max(|F(x) - G(x)|)$$

$$tail = -1: \quad \max(G(x) - F(x))$$

$$tail = 1: \quad \max(F(x) - G(x))$$

[H, P, KSSTAT, CV] = kstest(X, cdf, alpha, tail) also returns the observed p-value P, the observed Kolmogorov-Smirnov statistic KSSTAT, and the cutoff value CV for determining if KSSTAT is significant. If the return value of CV is NaN, then kstest determined the significance calculating a p-value according to an asymptotic formula rather than by comparing KSSTAT to a critical value.

## Examples

### Example 1

Let's generate some evenly spaced numbers and perform a Kolmogorov-Smirnov test to see how well they fit to a normal distribution:

```
x = -2:1:4
x =
    -2    -1     0     1     2     3     4

[h, p, k, c] = kstest(x, [], 0.05, 0)

h =
     0
p =
     0.13632
k =
     0.41277
c =
     0.48342
```

We cannot reject the null hypothesis that the values come from a standard normal distribution. Although intuitively it seems that these evenly-spaced integers could not follow a normal distribution, this example illustrates the difficulty in testing normality in small samples.

To understand the test, it is helpful to generate an empirical cumulative
distribution plot and overlay the theoretical normal distribution.

```
xx = -3:.1:5;
cdfplot(x)
hold on
plot(xx, normcdf(xx), 'r--')
```
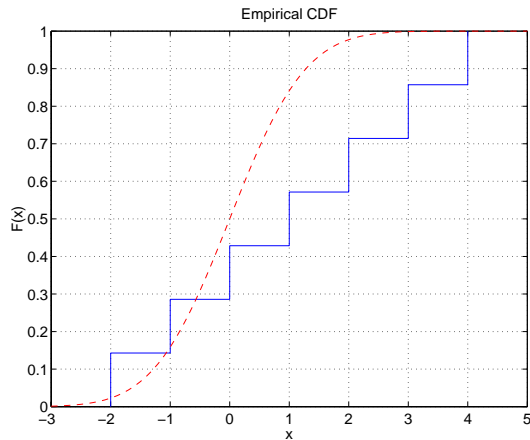


The Kolmogorov-Smirnov test statistic is the maximum difference between
these curves. It appears that this maximum of 0.41277 occurs as we approach
$x = 1.0$ from below. We can see that the empirical curve has the value 3/7 here,
and we can easily verify that the difference between the curves is 0.41277.

```
normcdf(1) - 3/7
ans =
     0.41277
```

We can also perform a one-sided test. By setting *tail* = -1 we indicate that our
alternative is $F < G$, so the test statistic counts only points where this
inequality is true.

```
[h, p, k] = kstest(x, [], .05, -1)
```

```
h =
     0

p =
     0.068181

k =
      0.41277
```

The test statistic is the same as before because in fact $F < G$ at x = 1.0. However, the p-value is smaller for the one-sided test. If we carry out the other one-sided test, we see that the test statistic changes, and is the difference between the two curves near x = -1.0.

```
[h, p, k] = kstest(x, [], 0.05, 1)

h =
     0

p =
      0.77533

k =
      0.12706

2/7 - normcdf(-1)

ans =
      0.12706
```

### Example 2

Now let's generate random numbers from a Weibull distribution, and test against that Weibull distribution and an exponential distribution.

```
x = weibrnd(1, 2, 100, 1);
kstest(x, [x weibcdf(x, 1, 2)])

ans =
     0

kstest(x, [x expcdf(x, 1)])

ans =
     1
```

# kstest

**See Also**      kstest2, lillietest

**Purpose**        Kolmogorov-Smirnov test to compare the distribution of two samples.

**Syntax**         H = kstest2(X1, X2)
                   H = kstest2(X1, X2, alpha, *tail*)
                   [H, P, KSSTAT] = kstest(X, cdf, alpha, *tail*)

**Description**    H = kstest2(X1, X2) performs a two-sample Kolmogorov-Smirnov test to
                   compare the distributions of values in the two data vectors X1 and X2. The null
                   hypothesis for this test is that X1 and X2 have the same continuous
                   distribution. The alternative hypothesis is that they have different continuous
                   distributions. The result H is 1 if we can reject the hypothesis that the
                   distributions are the same, or 0 if we cannot reject that hypothesis. We reject
                   the hypothesis if the test is significant at the 5% level.

                   For each potential value $x$, the Kolmogorov-Smirnov test compares the
                   proportion of X1 values less than $x$ with proportion of X2 values less than $x$. The
                   kstest2 function uses the maximum difference over all $x$ values is its test
                   statistic. Mathematically, this can be written as

                   $$\max(|F1(x) - F2(x)|)$$

                   where $F1(x)$ is the proportion of X1 values less than or equal to $x$ and $F2(x)$ is
                   the proportion of X2 values less than or equal to $x$.

                   H = kstest2(X1, X2, alpha, *tail*) specifies the significance level alpha and a
                   code *tail* for the type of alternative hypothesis. If *tail* = 0 (the default),
                   kstest performs a two-sided test with the general alternative $F1 \neq F2$. If
                   *tail* = -1, the alternative is that $F1 < F2$. If *tail* = 1, the alternative is
                   $F1 > F2$. The form of the test statistic depends on the value of *tail* as follows:

                   $tail$ =  0:  $\max(|F1(x) - F2(x)|)$

                   $tail$ = -1:  $\max(F2(x) - F1(x))$

                   $tail$ =  1:  $\max(F1(x) - F2(x))$

                   [H, P, KSSTAT, CV] = kstest(X, cdf, alpha, tail) also returns the observed
                   p-value P, the observed Kolmogorov-Smirnov statistic KSSTAT, and the cutoff
                   value CV for determining if KSSTAT is significant. If the return value of CV is NaN,
                   then kstest determined the significance calculating a p-value according to an
                   asymptotic formula rather than by comparing KSSTAT to a critical value.

**Examples**    Let's compare the distributions of a small evenly-spaced sample and a larger normal sample:

```
x = -1:1:5
y = randn(20,1);
[h,p,k] = kstest2(x,y)

h =
     1
p =
    0.0403
k =
    0.5714
```

The difference between their distributions is significant at the 5% level (p = 4%). To visualize the difference, we can overlay plots of the two empirical cumulative distribution functions. The Kolmogorov-Smirnov statistic is the maximum difference between these functions. After changing the color and line style of one of the two curves, we can see that the maximum difference appears to be near x = 1.9. We can also verify that the difference equals the k value that kstest2 reports:

```
cdfplot(x)
hold on
cdfplot(y)
h = findobj(gca,'type','line');
set(h(1),'linestyle',':','color','r')

1 - 3/7

ans =
    0.5714
```

Empirical CDF
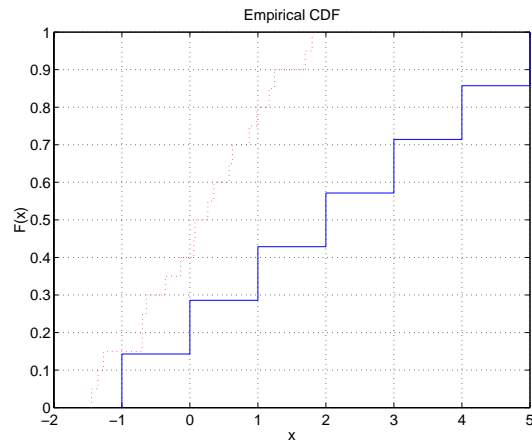
**See Also**    kstest, lillietest

# kurtosis

**Purpose**      Sample kurtosis.

**Syntax**       k = kurtosis(X)
                 k = kurtosis(X, *flag*)

**Description**  k = kurtosis(X) returns the sample kurtosis of X. For vectors, kurtosis(x) is
                 the kurtosis of the elements in the vector x. For matrices kurtosis(X) returns
                 the sample kurtosis for each column of X.

                 Kurtosis is a measure of how outlier-prone a distribution is. The kurtosis of the
                 normal distribution is 3. Distributions that are more outlier-prone than the
                 normal distribution have kurtosis greater than 3; distributions that are less
                 outlier-prone have kurtosis less than 3.

                 The kurtosis of a distribution is defined as

                 $$k = \frac{E(x-\mu)^4}{\sigma^4}$$

                 where $\mu$ is the mean of $x$, $\sigma$ is the standard deviation of $x$, and $E(t)$ represents
                 the expected value of the quantity $t$.

                 ---

                 **Note**   Some definitions of kurtosis subtract 3 from the computed value, so
                 that the normal distribution has kurtosis of 0. The kurtosis function does not
                 use this convention.

                 ---

                 k = kurtosis(X, flag) specifies whether to correct for bias (*flag* = 0) or not
                 (*flag* = 1, the default). When X represents a sample from a population, the
                 kurtosis of X is biased, that is, it will tend to differ from the population kurtosis
                 by a systematic amount that depends on the size of the sample. You can set
                 *flag* = 0 to correct for this systematic bias.

**Example**

```
X = randn([5 4])

X =
    1.1650    1.6961   -1.4462   -0.3600
    0.6268    0.0591   -0.7012   -0.1356
    0.0751    1.7971    1.2460   -1.3493
    0.3516    0.2641   -0.6390   -1.2704
   -0.6965    0.8717    0.5774    0.9846

k = kurtosis(X)

k =
    2.1658    1.2967    1.6378    1.9589
```

**See Also**    mean, moment, skewness, std, var

# leverage

| | |
|---|---|
| **Purpose** | Leverage values for a regression. |
| **Syntax** | h = leverage(data)<br>h = leverage(data, '*model*') |
| **Description** | h = leverage(data) finds the leverage of each row (point) in the matrix data for a linear additive regression model. |

h = leverage(data, '*model*') finds the leverage on a regression, using a specified model type, where '*model*' can be one of these strings:

- 'interaction' – includes constant, linear, and cross product terms
- 'quadratic' – includes interactions and squared terms
- 'purequadratic' – includes constant, linear, and squared terms

Leverage is a measure of the influence of a given observation on a regression due to its location in the space of the inputs.

**Example**    One rule of thumb is to compare the leverage to *2p/n* where *n* is the number of observations and *p* is the number of parameters in the model. For the Hald dataset this value is 0.7692.

```
load hald
h = max(leverage(ingredients, 'linear'))

h =
    0.7004
```

Since 0.7004 < 0.7692, there are no high leverage points using this rule.

**Algorithm**    [Q, R] = qr(x2fx(data, 'model'));

leverage = (sum(Q'.*Q'))'

**Reference**    Goodall, C. R. (1993). *Computation using the QR decomposition.* Handbook in Statistics, Volume 9. Statistical Computing (C. R. Rao, ed.). Amsterdam, NL Elsevier/North-Holland.

**See Also**    regstats

**Purpose**        Lilliefors test for goodness of fit to a normal distribution.

**Syntax**         H = lillietest(X)
                   H = lillietest(X, alpha)
                   [H, P, LSTAT, CV] = lillietest(X, alpha)

**Description**    H = lillietest(X) performs the Lilliefors test on the input data vector X and
                   returns H, the result of the hypothesis test. The result H is 1 if we can reject the
                   hypothesis that X has a normal distribution, or 0 if we cannot reject that
                   hypothesis. We reject the hypothesis if the test is significant at the 5% level.

                   The Lilliefors test evaluates the hypothesis that X has a normal distribution
                   with unspecified mean and variance, against the alternative that X does not
                   have a normal distribution. This test compares the empirical distribution of X
                   with a normal distribution having the same mean and variance as X. It is
                   similar to the Kolmogorov-Smirnov test, but it adjusts for the fact that the
                   parameters of the normal distribution are estimated from X rather than
                   specified in advance.

                   H = lillietest(X, alpha) performs the Lilliefors test at the 100*alpha%
                   level rather than the 5% level. alpha must be between 0.01 and 0.2.

                   [H, P, LSTAT, CV] = lillietest(X, alpha) returns three additional outputs. P
                   is the p-value of the test, obtained by linear interpolation in a set of table
                   created by Lilliefors. LSTAT is the value of the test statistic. CV is the critical
                   value for determining whether to reject the null hypothesis. If the value of
                   LSTAT is outside the range of the Lilliefors table, P is returned as NaN but H
                   indicates whether to reject the hypothesis.

**Example**        Do car weights follow a normal distribution? Not exactly, because weights are
                   always positive, and a normal distribution allows both positive and negative
                   values. However, perhaps the normal distribution is a reasonable
                   approximation.

```
load carsmall
[h p l c] = lillietest(Weight);
[h p l c]
```

```
ans =
    1.0000    0.0232    0.1032    0.0886
```

The Lilliefors test statistic of 0.10317 is larger than the cutoff value of 0.0886 for a 5% level test, so we reject the hypothesis of normality. In fact, the p-value of this test is approximately 0.02.

To visualize the distribution, we can make a histogram. This graph shows that the distribution is skewed to the right – from the peak near 2250, the frequencies drop off abruptly to the left but more gradually to the right.

```
hist(Weight)
```
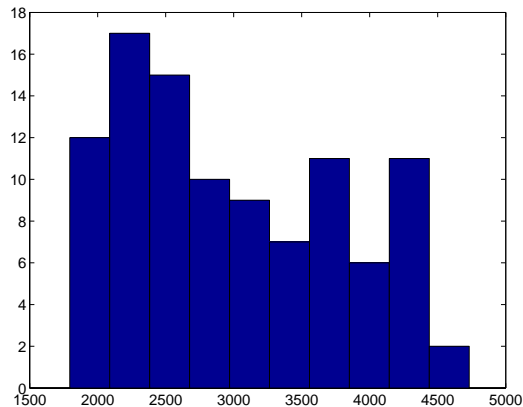


Sometimes it is possible to transform a variable to make its distribution more nearly normal. A log transformation, in particular, tends to compensate for skewness to the right.

```
[h p l c] = lillietest(log(Weight))

ans =
        0    0.13481    0.077924    0.0886
```

Now the p-value is approximately 0.13, so we do not reject the hypothesis.

**Reference**     Conover, W. J. (1980). *Practical Nonparametric Statistics.* New York, Wiley.

**See Also**     `hist, jbtest, kstest2`

# linkage

**Purpose**        Create hierarchical cluster tree.

**Syntax**         Z = linkage(Y)
                   Z = linkage(Y, '*method*')

**Description**    Z = linkage(Y) creates a hierarchical cluster tree, using the Single Linkage
                   algorithm. The input matrix, Y, is the distance vector output by the pdist
                   function, a vector of length $((m-1) \cdot m/2)$-by-1, where $m$ is the number of
                   objects in the original dataset.

                   Z = linkage(Y, '*method*') computes a hierarchical cluster tree using the
                   algorithm specified by '*method*', where '*method*' can be any of the following
                   character strings that identify ways to create the cluster hierarchy. Their
                   definitions are explained in "Mathematical Definitions" on page 2-179.

| String | Meaning |
|---|---|
| 'single' | Shortest distance (default) |
| 'complete' | Largest distance |
| 'average' | Average distance |
| 'centroid' | Centroid distance |
| 'ward' | Incremental sum of squares |

The output, Z, is an ($m$-1)-by-3 matrix containing cluster tree information. The
leaf nodes in the cluster hierarchy are the objects in the original dataset,
numbered from 1 to $m$. They are the singleton clusters from which all higher
clusters are built. Each newly formed cluster, corresponding to row $i$ in Z, is
assigned the index $m+i$, where $m$ is the total number of initial leaves.

Columns 1 and 2, Z(i, 1:2), contain the indices of the objects that were linked
in pairs to form a new cluster. This new cluster is assigned the index value $m+i$.
There are $m$-1 higher clusters that correspond to the interior nodes of the
hierarchical cluster tree.

Column 3, Z(i, 3), contains the corresponding linkage distances between the
objects paired in the clusters at each row $i$.

For example, consider a case with 30 initial nodes. If the tenth cluster formed by the linkage function combines object 5 and object 7 and their distance is 1.5, then row 10 of Z will contain the values (5, 7, 1. 5). This newly formed cluster will have the index 10+30=40. If cluster 40 shows up in a later row, that means this newly formed cluster is being combined again into some bigger cluster.

### Mathematical Definitions

The '*method*' argument is a character string that specifies the algorithm used to generate the hierarchical cluster tree information. These linkage algorithms are based on various measurements of proximity between two groups of objects. If $n_r$ is the number of objects in cluster $r$ and $n_s$ is the number of objects in cluster $s$, and $x_{ri}$ is the $i$th object in cluster $r$, the definitions of these various measurements are as follows:

- *Single linkage*, also called *nearest neighbor*, uses the smallest distance between objects in the two groups.

$$d(r, s) = min(dist(x_{ri}, x_{sj})), i \in (i, ..., n_r), j \in (1, ..., n_s)$$

- *Complete linkage*, also called *furthest neighbor*, uses the largest distance between objects in the two groups.

$$d(r, s) = max(dist(x_{ri}, x_{sj})), i \in (1, ..., n_r), j \in (1, ..., n_s)$$

- *Average linkage* uses the average distance between all pairs of objects in cluster $r$ and cluster $s$.

$$d(r, s) = \frac{1}{n_r n_s} \sum_{i=1}^{n_r} \sum_{j=1}^{n_s} dist(x_{ri}, x_{sj})$$

- *Centroid linkage* uses the distance between the centroids of the two groups.

$$d(r, s) = d(\bar{x}_r, \bar{x}_s)$$

where

$$\bar{x}_r = \frac{1}{n_r} \sum_{i=1}^{n_r} x_{ri}$$

and $\bar{x}_s$ is defined similarly.

- *Ward linkage* uses the incremental sum of squares; that is, the increase in the total within-group sum of squares as a result of joining groups *r* and *s*. It is given by

$$d(r, s) = n_r n_s d_{rs}^2 / (n_r + n_s)$$

where $d_{rs}^2$ is the distance between cluster *r* and cluster *s* defined in the Centroid linkage. The within-group sum of squares of a cluster is defined as the sum of the squares of the distance between all objects in the cluster and the centroid of the cluster.

**Example**

```
X = [3 1.7; 1 1; 2 3; 2 2.5; 1.2 1; 1.1 1.5; 3 1];
Y = pdist(x);
Z = linkage(y)

Z =
      2.0000    5.0000    0.2000
      3.0000    4.0000    0.5000
      8.0000    6.0000    0.5099
      1.0000    7.0000    0.7000
     11.0000    9.0000    1.2806
     12.0000   10.0000    1.3454
```

**See Also**

cluster, clusterdata, cophenet, dendrogram, inconsistent, pdist, squareform

# logncdf

**Purpose**    Lognormal cumulative distribution function.

**Syntax**    P = logncdf(X, MU, SIGMA)

**Description**    P = logncdf(X, MU, SIGMA) computes the lognormal cdf at each of the values in X using the corresponding means in MU and standard deviations in SIGMA. Vector or matrix inputs for X, MU, and SIGMA must have the same size, which is also the size of P. A scalar input for X, MU, or SIGMA is expanded to a constant matrix with the same dimensions as the other inputs.

The lognormal cdf is

$$p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_0^x \frac{e^{\frac{-(\ln(t) - \mu)^2}{2\sigma^2}}}{t} dt$$

**Example**
```
x = (0:0.2:10);
y = logncdf(x, 0, 1);
plot(x, y); grid;
xlabel('x'); ylabel('p');
```
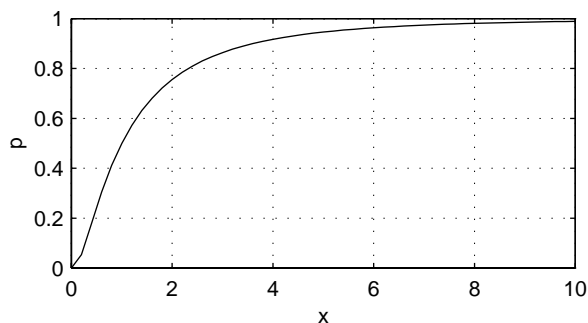


**Reference**    Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* John Wiley and Sons, 1993. p. 102–105.

**See Also**    cdf, logninv, lognpdf, lognrnd, lognstat

# logninv

**Purpose**      Inverse of the lognormal cumulative distribution function (cdf).

**Syntax**      X = logninv(P, MU, SIGMA)

**Description**  X = logninv(P, MU, SIGMA) computes the inverse lognormal cdf with mean MU
and standard deviation SIGMA, at the corresponding probabilities in P. Vector
or matrix inputs for P, MU, and SIGMA must have the same size, which is also the
size of X. A scalar input for P, MU, or SIGMA is expanded to a constant matrix with
the same dimensions as the other inputs.

We define the lognormal inverse function in terms of the lognormal cdf as

$$x = F^{-1}(p|\mu, \sigma) = \{x : F(x|\mu, \sigma) = p\}$$

where

$$p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_0^x \frac{e^{\frac{-(\ln(t)-\mu)^2}{2\sigma^2}}}{t} dt$$

**Example**
```
p = (0.005:0.01:0.995);
crit = logninv(p, 1, 0.5);
plot(p, crit)
xlabel('Probability'); ylabel('Critical Value'); grid
```
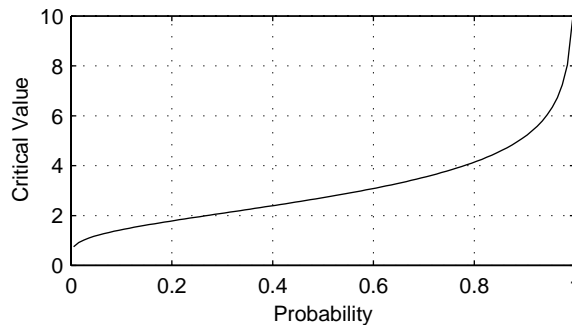
**Reference**      Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* John Wiley and Sons, 1993. p. 102–105.

**See Also**      icdf, logncdf, lognpdf, lognrnd, lognstat

# lognpdf

**Purpose**          Lognormal probability density function (pdf).

**Syntax**           Y = lognpdf(X, MU, SIGMA)

**Description**      Y = logncdf(X, MU, SIGMA) computes the lognormal cdf at each of the values
                     in X using the corresponding means in MU and standard deviations in SIGMA.
                     Vector or matrix inputs for X, MU, and SIGMA must have the same size, which is
                     also the size of Y. A scalar input for X, MU, or SIGMA is expanded to a constant
                     matrix with the same dimensions as the other inputs

                     The lognormal pdf is

                     $$y = f(x|\mu, \sigma) = \frac{1}{x\sigma\sqrt{2\pi}} e^{\frac{-(\ln(x) - \mu)^2}{2\sigma^2}}$$

**Example**          x = (0:0.02:10);
                     y = lognpdf(x, 0, 1);
                     plot(x, y); grid;
                     xlabel('x'); ylabel('p')
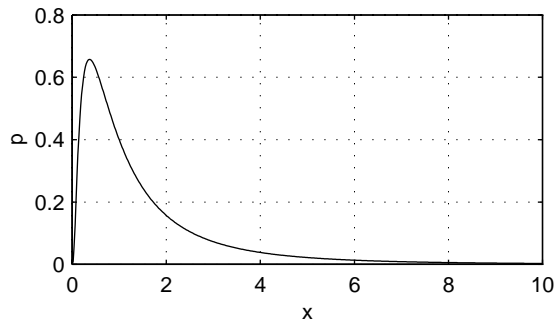


**Reference**        Mood, A. M., F.A. Graybill, and D.C. Boes, *Introduction to the Theory of
                     Statistics, Third Edition,* McGraw-Hill 1974 p. 540–541.

**See Also**         logncdf, logninv, lognrnd, lognstat, pdf

**Purpose**      Random matrices from the lognormal distribution.

**Syntax**       R = lognrnd(MU, SIGMA)
                 R = lognrnd(MU, SIGMA, m)
                 R = lognrnd(MU, SIGMA, m, n)

**Description**  R = lognrnd(MU, SIGMA) generates lognormal random numbers with parameters MU and SIGMA. Vector or matrix inputs for MU and SIGMA must have the same size, which is also the size of R. A scalar input for MU or SIGMA is expanded to a constant matrix with the same dimensions as the other input.

R = lognrnd(MU, SIGMA, m) generates lognormal random numbers with parameters MU and SIGMA, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = lognrnd(MU, SIGMA, m, n) generates lognormal random numbers with parameters MU and SIGMA, where scalars m and n are the row and column dimensions of R.

**Example**      r = lognrnd(0, 1, 4, 3)

                 r =
                     3.2058    0.4983    1.3022
                     1.8717    5.4529    2.3909
                     1.0780    1.0608    0.2355
                     1.4213    6.0320    0.4960

**Reference**    Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* John Wiley and Sons, 1993. p. 102–105.

**See Also**     random, logncdf, logninv, lognpdf, lognstat

# lognstat

**Purpose**      Mean and variance for the lognormal distribution.

**Syntax**       [M, V] = lognstat(MU, SIGMA)

**Description**  [M, V] = lognstat(MU, SIGMA) returns the mean and variance of the
lognormal distribution with parameters MU and SIGMA. Vector or matrix inputs
for MU and SIGMA must have the same size, which is also the size of M and V. A
scalar input for MU or SIGMA is expanded to a constant matrix with the same
dimensions as the other input.

The mean of the lognormal distribution with parameters $\mu$ and $\sigma$ is

$$e^{\left(\mu + \frac{\sigma^2}{2}\right)}$$

and the variance is

$$e^{(2\mu + 2\sigma^2)} - e^{(2\mu + \sigma^2)}$$

**Example**      [m, v] = lognstat(0, 1)

m =
    1.6487

v =
    7.0212

**Reference**    Mood, A. M., F.A. Graybill, and D.C. Boes, *Introduction to the Theory of
Statistics, Third Edition,* McGraw-Hill 1974 p. 540–541.

**See Also**     logncdf, logninv, lognrnd, lognrnd

| | |
|---|---|
| **Purpose** | Least squares fit line(s). |
| **Syntax** | lsline <br> h = lsline |
| **Description** | lsline superimposes the least squares line on each line object in the current axes (except LineStyles '-','--','.-'). <br><br> h = lsline returns the handles to the line objects. |
| **Example** | y = [2 3.4 5.6 8 11 12.3 13.8 16 18.8 19.9]'; <br> plot(y,'+'); <br> lsline; |



| | |
|---|---|
| **See Also** | polyfit, polyval |
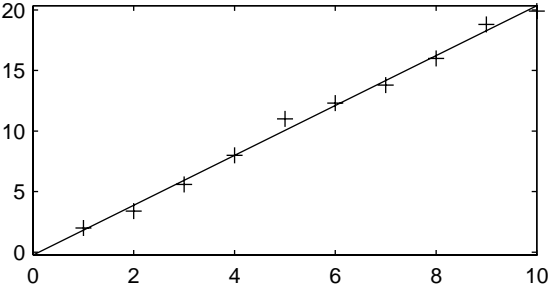
# mad

| | |
|---|---|
| **Purpose** | Mean absolute deviation (MAD) of a sample of data. |
| **Syntax** | y = mad(X) |
| **Description** | y = mad(X) computes the average of the absolute differences between a set of data and the sample mean of that data. For vectors, mad(x) returns the mean absolute deviation of the elements of x. For matrices, mad(X) returns the MAD of each column of X. |
| | The MAD is less efficient than the standard deviation as an estimate of the spread when the data is all from the normal distribution. |
| | Multiply the MAD by 1.3 to estimate $\sigma$ (the second parameter of the normal distribution). |
| **Examples** | This example shows a Monte Carlo simulation of the relative efficiency of the MAD to the sample standard deviation for normal data. |

```
x = normrnd(0, 1, 100, 100);
s = std(x);
s_MAD = 1.3 * mad(x);
efficiency = (norm(s - 1)./norm(s_MAD - 1)).^2

efficiency =

    0.5972
```

| | |
|---|---|
| **See Also** | std, range |

**Purpose**        Mahalanobis distance.

**Syntax**         d = mahal(Y, X)

**Description**    mahal(Y, X) computes the Mahalanobis distance of each point (row) of the
                   matrix Y from the sample in the matrix X.

                   The number of columns of Y must equal the number of columns in X, but the
                   number of rows may differ. The number of rows in X must exceed the number
                   of columns.

                   The Mahalanobis distance is a multivariate measure of the separation of a data
                   set from a point in space. It is the criterion minimized in linear discriminant
                   analysis.

**Example**        The Mahalanobis distance of a matrix r when applied to itself is a way to find
                   outliers.

```
r = mvnrnd([0 0], [1 0.9; 0.9 1], 100);
r = [r; 10 10];
d = mahal(r, r);
last6 = d(96:101)

last6 =

    1.1036
    2.2353
    2.0219
    0.3876
    1.5571
   52.7381
```

                   The last element is clearly an outlier.

**See Also**       classify

# manova1

**Purpose**      One-way Multivariate Analysis of Variance (MANOVA).

**Syntax**       d = manova1(X, group)
                 d = manova1(X, group, alpha)
                 [d, p] = manova1(...)
                 [d, p, stats] = anova1(...)

**Description**  d = manova1(X, group) performs a one-way Multivariate Analysis of Variance
                 (MANOVA) for comparing the multivariate means of the columns of X, grouped
                 by group. X is an *m*-by-*n* matrix of data values, and each row is a vector of
                 measurements on *n* variables for a single observation. group is a grouping
                 variable defined as a vector, string array, or cell array of strings. Two
                 observations are in the same group if they have the same value in the group
                 array. The observations in each group represent a sample from a population.

                 The function returns d, an estimate of the dimension of the space containing
                 the group means. manova1 tests the null hypothesis that the means of each
                 group are the same *n*-dimensional multivariate vector, and that any difference
                 observed in the sample X is due to random chance. If d = 0, there is no evidence
                 to reject that hypothesis. If d = 1, then you can reject the null hypothesis at the
                 5% level, but you cannot reject the hypothesis that the multivariate means lie
                 on the same line. Similarly, if d = 2 the multivariate means may lie on the same
                 plane in *n*-dimensional space, but not on the same line.

                 d = manova1(X, group, alpha) gives control of the significance level, alpha.
                 The return value d will be the smallest dimension having p > alpha, where p is
                 a p-value for testing whether the means lie in a space of that dimension.

                 [d, p] = manova1(...) also returns a p, a vector of p-values for testing
                 whether the means lie in a space of dimension 0, 1, and so on. The largest
                 possible dimension is either the dimension of the space, or one less than the
                 number of groups. There is one element of p for each dimension up to, but not
                 including, the largest.

                 If the *i*th p-value is near zero, this casts doubt on the hypothesis that the group
                 means lie on a space of *i*-1 dimensions. The choice of a critical p-value to
                 determine whether the result is judged "statistically significant" is left to the
                 researcher and is specified by the value of the input argument alpha. It is
                 common to declare a result significant if the p-value is less than 0.05 or 0.01.

[d, p, stats] = anova1(...) also returns stats, a structure containing additional MANOVA results. The structure contains the following fields.

| Field | Contents |
|-------|----------|
| W | Within-groups sum of squares and cross-products matrix |
| B | Between-groups sum of squares and cross-products matrix |
| T | Total sum of squares and cross-products matrix |
| dfW | Degrees of freedom for W |
| dfB | Degrees of freedom for B |
| dfT | Degrees of freedom for T |
| lambda | Vector of values of Wilk's lambda test statistic for testing whether the means have dimension 0, 1, etc. |
| chisq | Transformation of lambda to an approximate chi-square distribution |
| chisqdf | Degrees of freedom for chisq |
| eigenval | Eigenvalues of $W^{-1}B$ |
| eigenvec | Eigenvectors of $W^{-1}B$; these are the coefficients for the canonical variables C, and they are scaled so the within-group variance of the canonical variables is 1 |
| canon | Canonical variables C, equal to XC*eigenvec, where XC is X with columns centered by subtracting their means |
| mdist | A vector of Mahalanobis distances from each point to the mean of its group |
| gmdist | A matrix of Mahalanobis distances between each pair of group means |

The canonical variables C are linear combinations of the original variables, chosen to maximize the separation between groups. Specifically, C(:, 1) is the linear combination of the X columns that has the maximum separation between groups. This means that among all possible linear combinations, it is the one with the most significant F statistic in a one-way analysis of variance.

C(:, 2) has the maximum separation subject to it being orthogonal to C(:, 1), and so on.

You may find it useful to use the outputs from manova1 along with other functions to supplement your analysis. For example, you may want to start with a grouped scatter plot matrix of the original variables using gplotmatrix. You can use gscatter to visualize the group separation using the first two canonical variables. You can use manovacluster to graph a dendrogram showing the clusters among the group means.

### Assumptions

The MANOVA test makes the following assumptions about the data in X:

- The populations for each group are normally distributed.
- The variance-covariance matrix is the same for each population.
- All observations are mutually independent.

**Example**   We can use manova1 to determine whether there are differences in the averages of four car characteristics, among groups defined by the country where the cars were made.

```
load carbig
[d, p] = manova1([MPG Acceleration Weight Displacement], Origin)

d =
    3

p =
        0
    0.0000
    0.0075
    0.1934
```

There are four dimensions in the input matrix, so the group means must lie in a four-dimensional space. manova1 shows that we cannot reject the hypothesis that the means lie in a three-dimensional subspace.

**References**   Krzanowski, W. J. *Principles of Multivariate Analysis*. Oxford University Press, 1988.

**See Also**   anova1, gscatter, gplotmatrix, manovacluster

# manovacluster

| | |
|---|---|
| **Purpose** | Plot dendrogram showing group mean clusters after MANOVA. |
| **Syntax** | manovacluster(stats)<br>manovacluster(stats, '*method*')<br>H = manovacluster(stats) |
| **Description** | manovacluster(stats) generates a dendrogram plot of the group means after a multivariate analysis of variance (MANOVA). stats is the output stats structure from manova1. The clusters are computed by applying the single linkage method to the matrix of Mahalanobis distances between group means. |

See dendrogram for more information on the graphical output from this function. The dendrogram is most useful when the number of groups is large.

manovacluster(stats, '*method*') uses the specified method in place of single linkage. '*method*' can be any of the following character strings that identify ways to create the cluster hierarchy. See linkage for further explanation.

| String | Meaning |
|---|---|
| 'single' | Shortest distance (default) |
| 'complete' | Largest distance |
| 'average' | Average distance |
| 'centroid' | Centroid distance |
| 'ward' | Incremental sum of squares |

H = manovacluster(stats, '*method*') returns a vector of handles to the lines in the figure.

**Example**

Let's analyze the larger car dataset to determine which countries produce cars with the most similar characteristics.

```
load carbig
X = [MPG Acceleration Weight Displacement];
[d, p, stats] = manova1(X, Origin);
manovacluster(stats)
```
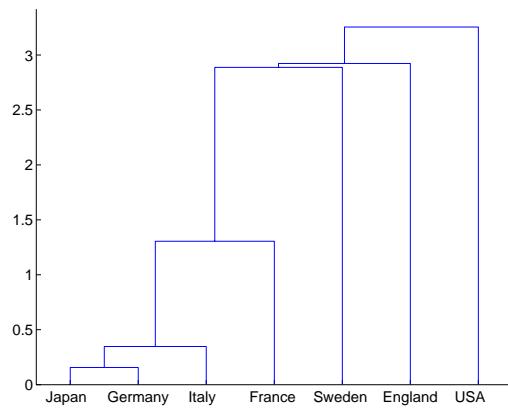
**See Also**        cluster, dendrogram, linkage, manova1

# mean

**Purpose**        Average or mean value of vectors and matrices.

**Syntax**         m = mean(X)

**Description**    m = mean(X) calculates the sample average

$$\overline{x}_j = \frac{1}{n} \sum_{i=1}^{n} x_{ij}$$

For vectors, mean(x) is the mean value of the elements in vector x. For matrices, mean(X) is a row vector containing the mean value of each column.

The mean function is part of the standard MATLAB language.

**Example**        These commands generate five samples of 100 normal random numbers with mean, zero, and standard deviation, one. The sample averages in xbar are much less variable $(0.00 \pm 0.10)$.

```
x = normrnd(0, 1, 100, 5);
xbar = mean(x)

xbar =

    0.0727    0.0264    0.0351    0.0424    0.0752
```

**See Also**       median, std, cov, corrcoef, var

# median

**Purpose**        Median value of vectors and matrices.

**Syntax**        m = median(X)

**Description**   m = median(X) calculates the median value, which is the 50th percentile of a
sample. The median is a robust estimate of the center of a sample of data, since
outliers have little effect on it.

For vectors, median(x) is the median value of the elements in vector x. For
matrices, median(X) is a row vector containing the median value of each
column. Since median is implemented using sort, it can be costly for large
matrices.

The median function is part of the standard MATLAB language.

**Examples**
```
xodd = 1:5;
modd = median(xodd)

modd =

     3

meven = median(xeven)

meven =

   2.5000
```

This example shows robustness of the median to outliers.

```
xoutlier = [x 10000];
moutlier = median(xoutlier)

moutlier =

     3
```

**See Also**      mean, std, cov, corrcoef

# mle

| | |
|---|---|
| **Purpose** | Maximum likelihood estimation. |
| **Syntax** | phat = mle('*dist*', data) |
| | [phat, pci] = mle('*dist*', data) |
| | [phat, pci] = mle('*dist*', data, alpha) |
| | [phat, pci] = mle('*dist*', data, alpha, p1) |

**Description**    phat = mle('*dist*', data) returns the maximum likelihood estimates (MLEs) for the distribution specified in '*dist*' using the sample in the vector, data. See "Overview of the Distributions" on page 1-12 for the list of available distributions.

[phat, pci] = mle('*dist*', data) returns the MLEs and 95% percent confidence intervals.

[phat, pci] = mle('*dist*', data, alpha) returns the MLEs and 100(1-alpha)% confidence intervals given the data and the specified alpha.

[phat, pci] = mle('*dist*', data, alpha, p1) is used for the binomial distribution only, where p1 is the number of trials.

**Example**
```
rv = binornd(20, 0.75)

rv =
    16

[p, pci] = mle('binomial', rv, 0.05, 20)

p =
    0.8000

pci =
    0.5634
    0.9427
```

**See Also**    betafit, binofit, expfit, gamfit, normfit, poissfit, weibfit

**Purpose**        Central moment of all orders.

**Syntax**         m = moment(X, order)

**Description**    m = moment(X, order) returns the central moment of X specified by the
                   positive integer order. For vectors, moment(x, order) returns the central
                   moment of the specified order for the elements of x. For matrices,
                   moment(X, order) returns central moment of the specified order for each
                   column.

                   Note that the central first moment is zero, and the second central moment is
                   the variance computed using a divisor of $n$ rather than $n$-1, where $n$ is the
                   length of the vector x or the number of rows in the matrix X.

                   The central moment of order $k$ of a distribution is defined as

                   $$m_n = E(x-\mu)^k$$

                   where $E(x)$ is the expected value of $x$.

**Example**        X = randn([6 5])

                   X =
                       1.1650     0.0591     1.2460    -1.2704    -0.0562
                       0.6268     1.7971    -0.6390     0.9846     0.5135
                       0.0751     0.2641     0.5774    -0.0449     0.3967
                       0.3516     0.8717    -0.3600    -0.7989     0.7562
                      -0.6965    -1.4462    -0.1356    -0.7652     0.4005
                       1.6961    -0.7012    -1.3493     0.8617    -1.3414

                   m = moment(X, 3)

                   m =
                      -0.0282     0.0571     0.1253     0.1460    -0.4486

**See Also**       kurtosis, mean, skewness, std, var

# multcompare

**Purpose**  Multiple comparison test of means or other estimates.

**Syntax**
```
c = multcompare(stats)
c = multcompare(stats, alpha)
c = multcompare(stats, alpha, 'displayopt')
c = multcompare(stats, alpha, 'displayopt', 'ctype')
c = multcompare(stats, alpha, 'displayopt', 'ctype', 'estimate')
c = multcompare(stats, alpha, 'displayopt', 'ctype', 'estimate', dim)
[c, m] = multcompare(...)
[c, m, h] = multcompare(...)
```

**Description**  c = multcompare(stats) performs a multiple comparison test using the information in the stats structure, and returns a matrix c of pairwise comparison results. It also displays an interactive figure presenting a graphical representation of the test.

In a one-way analysis of variance, you compare the means of several groups to test the hypothesis that they are all the same, against the general alternative that they are not all the same. Sometimes this alternative may be too general. You may need information about which pairs of means are significantly different, and which are not. A test that can provide such information is called a "multiple comparison procedure."

When you perform a simple t-test of one group mean against another, you specify a significance level that determines the cutoff value of the t statistic. For example, you can specify the value alpha = 0.05 to insure that when there is no real difference, you will incorrectly find a significant difference no more than 5% of the time. When there are many group means, there are also many pairs to compare. If you applied an ordinary t-test in this situation, the alpha value would apply to each comparison, so the chance of incorrectly finding a significant difference would increase with the number of comparisons. Multiple comparison procedures are designed to provide an upper bound on the probability that *any* comparison will be incorrectly found significant.

The output c contains the results of the test in the form of a five-column matrix. Each row of the matrix represents one test, and there is one row for each pair of groups. The entries in the row indicate the means being compared, the estimated difference in means, and a confidence interval for the difference.

For example, suppose one row contains the following entries.

    2.0000    5.0000    1.9442    8.2206    14.4971

These numbers indicate that the mean of group 2 minus the mean of group 5 is estimated to be 8.2206, and a 95% confidence interval for the true mean is [1.9442, 14.4971].

In this example the confidence interval does not contain 0.0, so the difference is significant at the 0.05 level. If the confidence interval did contain 0.0, the difference would not be significant at the 0.05 level.

The multcompare function also displays a graph with each group mean represented by a symbol and an interval around the symbol. Two means are significantly different if their intervals are disjoint, and are not significantly different if their intervals overlap. You can use the mouse to select any group, and the graph will highlight any other groups that are significantly different from it.

c = multcompare(stats, alpha) determines the confidence levels of the intervals in the c matrix and in the figure. The confidence level is 100*(1-alpha)%. The default value of alpha is 0.05.

c = multcompare(stats, alpha, '*displayopt*') enables the graph display when '*displayopt*' is 'on' (default) and suppresses the display when '*displayopt*' is 'off'.

c = multcompare(stats, alpha, '*displayopt*', '*ctype*') specifies the critical value to use for the multiple comparison, which can be any of the following.

| ctype | Meaning |
| --- | --- |
| 'hsd' | Use Tukey's honestly significant difference criterion. This is the default, and it is based on the Studentized range distribution. It is optimal for balanced one-way ANOVA and similar procedures with equal sample sizes. It has been proven to be conservative for one-way ANOVA with different sample sizes. According to the unproven Tukey-Kramer conjecture, it is also accurate for problems where the quantities being compared are correlated, as in analysis of covariance with unbalanced covariate values. |
| 'lsd' | Use Tukey's least significant difference procedure. This procedure is a simple t-test. It is reasonable if the preliminary test (say, the one-way ANOVA F statistic) shows a significant difference. If it is used unconditionally, it provides no protection against multiple comparisons. |
| 'bonferroni' | Use critical values from the t distribution, after a Bonferroni adjustment to compensate for multiple comparisons. This procedure is conservative, but usually less so than the Scheffé procedure. |
| 'dunn-sidak' | Use critical values from the t distribution, after an adjustment for multiple comparisons that was proposed by Dunn and proved accurate by Šidák. This procedure is similar to, but less conservative than, the Bonferroni procedure. |
| 'scheffe' | Use critical values from Scheffé's S procedure, derived from the F distribution. This procedure provides a simultaneous confidence level for comparisons of all linear combinations of the means, and it is conservative for comparisons of simple differences of pairs. |

c = multcompare(stats, alpha, '*displayopt*', '*ctype*', '*estimate*')
specifies the estimate to be compared. The allowable values of estimate depend on the function that was the source of the stats structure, according to the following table.

| Source | Allowable Values of Estimate |
|--------|------------------------------|
| 'anova1' | Ignored. Always compare the group means. |
| 'anova2' | Either 'column' (the default) or 'row' to compare column or row means. |
| 'anovan' | Ignored. Always compare the population marginal means as specified by the dim argument. |
| 'aoctool' | Either 'slope', 'intercept', or 'pmm' to compare slopes, intercepts, or population marginal means. If the analysis of covariance model did not include separate slopes, then 'slope' is not allowed. If it did not include separate intercepts, then no comparisons are possible. |
| 'friedman' | Ignored. Always compare average column ranks. |
| 'kruskalwallis' | Ignored. Always compare average group ranks. |

c = multcompare(stats, alpha, '*displayopt*', '*ctype*', '*estimate*', dim)
specifies the population marginal means to be compared. This argument is used only if the input stats structure was created by the anovan function. For n-way ANOVA with n factors, you can specify dim as a scalar or a vector of integers between 1 and n. The default value is 1.

For example, if dim = 1, the estimates that are compared are the means for each value of the first grouping variable, adjusted by removing effects of the other grouping variables as if the design were balanced. If dim = [1 3], population marginal means are computed for each combination of the first and third grouping variables, removing effects of the second grouping variable. If you fit a singular model, some cell means may not be estimable and any population marginal means that depend on those cell means will have the value NaN.

Population marginal means are described by Milliken and Johnson (1992) and by Searle, Speed, and Milliken (1980). The idea behind population marginal means is to remove any effect of an unbalanced design by fixing the values of the factors specified by dim, and averaging out the effects of other factors as if each factor combination occurred the same number of times. The definition of population marginal means does not depend on the number of observations at each factor combination. For designed experiments where the number of observations at each factor combination has no meaning, population marginal means can be easier to interpret than simple means ignoring other factors. For surveys and other studies where the number of observations at each combination does have meaning, population marginal means may be harder to interpret.

[c, m] = multcompare(...) returns an additional matrix m. The first column of m contains the estimated values of the means (or whatever statistics are being compared) for each group, and the second column contains their standard errors.

[c, m, h] = multcompare(...) returns a handle h to the comparison graph. Note that the title of this graph contains instructions for interacting with the graph, and the *x*-axis label contains information about which means are significantly different from the selected mean. If you plan to use this graph for presentation, you may want to omit the title and the *x*-axis label. You can remove them using interactive features of the graph window, or you can use the following commands.

```
title('')
xlabel('')
```

**Example**     Let's revisit the anova1 example testing the material strength in structural beams. From the anova1 output we found significant evidence that the three types of beams are not equivalent in strength. Now we can determine where those differences lie. First we create the data arrays and we perform one-way ANOVA.

```
strength = [82 86 79 83 84 85 86 87 74 82 78 75 76 77 79 ...
            79 77 78 82 79];
alloy = {'st','st','st','st','st','st','st','st',...
         'al1','al1','al1','al1','al1','al1',...
         'al2','al2','al2','al2','al2','al2'};
```

**mult**compare

```
[p, a, s] = anova1(strength, alloy);
```

Among the outputs is a structure that we can use as input to multcompare.

```
multcompare(s)
```

```
ans =
        1.0000      2.0000      3.6064      7.0000     10.3936
        1.0000      3.0000      1.6064      5.0000      8.3936
        2.0000      3.0000     -5.6280     -2.0000      1.6280
```

**Click on the group you want to test**



2 groups have slopes significantly different from st
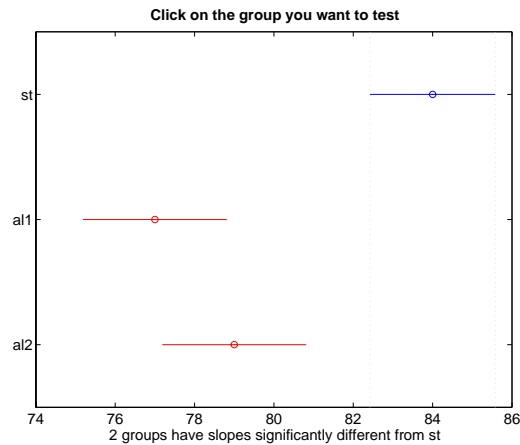
The third row of the output matrix shows that the differences in strength between the two alloys is not significant. A 95% confidence interval for the difference is [-5.6, 1.6], so we cannot reject the hypothesis that the true difference is zero.

The first two rows show that both comparisons involving the first group (steel) have confidence intervals that do not include zero. In other words, those differences are significant. The graph shows the same information.

**See Also**        anova1, anova2, anovan, aoctool, friedman, kruskalwallis

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# multcompare

**References**     Hochberg, Y., and A. C. Tamhane, *Multiple Comparison Procedures*, 1987, Wiley.

Milliken, G. A., and D. E. Johnson, *Analysis of Messy Data, Volume 1: Designed Experiments*, 1992, Chapman & Hall.

Searle, S. R., F. M. Speed, and G. A. Milliken, "Population marginal means in the linear model: an alternative to least squares means," *American Statistician*, 1980, pp. 216-221.

**Purpose**        Random matrices from the multivariate normal distribution.

**Syntax**         r = mvnrnd(mu, SIGMA, cases)

**Description**    r = mvnrnd(mu, SIGMA, cases) returns a matrix of random numbers chosen
                   from the multivariate normal distribution with mean vector mu and covariance
                   matrix SIGMA. cases specifies the number of rows in r.

                   SIGMA is a symmetric positive definite matrix with size equal to the length
                   of mu.

**Example**        mu = [2 3];
                   sigma = [1 1.5; 1.5 3];
                   r = mvnrnd(mu, sigma, 100);
                   plot(r(:,1), r(:,2), '+')
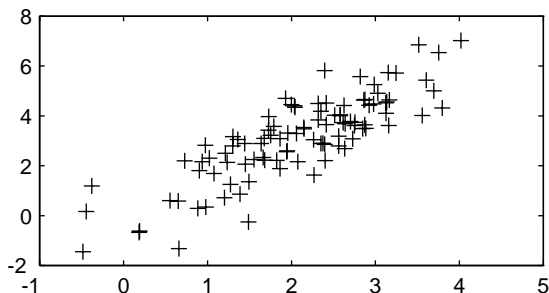


**See Also**       normrnd

# mvtrnd

**Purpose**        Random matrices from the multivariate t distribution.

**Syntax**         r = mvtrnd(C, df, cases)

**Description**    r = mvtrnd(C, df, cases) returns a matrix of random numbers chosen from
                   the multivariate t distribution, where C is a correlation matrix. df is the
                   degrees of freedom and is either a scalar or is a vector with cases elements. If
                   p is the number of columns in C, then the output r has cases rows and p
                   columns.

                   Let t represent a row of r. Then the distribution of t is that of a vector having
                   a multivariate normal distribution with mean 0, variance 1, and covariance
                   matrix C, divided by an independent chi-square random value having df
                   degrees of freedom. The rows of r are independent.

                   C must be a square, symmetric and positive definite matrix. If its diagonal
                   elements are not all 1 (that is, if C is a covariance matrix rather than a
                   correlation matrix), mvtrnd computes the equivalent correlation matrix before
                   generating the random numbers.

**Example**        sigma = [1 0.8;0.8 1];
                   r = mvtrnd(sigma, 3, 100);
                   plot(r(:,1),r(:,2),'+')
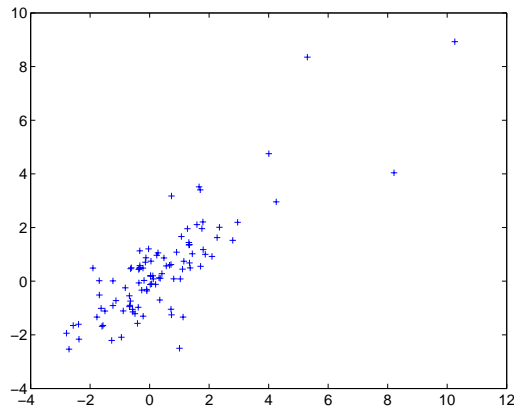


**See Also**       mvnrnd, trnd

**Purpose**        Maximum ignoring NaNs.

**Syntax**         m = nanmax(a)
                   [m, ndx] = nanmax(a)
                   m = nanmax(a, b)

**Description**    m = nanmax(a) returns the maximum with NaNs treated as missing. For
                   vectors, nanmax(a) is the largest non-NaN element in a. For matrices,
                   nanmax(A) is a row vector containing the maximum non-NaN element from each
                   column.

                   [m, ndx] = nanmax(a) also returns the indices of the maximum values in
                   vector ndx.

                   m = nanmax(a, b) returns the larger of a or b, which must match in size.

**Example**            m = magic(3);
                       m([1 6 8]) = [NaN NaN NaN]

                       m =

                           NaN     1     6
                             3     5   NaN
                             4   NaN     2

                       [nmax, maxidx] = nanmax(m)

                       nmax =

                             4     5     6

                       maxidx =

                             3     2     1

**See Also**       nanmin, nanmean, nanmedian, nanstd, nansum

# nanmean

**Purpose**      Mean ignoring NaNs

**Syntax**       y = nanmean(X)

**Description**  y = nanmean(X) is the average computed by treating NaNs as missing values.

For vectors, nanmean(x) is the mean of the non-NaN elements of x. For matrices, nanmean(X) is a row vector containing the mean of the non-NaN elements in each column.

**Example**
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

   NaN     1     6
     3     5   NaN
     4   NaN     2

nmean = nanmean(m)

nmean =

   3.5000    3.0000    4.0000
```

**See Also**     nanmin, nanmax, nanmedian, nanstd, nansum

**Purpose**      Median ignoring NaNs

**Syntax**       y = nanmedian(X)

**Description**  y = nanmedian(X) is the median computed by treating NaNs as missing values.

For vectors, nanmedian(x) is the median of the non-NaN elements of x. For matrices, nanmedian(X) is a row vector containing the median of the non-NaN elements in each column of X.

**Example**
```
m = magic(4);
m([1 6 9 11]) = [NaN NaN NaN NaN]

m =

    NaN      2    NaN     13
      5    NaN     10      8
      9      7    NaN     12
      4     14     15      1

nmedian = nanmedian(m)

nmedian =

    5.0000    7.0000   12.5000   10.0000
```

**See Also**     nanmin, nanmax, nanmean, nanstd, nansum

# nanmin

**Purpose**      Minimum ignoring NaNs

**Syntax**       m = nanmin(a)
                 [m, ndx] = nanmin(a)
                 m = nanmin(a, b)

**Description**  m = nanmin(a) is the minimum computed by treating NaNs as missing values. For vectors, nanmin(a) is the smallest non-NaN element in a. For matrices, nanmin(A) is a row vector containing the minimum non-NaN element from each column.

[m, ndx] = nanmin(a) also returns the indices of the minimum values in vector ndx.

m = nanmin(a, b) returns the smaller of a or b, which must match in size.

**Example**
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

    NaN      1      6
      3      5    NaN
      4    NaN      2

[nmin, minidx] = nanmin(m)

nmin =

      3      1      2

minidx =

      2      1      3
```

**See Also**     nanmax, nanmean, nanmedian, nanstd, nansum

**Purpose**        Standard deviation ignoring NaNs.

**Syntax**         y = nanstd(X)

**Description**    y = nanstd(X) is the standard deviation computed by treating NaNs as
                   missing values.

                   For vectors, nanstd(x) is the standard deviation of the non-NaN elements of x.
                   For matrices, nanstd(X) is a row vector containing the standard deviations of
                   the non-NaN elements in each column of X.

**Example**
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

    NaN      1      6
      3      5    NaN
      4    NaN      2

nstd = nanstd(m)

nstd =

    0.7071    2.8284    2.8284
```

**See Also**      nanmax, nanmin, nanmean, nanmedian, nansum

# nansum

**Purpose**      Sum ignoring NaNs.

**Syntax**       y = nansum(X)

**Description**  y = nansum(X) is the sum computed by treating NaNs as missing values.

For vectors, nansum(x) is the sum of the non-NaN elements of x. For matrices, nansum(X) is a row vector containing the sum of the non-NaN elements in each column of X.

**Example**
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

    NaN      1      6
      3      5    NaN
      4    NaN      2

nsum = nansum(m)

nsum =

      7      6      8
```

**See Also**     nanmax, nanmin, nanmean, nanmedian, nanstd

**Purpose**          Negative binomial cumulative distribution function.

**Syntax**           Y = nbincdf(X, R, P)

**Description**      Y = nbincdf(X, R, P) computes the negative binomial cdf at each of the values
                     in X using the corresponding parameters in R and P. Vector or matrix inputs for
                     X, R, and P must have the same size, which is also the size of Y. A scalar input
                     for X, R, or P is expanded to a constant matrix with the same dimensions as the
                     other inputs.

                     The negative binomial cdf is

$$y = F(x|r, p) = \sum_{i=0}^{x} \binom{r+i-1}{i} p^r q^i I_{(0, 1, \ldots)}(i)$$

                     The motivation for the negative binomial is the case of successive trials, each
                     having a constant probability P of success. What you want to find out is how
                     many *extra* trials you must do to observe a given number R of successes.

**Example**          x = (0: 15);
                     p = nbincdf(x, 3, 0. 5);
                     stairs(x, p)
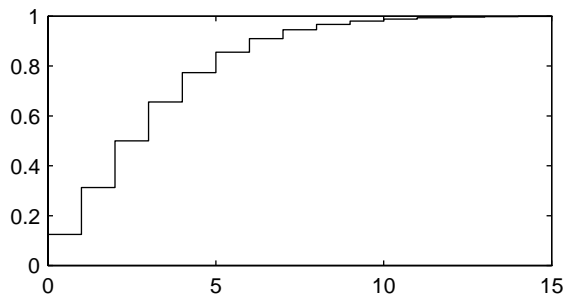


**See Also**         cdf, nbininv, nbinpdf, nbinrnd, nbinstat

# nbininv

**Purpose**       Inverse of the negative binomial cumulative distribution function (cdf).

**Syntax**        X = nbininv(Y, R, P)

**Description**   X = nbininv(Y, R, P) returns the inverse of the negative binomial cdf with
                  parameters R and P at the corresponding probabilities in P. Since the binomial
                  distribution is discrete, nbininv returns the least integer X such that the
                  negative binomial cdf evaluated at X equals or exceeds Y. Vector or matrix
                  inputs for Y, R, and P must have the same size, which is also the size of X. A
                  scalar input for Y, R, or P is expanded to a constant matrix with the same
                  dimensions as the other inputs.

                  The negative binomial cdf models consecutive trials, each having a constant
                  probability P of success. The parameter R is the number of successes required
                  before stopping.

**Example**       How many times would you need to flip a fair coin to have a 99% probability of
                  having observed 10 heads?

                      flips = nbininv(0.99, 10, 0.5) + 10

                      flips =

                          33

                  Note that you have to flip at least 10 times to get 10 heads. That is why the
                  second term on the right side of the equals sign is a 10.

**See Also**      icdf, nbincdf, nbinpdf, nbinrnd, nbinstat

**Purpose**        Negative binomial probability density function.

**Syntax**        Y = nbinpdf(X, R, P)

**Description**    Y = nbinpdf(X, R, P) returns the negative binomial pdf at each of the values
in X using the corresponding parameters in R and P. Vector or matrix inputs for
X, R, and P must have the same size, which is also the size of Y. A scalar input
for X, R, or P is expanded to a constant matrix with the same dimensions as the
other inputs. Note that the density function is zero unless the values in X are
integers.

The negative binomial pdf is

$$y = f(x|r, p) = \binom{r + x - 1}{x} p^r q^x I_{(0, 1, \ldots)}(x)$$

The negative binomial pdf models consecutive trials, each having a constant
probability P of success. The parameter R is the number of successes required
before stopping.

**Example**
```
x = (0:10);
y = nbinpdf(x, 3, 0.5);
plot(x, y, '+')
set(gca, 'Xlim', [-0.5, 10.5])
```
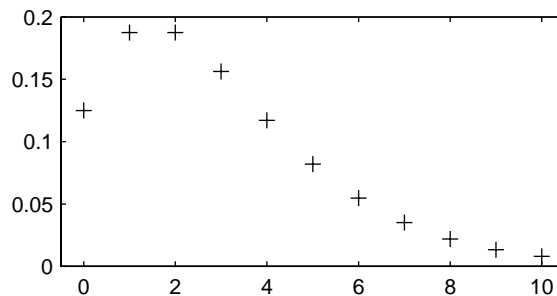


**See Also**      nbincdf, nbininv, nbinrnd, nbinstat, pdf

# nbinrnd

**Purpose**        Random matrices from a negative binomial distribution.

**Syntax**         RND = nbinrnd(R, P)
                   RND = nbinrnd(R, P, m)
                   RND = nbinrnd(R, P, m, n)

**Description**    RND = nbinrnd(R, P) is a matrix of random numbers chosen from a negative
                   binomial distribution with parameters R and P. Vector or matrix inputs for R
                   and P must have the same size, which is also the size of RND. A scalar input for
                   R or P is expanded to a constant matrix with the same dimensions as the other
                   input.

                   RND = nbinrnd(R, P, m) generates random numbers with parameters R and P,
                   where m is a 1-by-2 vector that contains the row and column dimensions of RND.

                   RND = nbinrnd(R, P, m, n) generates random numbers with parameters R
                   and P, where scalars m and n are the row and column dimensions of RND.

                   The negative binomial distribution models consecutive trials, each having a
                   constant probability P of success. The parameter R is the number of successes
                   required before stopping.

**Example**        Suppose you want to simulate a process that has a defect probability of 0.01.
                   How many units might Quality Assurance inspect before finding three
                   defective items?

                       r = nbinrnd(3, 0.01, 1, 6) + 3

                       r =

                           496    142    420    396    851    178

**See Also**       nbincdf, nbininv, nbinpdf, nbinstat

**Purpose**        Mean and variance of the negative binomial distribution.

**Syntax**         [M, V] = nbinstat(R, P)

**Description**    [M, V] = nbinstat(R, P) returns the mean and variance of the negative
                   binomial distribution with parameters R and P. Vector or matrix inputs for R
                   and P must have the same size, which is also the size of M and V. A scalar input
                   for R or P is expanded to a constant matrix with the same dimensions as the
                   other input.

                   The mean of the negative binomial distribution with parameters $r$ and $p$ is $rq/p$,
                   where $q = 1-p$. The variance is $rq/p^2$.

**Example**        p = 0.1:0.2:0.9;
                   r = 1:5;
                   [R, P] = meshgrid(r, p);
                   [M, V] = nbinstat(R, P)

                   M =

                   |   9.0000 |  18.0000 |  27.0000 |  36.0000 |  45.0000 |
                   |----------|----------|----------|----------|----------|
                   |   2.3333 |   4.6667 |   7.0000 |   9.3333 |  11.6667 |
                   |   1.0000 |   2.0000 |   3.0000 |   4.0000 |   5.0000 |
                   |   0.4286 |   0.8571 |   1.2857 |   1.7143 |   2.1429 |
                   |   0.1111 |   0.2222 |   0.3333 |   0.4444 |   0.5556 |

                   V =

                   |  90.0000 | 180.0000 | 270.0000 | 360.0000 | 450.0000 |
                   |----------|----------|----------|----------|----------|
                   |   7.7778 |  15.5556 |  23.3333 |  31.1111 |  38.8889 |
                   |   2.0000 |   4.0000 |   6.0000 |   8.0000 |  10.0000 |
                   |   0.6122 |   1.2245 |   1.8367 |   2.4490 |   3.0612 |
                   |   0.1235 |   0.2469 |   0.3704 |   0.4938 |   0.6173 |

**See Also**       nbincdf, nbininv, nbinpdf, nbinrnd

# ncfcdf

**Purpose**        Noncentral F cumulative distribution function (cdf).

**Syntax**         P = ncfcdf(X, NU1, NU2, DELTA)

**Description**    P = ncfcdf(X, NU1, NU2, DELTA) computes the noncentral F cdf at each of the
                   values in X using the corresponding numerator degrees of freedom in NU1,
                   denominator degrees of freedom in NU2, and positive noncentrality parameters
                   in DELTA. Vector or matrix inputs for X, NU1, NU2, and DELTA must have the same
                   size, which is also the size of P. A scalar input for X, NU1, NU2, or DELTA is
                   expanded to a constant matrix with the same dimensions as the other inputs.

                   The noncentral F cdf is

$$F(x|\nu_1, \nu_2, \delta) = \sum_{j=0}^{\infty} \left( \frac{\left(\frac{1}{2}\delta\right)^j}{j!} e^{-\frac{\delta}{2}} \right) I\left( \frac{\nu_1 \cdot x}{\nu_2 + \nu_1 \cdot x} \middle| \frac{\nu_1}{2} + j, \frac{\nu_2}{2} \right)$$

                   where $I(x/a,b)$ is the incomplete beta function with parameters $a$ and $b$.

**Example**        Compare the noncentral F cdf with $\delta$ = 10 to the F cdf with the same number of
                   numerator and denominator degrees of freedom (5 and 20 respectively).

```
x = (0.01:0.1:10.01)';
p1 = ncfcdf(x, 5, 20, 10);
p  = fcdf(x, 5, 20);
plot(x, p, '--', x, p1, '-')
```
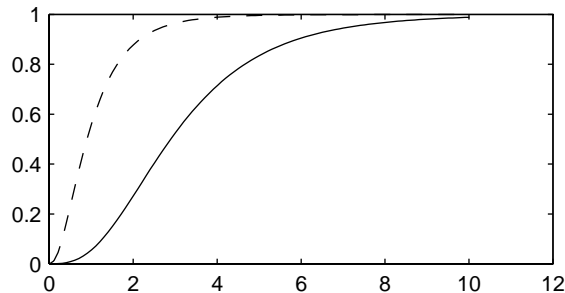
**References**    Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 189–200.

**See Also**    cdf, ncfpdf, ncfinv, ncfrnd, ncfstat

# ncfinv

**Purpose**         Inverse of the noncentral F cumulative distribution function (cdf).

**Syntax**          X = ncfinv(P, NU1, NU2, DELTA)

**Description**     X = ncfinv(P, NU1, NU2, DELTA) returns the inverse of the noncentral F cdf
                    with numerator degrees of freedom NU1, denominator degrees of freedom NU2,
                    and positive noncentrality parameter DELTA for the corresponding probabilities
                    in P. Vector or matrix inputs for P, NU1, NU2, and DELTA must have the same
                    size, which is also the size of X. A scalar input for P, NU1, NU2, or DELTA is
                    expanded to a constant matrix with the same dimensions as the other inputs.

**Example**         One hypothesis test for comparing two sample variances is to take their ratio
                    and compare it to an F distribution. If the numerator and denominator degrees
                    of freedom are 5 and 20 respectively, then you reject the hypothesis that the
                    first variance is equal to the second variance if their ratio is less than that
                    computed below.

                        critical = finv(0.95, 5, 20)

                        critical =

                            2.7109

                    Suppose the truth is that the first variance is twice as big as the second
                    variance. How likely is it that you would detect this difference?

                        prob = 1 - ncfcdf(critical, 5, 20, 2)

                        prob =

                            0.1297

**References**      Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
                    Edition,* John Wiley and Sons, 1993. p. 102–105.

                    Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
                    Distributions-2,* John Wiley and Sons, 1970. pp. 189–200.

**See Also**        icdf, ncfcdf, ncfpdf, ncfrnd, ncfstat

**Purpose**        Noncentral F probability density function.

**Syntax**         Y = ncfpdf(X, NU1, NU2, DELTA)

**Description**    Y = ncfpdf(X, NU1, NU2, DELTA) computes the noncentral F pdf at each of the values in X using the corresponding numerator degrees of freedom in NU1, denominator degrees of freedom in NU2, and positive noncentrality parameters in DELTA. Vector or matrix inputs for X, NU1, NU2, and DELTA must have the same size, which is also the size of Y. A scalar input for P, NU1, NU2, or DELTA is expanded to a constant matrix with the same dimensions as the other inputs.

The F distribution is a special case of the noncentral F where $\delta = 0$. As $\delta$ increases, the distribution flattens like the plot in the example.

**Example**        Compare the noncentral F pdf with $\delta = 10$ to the F pdf with the same number of numerator and denominator degrees of freedom (5 and 20 respectively).

```
x = (0.01:0.1:10.01)';
p1 = ncfpdf(x, 5, 20, 10);
p  = fpdf(x, 5, 20);
plot(x, p, '--', x, p1, '-')
```
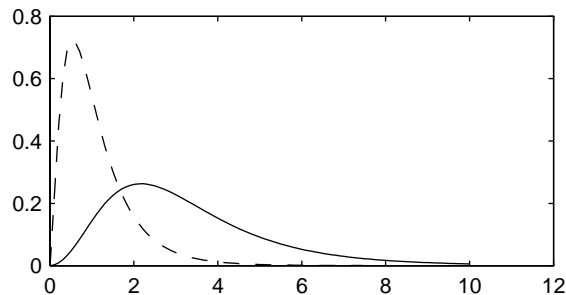


**References**     Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 189–200.

**See Also**       ncfcdf, ncfinv, ncfrnd, ncfstat, pdf

# ncfrnd

**Purpose**        Random matrices from the noncentral F distribution.

**Syntax**         R = ncfrnd(NU1, NU2, DELTA)
                   R = ncfrnd(NU1, NU2, DELTA, m)
                   R = ncfrnd(NU1, NU2, DELTA, m, n)

**Description**    R = ncfrnd(NU1, NU2, DELTA) returns a matrix of random numbers chosen from
                   the noncentral F distribution with parameters NU1, NU2 and DELTA. Vector or
                   matrix inputs for NU1, NU2, and DELTA must have the same size, which is also
                   the size of R. A scalar input for NU1, NU2, or DELTA is expanded to a constant
                   matrix with the same dimensions as the other inputs.

                   R = ncfrnd(NU1, NU2, DELTA, m) returns a matrix of random numbers with
                   parameters NU1, NU2, and DELTA, where m is a 1-by-2 vector that contains the
                   row and column dimensions of R.

                   R = ncfrnd(NU1, NU2, DELTA, m, n) generates random numbers with
                   parameters NU1, NU2, and DELTA, where scalars m and n are the row and column
                   dimensions of R.

**Example**        Compute six random numbers from a noncentral F distribution with 10
                   numerator degrees of freedom, 100 denominator degrees of freedom and a
                   noncentrality parameter, $\delta$, of 4.0. Compare this to the F distribution with the
                   same degrees of freedom.

                       r = ncfrnd(10, 100, 4, 1, 6)

                       r =
                           2.5995     0.8824     0.8220     1.4485     1.4415     1.4864

                       r1 = frnd(10, 100, 1, 6)

                       r1 =
                           0.9826     0.5911     1.0967     0.9681     2.0096     0.6598

**References**     Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
                   Distributions-2,* John Wiley and Sons, 1970. pp. 189–200.

**See Also**       ncfcdf, ncfinv, ncfpdf, ncfstat

**Purpose**      Mean and variance of the noncentral F distribution.

**Syntax**       [M, V] = ncfstat(NU1, NU2, DELTA)

**Description**  [M, V] = ncfstat(NU1, NU2, DELTA) returns the mean and variance of the noncentral F pdf with NU1 and NU2 degrees of freedom and noncentrality parameter DELTA. Vector or matrix inputs for NU1, NU2, and DELTA must have the same size, which is also the size of M and V. A scalar input for NU1, NU2, or DELTA is expanded to a constant matrix with the same dimensions as the other input.

The mean of the noncentral F distribution with parameters $\nu_1$, $\nu_2$, and $\delta$ is

$$\frac{\nu_2(\delta + \nu_1)}{\nu_1(\nu_2 - 2)}$$

where $\nu_2 > 2$.

The variance is

$$2\left(\frac{\nu_2}{\nu_1}\right)^2\left[\frac{(\delta + \nu_1)^2 + (2\delta + \nu_1)(\nu_2 - 2)}{(\nu_2 - 2)^2(\nu_2 - 4)}\right]$$

where $\nu_2 > 4$.

**Example**      [m, v] = ncfstat(10, 100, 4)

m =
      1.4286

v =
      3.9200

**References**   Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* John Wiley and Sons, 1993. p. 73–74.

Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 189–200.

**See Also**     ncfcdf, ncfinv, ncfpdf, ncfrnd

# nctcdf

| | |
|---|---|
| **Purpose** | Noncentral T cumulative distribution function. |
| **Syntax** | P = nctcdf(X, NU, DELTA) |
| **Description** | P = nctcdf(X, NU, DELTA) computes the noncentral T cdf at each of the values in X using the corresponding degrees of freedom in NU and noncentrality parameters in DELTA. Vector or matrix inputs for X, NU, and DELTA must have the same size, which is also the size of P. A scalar input for X, NU, or DELTA is expanded to a constant matrix with the same dimensions as the other inputs. |
| **Example** | Compare the noncentral T cdf with DELTA = 1 to the T cdf with the same number of degrees of freedom (10). |

```
x = (-5:0.1:5)';
p1 = nctcdf(x, 10, 1);
p = tcdf(x, 10);
plot(x, p, '--', x, p1, '-')
```
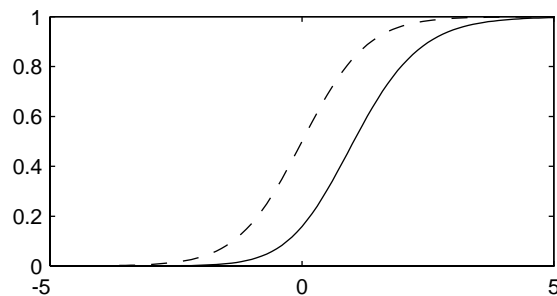


**References**  Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* John Wiley and Sons, 1993. p. 147–148.

Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 201–219.

**See Also**  cdf, nctcdf, nctinv, nctpdf, nctrnd, nctstat

**Purpose**        Inverse of the noncentral T cumulative distribution.

**Syntax**         X = nctinv(P, NU, DELTA)

**Description**    X = nctinv(P, NU, DELTA) returns the inverse of the noncentral T cdf with NU
                   degrees of freedom and noncentrality parameter DELTA for the corresponding
                   probabilities in P. Vector or matrix inputs for P, NU, and DELTA must have the
                   same size, which is also the size of X. A scalar input for P, NU, or DELTA is
                   expanded to a constant matrix with the same dimensions as the other inputs.

**Example**            x = nctinv([0.1 0.2], 10, 1)

                       x =
                          -0.2914      0.1618

**References**     Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
                   Edition,* John Wiley and Sons, 1993. p. 147–148.

                   Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
                   Distributions-2,* John Wiley and Sons, 1970. pp. 201–219.

**See Also**       icdf, nctcdf, nctpdf, nctrnd, nctstat

# nctpdf

**Purpose**        Noncentral T probability density function (pdf).

**Syntax**         Y = nctpdf(X, V, DELTA)

**Description**    Y = nctpdf(X, V, DELTA) computes the noncentral T pdf at each of the values
                   in X using the corresponding degrees of freedom in V and noncentrality
                   parameters in DELTA. Vector or matrix inputs for X, V, and DELTA must have the
                   same size, which is also the size of Y. A scalar input for X, V, or DELTA is
                   expanded to a constant matrix with the same dimensions as the other inputs.

**Example**        Compare the noncentral T pdf with DELTA = 1 to the T pdf with the same
                   number of degrees of freedom (10).

```
x = (-5:0.1:5)';
p1 = nctpdf(x, 10, 1);
p = tpdf(x, 10);
plot(x, p, '--', x, p1, '-')
```
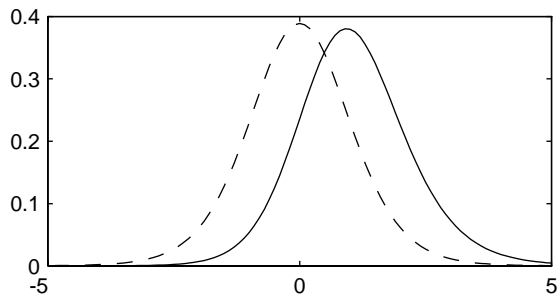


**References**     Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
                   Edition,* John Wiley and Sons, 1993. p. 147–148.

                   Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
                   Distributions-2,* John Wiley and Sons, 1970. pp. 201–219.

**See Also**       nctcdf, nctinv, nctrnd, nctstat, pdf

**Purpose**        Random matrices from noncentral T distribution.

**Syntax**         R = nctrnd(V, DELTA)
                   R = nctrnd(V, DELTA, m)
                   R = nctrnd(V, DELTA, m, n)

**Description**    R = nctrnd(V, DELTA) returns a matrix of random numbers chosen from the
                   noncentral T distribution with parameters V and DELTA. Vector or matrix
                   inputs for V and DELTA must have the same size, which is also the size of R. A
                   scalar input for V or DELTA is expanded to a constant matrix with the same
                   dimensions as the other input.

                   R = nctrnd(V, DELTA, m) returns a matrix of random numbers with
                   parameters V and DELTA, where m is a 1-by-2 vector that contains the row and
                   column dimensions of R.

                   R = nctrnd(V, DELTA, m, n) generates random numbers with parameters V and
                   DELTA, where scalars m and n are the row and column dimensions of R.

**Example**        nctrnd(10, 1, 5, 1)

                   ans =

                       1.6576
                       1.0617
                       1.4491
                       0.2930
                       3.6297

**References**     Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
                   Edition,* John Wiley and Sons, 1993. p. 147–148.

                   Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
                   Distributions-2,* John Wiley and Sons, 1970. pp. 201–219.

**See Also**       nctcdf, nctinv, nctpdf, nctstat

# nctstat

**Purpose**     Mean and variance for the noncentral t distribution.

**Syntax**      [M, V] = nctstat(NU, DELTA)

**Description**  [M, V] = nctstat(NU, DELTA) returns the mean and variance of the
noncentral t pdf with NU degrees of freedom and noncentrality parameter
DELTA. Vector or matrix inputs for NU and DELTA must have the same size, which
is also the size of M and V. A scalar input for NU or DELTA is expanded to a
constant matrix with the same dimensions as the other input.

The mean of the noncentral t distribution with parameters $\nu$ and $\delta$ is

$$\frac{\delta(\nu/2)^{1/2}\Gamma((\nu-1)/2)}{\Gamma(\nu/2)}$$

where $\nu > 1$.

The variance is

$$\frac{\nu}{(\nu-2)}(1+\delta^2) - \frac{\nu}{2}\delta^2\left[\frac{\Gamma((\nu-1)/2)}{\Gamma(\nu/2)}\right]^2$$

where $\nu > 2$.

**Example**
```
[m, v] = nctstat(10, 1)

m =
    1.0837

v =
    1.3255
```

**References**  Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
Edition,* John Wiley and Sons, 1993. p. 147–148.

Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
Distributions-2,* John Wiley and Sons, 1970. pp. 201–219.

**See Also**    nctcdf, nctinv, nctpdf, nctrnd

**Purpose**     Noncentral chi-square cumulative distribution function (cdf).

**Syntax**      P = ncx2cdf(X, V, DELTA)

**Description**  P = ncx2cdf(X, V, DELTA) computes the noncentral chi-square cdf at each of the values in X using the corresponding degrees of freedom in V and positive noncentrality parameters in DELTA. Vector or matrix inputs for X, V, and DELTA must have the same size, which is also the size of P. A scalar input for X, V, or DELTA is expanded to a constant matrix with the same dimensions as the other inputs.

Some texts refer to this distribution as the generalized Rayleigh, Rayleigh-Rice, or Rice distribution.

The noncentral chi-square cdf is

$$F(x|\nu, \delta) = \sum_{j=0}^{\infty} \left( \frac{\left(\frac{1}{2}\delta\right)^{j}}{j!} e^{-\frac{\delta}{2}} \right) Pr[\chi^2_{\nu + 2j} \leq x]$$

**Example**
```
x = (0:0.1:10)';
p1 = ncx2cdf(x, 4, 2);
p = chi2cdf(x, 4);
plot(x, p, '--', x, p1, '-')
```
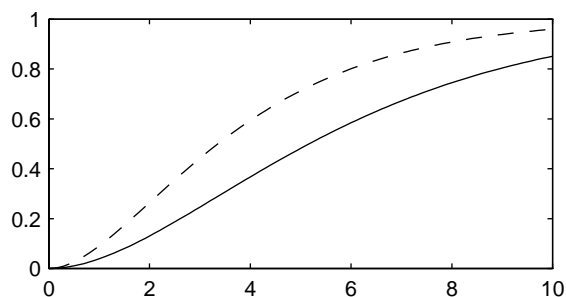
# ncx2cdf

**References**     Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 130–148.

**See Also**     cdf, ncx2inv, ncx2pdf, ncx2rnd, ncx2stat

**Purpose**          Inverse of the noncentral chi-square cdf.

**Syntax**           X = ncx2inv(P, V, DELTA)

**Description**      X = ncx2inv(P, V, DELTA) returns the inverse of the noncentral chi-square cdf
with parameters V and DELTA at the corresponding probabilities in P. Vector or
matrix inputs for P, V, and DELTA must have the same size, which is also the size
of X. A scalar input for P, V, or DELTA is expanded to a constant matrix with the
same dimensions as the other inputs.

**Algorithm**       ncx2inv uses Newton's method to converge to the solution.

**Example**          ncx2inv([0.01  0.05  0.1], 4, 2)

                     ans =

                         0.4858      1.1498      1.7066

**References**      Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
Edition,* John Wiley and Sons, 1993. p. 50–52.

Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
Distributions-2,* John Wiley and Sons, 1970. pp. 130–148.

**See Also**         icdf, ncx2cdf, ncx2pdf, ncx2rnd, ncx2stat

# ncx2pdf

**Purpose**        Noncentral chi-square probability density function (pdf).

**Syntax**        Y = ncx2pdf(X, V, DELTA)

**Description**    Y = ncx2pdf(X, V, DELTA) computes the noncentral chi-square pdf at each of the values in X using the corresponding degrees of freedom in V and positive noncentrality parameters in DELTA. Vector or matrix inputs for X, V, and DELTA must have the same size, which is also the size of Y. A scalar input for X, V, or DELTA is expanded to a constant matrix with the same dimensions as the other inputs.

Some texts refer to this distribution as the generalized Rayleigh, Rayleigh-Rice, or Rice distribution.

**Example**      As the noncentrality parameter $\delta$ increases, the distribution flattens as shown in the plot.

```
x = (0: 0. 1: 10)';
p1 = ncx2pdf(x, 4, 2);
p = chi2pdf(x, 4);
plot(x, p, '--', x, p1, '-')
```
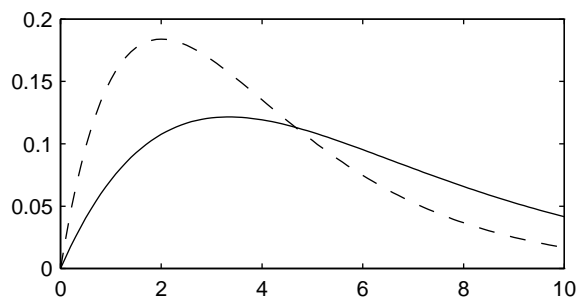


**References**  Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 130–148.

**See Also**    ncx2cdf, ncx2inv, ncx2rnd, ncx2stat, pdf

**Purpose**        Random matrices from the noncentral chi-square distribution.

**Syntax**         R = ncx2rnd(V, DELTA)
                   R = ncx2rnd(V, DELTA, m)
                   R = ncx2rnd(V, DELTA, m, n)

**Description**    R = ncx2rnd(V, DELTA) returns a matrix of random numbers chosen from the
                   non-central chi-square distribution with parameters V and DELTA. Vector or
                   matrix inputs for V and DELTA must have the same size, which is also the size
                   of R. A scalar input for V or DELTA is expanded to a constant matrix with the
                   same dimensions as the other input.

                   R = ncx2rnd(V, DELTA, m) returns a matrix of random numbers with
                   parameters V and DELTA, where m is a 1-by-2 vector that contains the row and
                   column dimensions of R.

                   R = ncx2rnd(V, DELTA, m, n) generates random numbers with parameters V and
                   DELTA, where scalars m and n are the row and column dimensions of R.

**Example**        ncx2rnd(4, 2, 6, 3)

                   ans =

|          |         |          |
|----------|---------|----------|
| 6. 8552  | 5. 9650 | 11. 2961 |
| 5. 2631  | 4. 2640 | 5. 9495  |
| 9. 1939  | 6. 7162 | 3. 8315  |
| 10. 3100 | 4. 4828 | 7. 1653  |
| 2. 1142  | 1. 9826 | 4. 6400  |
| 3. 8852  | 5. 3999 | 0. 9282  |

**References**     Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second
                   Edition,* John Wiley and Sons, 1993. p. 50–52.

                   Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate
                   Distributions-2,* John Wiley and Sons, 1970. pp. 130–148.

**See Also**       ncx2cdf, ncx2inv, ncx2pdf, ncx2stat

# ncx2stat

| | |
|---|---|
| **Purpose** | Mean and variance for the noncentral chi-square distribution. |
| **Syntax** | [M, V] = ncx2stat(NU, DELTA) |
| **Description** | [M, V] = ncx2stat(NU, DELTA) returns the mean and variance of the noncentral chi-square pdf with NU degrees of freedom and noncentrality parameter DELTA. Vector or matrix inputs for NU and DELTA must have the same size, which is also the size of M and V. A scalar input for NU or DELTA is expanded to a constant matrix with the same dimensions as the other input. |

The mean of the noncentral chi-square distribution with parameters $\nu$ and $\delta$ is $\nu + \delta$, and the variance is $2(\nu + 2\delta)$.

| | |
|---|---|
| **Example** | [m, v] = ncx2stat(4, 2)<br><br>m =<br>   6<br><br>v =<br>   16 |
| **References** | Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* John Wiley and Sons, 1993. p. 50–52. |

Johnson, N., and S. Kotz, *Distributions in Statistics: Continuous Univariate Distributions-2,* John Wiley and Sons, 1970. pp. 130–148.

| | |
|---|---|
| **See Also** | ncx2cdf, ncx2inv, ncx2pdf, ncx2rnd |

**Purpose**        Nonlinear least-squares data fitting by the Gauss-Newton method.

**Syntax**         [beta, r, J] = nlinfit(X, y, FUN, beta0)

**Description**    beta = nlinfit(X, y, FUN, beta0) returns the coefficients of the nonlinear
                   function described in FUN. FUN can be a function handle specified using @, an
                   inline function, or a quoted text string containing the name of a function.

                   The function FUN has the form $\hat{y} = f(\beta, X)$. It returns the predicted values of $y$
                   given initial parameter estimates $\beta$ and the independent variable $X$.

                   The matrix X has one column per independent variable. The response, y, is a
                   column vector with the same number of rows as X.

                   [beta, r, J] = nlinfit(X, y, FUN, beta0) returns the fitted coefficients, beta,
                   the residuals, r, and the Jacobian, J, for use with nlintool to produce error
                   estimates on predictions.

**Example**
```
load reaction
betafit = nlinfit(reactants, rate, @hougen, beta)

betafit =

    1.2526
    0.0628
    0.0400
    0.1124
    1.1914
```

**See Also**       nlintool

# nlintool

**Purpose**        Fits a nonlinear equation to data and displays an interactive graph.

**Syntax**         nlintool(x, y, FUN, beta0)
                   nlintool(x, y, FUN, beta0, alpha)
                   nlintool(x, y, FUN, beta0, alpha, 'xname', 'yname')

**Description**    nlintool(x, y, FUN, beta0) is a prediction plot that provides a nonlinear curve fit to (*x,y*) data. It plots a 95% global confidence interval for predictions as two red curves. beta0 is a vector containing initial guesses for the parameters.

nlintool(x, y, FUN, beta0, alpha) plots a 100(1-alpha)% confidence interval for predictions.

nlintool displays a "vector" of plots, one for each column of the matrix of inputs, x. The response variable, y, is a column vector that matches the number of rows in x.

The default value for alpha is 0.05, which produces 95% confidence intervals.

nlintool(x, y, FUN, beta0, alpha, 'xname', 'yname') labels the plot using the string matrix, 'xname' for the x variables and the string 'yname' for the y variable.

You can drag the dotted white reference line and watch the predicted values update simultaneously. Alternatively, you can get a specific prediction by typing the value for x into an editable text field. Use the pop-up menu labeled **Export** to move specified variables to the base workspace. You can change the type of confidence bounds using the **Bounds** menu.

**Example**        See "Nonlinear Regression Models" on page 1-100.

**See Also**       nlinfit, rstool

**Purpose**          Confidence intervals on estimates of parameters in nonlinear models.

**Syntax**           ci = nlparci(beta, r, J)

**Description**      nlparci(beta, r, J) returns the 95% confidence interval ci on the nonlinear
                     least squares parameter estimates beta, given the residuals r and the
                     Jacobian matrix J at the solution. The confidence interval calculation is valid
                     for systems where the number of rows of J exceeds the length of beta.

                     nlparci uses the outputs of nlinfit for its inputs.

**Example**          Continuing the example from nlinfit:

                     ```
                     load reaction
                     [beta, resids, J] = nlinfit(reactants, rate, 'hougen', beta);
                     ci = nlparci(beta, resids, J)

                     ci =

                         -1.0798    3.3445
                         -0.0524    0.1689
                         -0.0437    0.1145
                         -0.0891    0.2941
                         -1.1719    3.7321
                     ```

**See Also**         nlinfit, nlintool, nlpredci

# nlpredci

**Purpose**  Confidence intervals on predictions of nonlinear models.

**Syntax**
ypred = nlpredci(FUN, inputs, beta, r, J)
[ypred, delta] = nlpredci(FUN, inputs, beta, r, J)
ypred = nlpredci(FUN, inputs, beta, r, J, alpha, '*simopt*', '*predopt*')

**Description**  ypred = nlpredci(FUN, inputs, beta, r, J) returns the predicted responses, ypred, given the fitted parameters beta, residuals r, and the Jacobian matrix J. inputs is a matrix of values of the independent variables in the nonlinear function.

[ypred, delta] = nlpredci(FUN, inputs, beta, r, J) also returns the half-width, delta, of confidence intervals for the nonlinear least squares predictions. The confidence interval calculation is valid for systems where the length of r exceeds the length of beta and J is of full column rank. The interval [ypred-delta, ypred+delta] is a 95% non-simultaneous confidence interval for the true value of the function at the specified input values.

ypred = nlpredci(FUN, inputs, beta, r, J, alpha, '*simopt*', '*predopt*') controls the type of confidence intervals. The confidence level is 100(1-alpha)%. '*simopt*' can be 'on' for simultaneous intervals or 'off' (the default) for non-simultaneous intervals. '*predopt*' can be 'curve' (the default) for confidence intervals for the function value at the inputs, or 'observation' for confidence intervals for a new response value.

nlpredci uses the outputs of nlinfit for its inputs.

**Example**  Continuing the example from nlinfit, we can determine the predicted function value at [100 300 80] and the half-width of a confidence interval for it.

```
load reaction
[beta, resids, J] = nlinfit(reactants, rate, @hougen, beta);
[ypred, delta] = nlpredci(@hougen, [100 300 80], beta, resids, J)

ypred =
    13

delta =
    1.4277
```

**See Also**    nlinfit, nlintool, nlparci

# normcdf

**Purpose**  Normal cumulative distribution function (cdf).

**Syntax**  P = normcdf(X, MU, SIGMA)

**Description**  normcdf(X, MU, SIGMA) computes the normal cdf at each of the values in X using the corresponding parameters in MU and SIGMA. Vector or matrix inputs for X, MU, and SIGMA must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in SIGMA must be positive.

The normal cdf is

$$p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{x} e^{\frac{-(t-\mu)^2}{2\sigma^2}} \, dt$$

The result, $p$, is the probability that a single observation from a normal distribution with parameters $\mu$ and $\sigma$ will fall in the interval (-∞ $x$].

The *standard normal* distribution has $\mu = 0$ and $\sigma = 1$.

**Examples**  What is the probability that an observation from a standard normal distribution will fall on the interval [-1 1]?

```
p = normcdf([-1 1]);
p(2) - p(1)

ans =

    0.6827
```

More generally, about 68% of the observations from a normal distribution fall within one standard deviation, $\sigma$, of the mean, $\mu$.

**See Also**  cdf, normfit, norminv, normpdf, normplot, normrnd, normspec, normstat

**Purpose**        Parameter estimates and confidence intervals for normal data.

**Syntax**         [muhat, sigmahat, muci, sigmaci] = normfit(X)
                   [muhat, sigmahat, muci, sigmaci] = normfit(X, alpha)

**Description**    [muhat, sigmahat, muci, sigmaci] = normfit(X) returns estimates muhat
                   and sigmahat of the normal distribution parameters μ and σ, given the matrix
                   of data X. muci and sigmaci are 95% confidence intervals and have two rows
                   and as many columns as matrix X. The top row is the lower bound of the
                   confidence interval and the bottom row is the upper bound.

                   [muhat, sigmahat, muci, sigmaci] = normfit(X, alpha) gives estimates and
                   100(1-alpha)% confidence intervals. For example, alpha = 0.01 gives 99%
                   confidence intervals.

**Example**        In this example the data is a two-column random normal matrix. Both columns
                   have μ = 10 and σ = 2. Note that the confidence intervals below contain the
                   "true values."

```
r = normrnd(10, 2, 100, 2);
[mu, sigma, muci, sigmaci] = normfit(r)

mu =
    10.1455   10.0527

sigma =
     1.9072    2.1256

muci =
     9.7652    9.6288
    10.5258   10.4766

sigmaci =
     1.6745    1.8663
     2.2155    2.4693
```

**See Also**       normcdf, norminv, normpdf, normplot, normrnd, normspec, normstat, betafit,
                   binofit, expfit, gamfit, poissfit, unifit, weibfit

# norminv

**Purpose**     Inverse of the normal cumulative distribution function (cdf).

**Syntax**      X = norminv(P, MU, SIGMA)

**Description**   X = norminv(P, MU, SIGMA) computes the inverse of the normal cdf with
parameters MU and SIGMA at the corresponding probabilities in P. Vector or
matrix inputs for P, MU, and SIGMA must all have the same size. A scalar input
is expanded to a constant matrix with the same dimensions as the other inputs.
The parameters in SIGMA must be positive, and the values in P must lie on the
interval [0 1].

We define the normal inverse function in terms of the normal cdf as

$$x = F^{-1}(p|\mu, \sigma) = \{x : F(x|\mu, \sigma) = p\}$$

where

$$p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{x} e^{\frac{-(t-\mu)^2}{2\sigma^2}} dt$$

The result, $x$, is the solution of the integral equation above where you supply
the desired probability, $p$.

**Examples**    Find an interval that contains 95% of the values from a standard normal
distribution.

    x = norminv([0.025  0.975], 0, 1)

    x =
       -1.9600      1.9600

Note the interval x is not the only such interval, but it is the shortest.

    xl = norminv([0.01  0.96], 0, 1)

    xl =
       -2.3263      1.7507

The interval xl also contains 95% of the probability, but it is longer than x.

**See Also**    icdf, normfit, normfit, normpdf, normplot, normrnd, normspec, normstat

**Purpose**        Normal probability density function (pdf).

**Syntax**         Y = normpdf(X, MU, SIGMA)

**Description**    normpdf(X, MU, SIGMA) computes the normal pdf at each of the values in X using
                  the corresponding parameters in MU and SIGMA. Vector or matrix inputs for X,
                  MU, and SIGMA must all have the same size. A scalar input is expanded to a
                  constant matrix with the same dimensions as the other inputs. The parameters
                  in SIGMA must be positive.

                  The normal pdf is

$$y = f(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

                  The *likelihood function* is the pdf viewed as a function of the parameters.
                  Maximum likelihood estimators (MLEs) are the values of the parameters that
                  maximize the likelihood function for a fixed value of x.

                  The *standard normal* distribution has $\mu = 0$ and $\sigma = 1$.

                  If *x* is standard normal, then $x\sigma + \mu$ is also normal with mean $\mu$ and standard
                  deviation $\sigma$. Conversely, if *y* is normal with mean $\mu$ and standard deviation $\sigma$,
                  then $x = (y-\mu) / \sigma$ is standard normal.

**Examples**       mu = [0:0.1:2];
                  [y i] = max(normpdf(1.5, mu, 1));
                  MLE = mu(i)

                  MLE =

                       1.5000

**See Also**       normfit, normfit, norminv, normplot, normrnd, normspec, normstat, pdf

# normplot

**Purpose**        Normal probability plot for graphical normality testing.

**Syntax**         normplot(X)
                   h = normplot(X)

**Description**    normplot(X) displays a normal probability plot of the data in X. For matrix X, normplot displays a line for each column of X.

The plot has the sample data displayed with the plot symbol ' +' . Superimposed on the plot is a line joining the first and third quartiles of each column of X (a robust linear fit of the sample order statistics.) This line is extrapolated out to the ends of the sample to help evaluate the linearity of the data.

If the data does come from a normal distribution, the plot will appear linear. Other probability density functions will introduce curvature in the plot.

h = normplot(X) returns a handle to the plotted lines.

**Examples**       Generate a normal sample and a normal probability plot of the data.

```
x = normrnd(0, 1, 50, 1);
h = normplot(x);
```
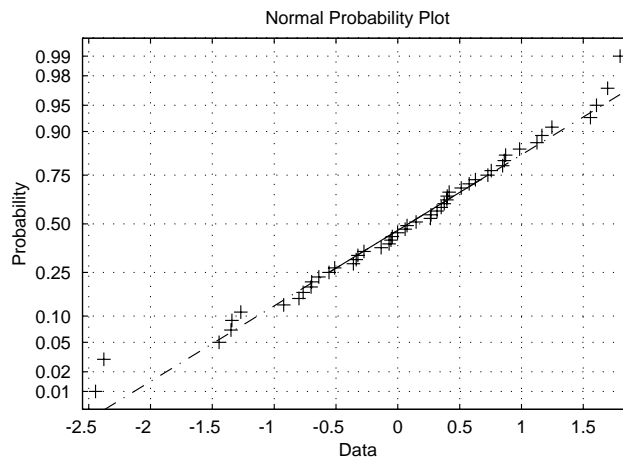
The plot is linear, indicating that you can model the sample by a normal distribution.

**See Also**    cdfplot, hist, normfit, normfit, norminv, normpdf, normrnd, normspec, normstat

# normrnd

| | |
|---|---|
| **Purpose** | Random numbers from the normal distribution. |
| **Syntax** | R = normrnd(MU, SIGMA)<br>R = normrnd(MU, SIGMA, m)<br>R = normrnd(MU, SIGMA, m, n) |

**Description**  R = normrnd(MU, SIGMA) generates normal random numbers with mean MU and standard deviation SIGMA. Vector or matrix inputs for MU and SIGMA must have the same size, which is also the size of R. A scalar input for MU or SIGMA is expanded to a constant matrix with the same dimensions as the other input.

R = normrnd(MU, SIGMA, m) generates normal random numbers with parameters MU and SIGMA, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = normrnd(MU, SIGMA, m, n) generates normal random numbers with parameters MU and SIGMA, where scalars m and n are the row and column dimensions of R.

**Examples**

```
n1 = normrnd(1:6, 1./(1:6))

n1 =
    2.1650    2.3134    3.0250    4.0879    4.8607    6.2827

n2 = normrnd(0, 1, [1 5])

n2 =
    0.0591    1.7971    0.2641    0.8717    -1.4462

n3 = normrnd([1 2 3;4 5 6], 0.1, 2, 3)

n3 =
    0.9299    1.9361    2.9640
    4.1246    5.0577    5.9864
```

**See Also**  normfit, normfit, norminv, normpdf, normplot, normspec, normstat

**Purpose**        Plot normal density between specification limits.

**Syntax**         p = normspec(specs, mu, sigma)
                   [p, h] = normspec(specs, mu, sigma)

**Description**    p = normspec(specs, mu, sigma) plots the normal density between a lower
                   and upper limit defined by the two elements of the vector specs, where mu and
                   sigma are the parameters of the plotted normal distribution.

                   [p, h] = normspec(specs, mu, sigma) returns the probability p of a sample
                   falling between the lower and upper limits. h is a handle to the line objects.

                   If specs(1) is -Inf, there is no lower limit, and similarly if specs(2) = Inf,
                   there is no upper limit.

**Example**        Suppose a cereal manufacturer produces 10 ounce boxes of corn flakes.
                   Variability in the process of filling each box with flakes causes a 1.25 ounce
                   standard deviation in the true weight of the cereal in each box. The average box
                   of cereal has 11.5 ounces of flakes. What percentage of boxes will have less than
                   10 ounces?

                       normspec([10 Inf], 11.5, 1.25)
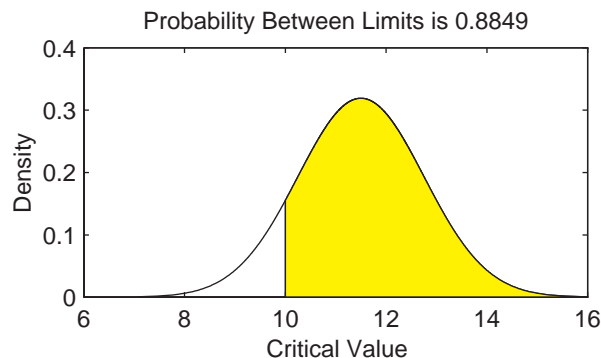


**See Also**       capaplot, disttool, histfit, normfit, normfit, norminv, normpdf, normplot,
                   normrnd, normstat

# normstat

| | |
|---|---|
| **Purpose** | Mean and variance for the normal distribution. |
| **Syntax** | [M,V] = normstat(MU,SIGMA) |
| **Description** | [M,V] = normstat(MU,SIGMA) returns the mean and variance for the normal distribution with parameters MU and SIGMA. Vector or matrix inputs for MU and SIGMA must have the same size, which is also the size of M and V. A scalar input for MU or SIGMA is expanded to a constant matrix with the same dimensions as the other input. |

The mean of the normal distribution with parameters $\mu$ and $\sigma$ is $\mu$, and the variance is $\sigma^2$.

**Examples**

```
n = 1:5;
[m,v] = normstat(n'*n, n'*n)
[m,v] = normstat(n'*n, n'*n)

m =
      1      2      3      4      5
      2      4      6      8     10
      3      6      9     12     15
      4      8     12     16     20
      5     10     15     20     25

v =
      1      4      9     16     25
      4     16     36     64    100
      9     36     81    144    225
     16     64    144    256    400
     25    100    225    400    625
```

**See Also**  normfit, normfit, norminv, normpdf, normplot, normrnd, normspec

| | |
|---|---|
| **Purpose** | Pareto charts for Statistical Process Control. |
| **Syntax** | pareto(y)<br>pareto(y, names)<br>h = pareto(...) |

**Description**    pareto(y, names) displays a Pareto chart where the values in the vector y are drawn as bars in descending order. Each bar is labeled with the associated value in the string matrix names. pareto(y) labels each bar with the index of the corresponding element in y.

The line above the bars shows the cumulative percentage.

pareto(y, names) labels each bar with the row of the string matrix names that corresponds to the plotted element of y.

h = pareto(...) returns a combination of patch and line handles.

**Example**    Create a Pareto chart from data measuring the number of manufactured parts rejected for various types of defects.

```
defects = ['pits';'cracks';'holes';'dents'];
quantity = [5 3 19 25];
pareto(quantity, defects)
```
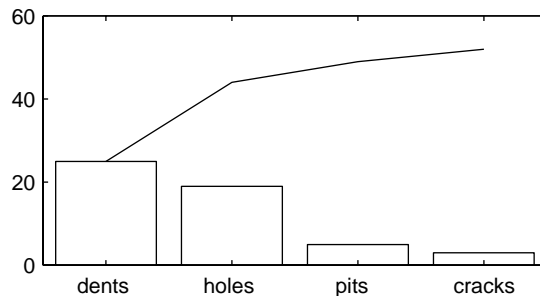


**See Also**    bar, capaplot, ewmaplot, hist, histfit, schart, xbarplot

# pcacov

**Purpose**          Principal Components Analysis (PCA) using the covariance matrix.

**Syntax**           pc = pcacov(X)
                     [pc, latent, explained] = pcacov(X)

**Description**      [pc, latent, explained] = pcacov(X) takes the covariance matrix X and
                     returns the principal components in pc, the eigenvalues of the covariance
                     matrix of X in latent, and the percentage of the total variance in the
                     observations explained by each eigenvector in explained.

**Example**              load hald
                         covx = cov(ingredients);
                         [pc, variances, explained] = pcacov(covx)

                         pc =

                              0.0678    -0.6460     0.5673    -0.5062
                              0.6785    -0.0200    -0.5440    -0.4933
                             -0.0290     0.7553     0.4036    -0.5156
                             -0.7309    -0.1085    -0.4684    -0.4844

                         variances =

                            517.7969
                             67.4964
                             12.4054
                              0.2372

                         explained =

                             86.5974
                             11.2882
                              2.0747
                              0.0397

**References**       Jackson, J. E*., A User's Guide to Principal Components,* John Wiley and Sons,
                     Inc. 1991. pp. 1–25.

**See Also**         barttest, pcares, princomp

**Purpose**        Residuals from a Principal Components Analysis.

**Syntax**         residuals = pcares(X, ndim)

**Description**    pcares(X, ndim) returns the residuals obtained by retaining ndim principal
                   components of X. Note that ndim is a scalar and must be less than the number
                   of columns in X. Use the data matrix, *not* the covariance matrix, with this
                   function.

**Example**        This example shows the drop in the residuals from the first row of the Hald
                   data as the number of component dimensions increase from one to three.

```
load hald
r1 = pcares(ingredients, 1);
r2 = pcares(ingredients, 2);
r3 = pcares(ingredients, 3);

r11 = r1(1, :)
r11 =

    2.0350    2.8304   -6.8378    3.0879

r21 = r2(1, :)
r21 =

   -2.4037    2.6930   -1.6482    2.3425

r31 = r3(1, :)
r31 =

    0.2008    0.1957    0.2045    0.1921
```

**Reference**     Jackson, J. E., *A User's Guide to Principal Components,* John Wiley and Sons,
                  Inc. 1991. pp. 1–25.

**See Also**      barttest, pcacov, princomp

# pdf

| | |
|---|---|
| **Purpose** | Probability density function (pdf) for a specified distribution. |
| **Syntax** | Y = pdf('name', X, A1, A2, A3) |

**Description**   pdf('*name*', X, A1, A2, A3) returns a matrix of densities, where '*name*' is a string containing the name of the distribution. X is a matrix of values, and A1, A2, and A3 are matrices of distribution parameters. Depending on the distribution, some of the parameters may not be necessary.

Vector or matrix inputs for X, A1, A2, and A3 must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

pdf is a utility routine allowing access to all the pdfs in the Statistics Toolbox using the name of the distribution as a parameter. See "Overview of the Distributions" on page 1-12 for the list of available distributions.

**Examples**

```
p = pdf('Normal', -2:2, 0, 1)

p =
    0.0540    0.2420    0.3989    0.2420    0.0540

p = pdf('Poisson', 0:4, 1:5)

p =
    0.3679    0.2707    0.2240    0.1954    0.1755
```

**See Also**   betapdf, binopdf, cdf, chi2pdf, exppdf, fpdf, gampdf, geopdf, hygepdf, lognpdf, nbinpdf, ncfpdf, nctpdf, ncx2pdf, normpdf, poisspdf, raylpdf, tpdf, unidpdf, unifpdf, weibpdf

**Purpose**     Pairwise distance between observations.

**Syntax**      Y = pdist(X)
                Y = pdist(X, '*metric*')
                Y = pdist(X, 'minkowski', p)

**Description**  Y = pdist(X) computes the Euclidean distance between pairs of objects in
                $m$-by-$n$ matrix X, which is treated as $m$ vectors of size $n$. For a dataset made up
                of $m$ objects, there are $(m-1) \cdot m/2$ pairs.

                The output, Y, is a vector of length $(m-1) \cdot m/2$, containing the distance
                information. The distances are arranged in the order (1,2), (1,3), ..., (1,$m$),
                (2,3), ..., (2,$m$), ..., ..., ($m$-1,$m$). Y is also commonly known as a similarity matrix
                or dissimilarity matrix.

                To save space and computation time, Y is formatted as a vector. However, you
                can convert this vector into a square matrix using the squareform function so
                that element $i,j$ in the matrix corresponds to the distance between objects $i$ and
                $j$ in the original dataset.

                Y = pdist(X, '*metric*') computes the distance between objects in the data
                matrix, X, using the method specified by '*metric*', where '*metric*' can be any
                of the following character strings that identify ways to compute the distance.

| String | Meaning |
|---|---|
| 'Euclid' | Euclidean distance (default) |
| 'SEuclid' | Standardized Euclidean distance |
| 'Mahal' | Mahalanobis distance |
| 'CityBlock' | City Block metric |
| 'Minkowski' | Minkowski metric |

                Y = pdist(X, 'minkowski', p) computes the distance between objects in the
                data matrix, X, using the Minkowski metric. p is the exponent used in the
                Minkowski computation which, by default, is 2.

## Mathematical Definitions of Methods

Given an $m$-by-$n$ data matrix X, which is treated as $m$ (1-$by$-$n$) row vectors $x_1$, $x_2$, ..., $x_m$, the various distances between the vector $x_r$ and $x_s$ are defined as follows:

- Euclidean distance

$$d_{rs}^2 = (x_r - x_s)(x_r - x_s)'$$

- Standardized Euclidean distance

$$d_{rs}^2 = (x_r - x_s)D^{-1}(x_r - x_s)'$$

where $D$ is the diagonal matrix with diagonal elements given by $v_j^2$, which denotes the variance of the variable $X_j$ over the $m$ objects.

- Mahalanobis distance

$$d_{rs}^2 = (x_r - x_s)'V^{-1}(x_r - x_s)$$

where $V$ is the sample covariance matrix.

- City Block metric

$$d_{rs} = \sum_{j=1}^{n} |x_{rj} - x_{sj}|$$

- Minkowski metric

$$d_{rs} = \left\lfloor \sum_{j=1}^{n} |x_{rj} - x_{sj}|^p \right\rfloor^{1/p}$$

Notice that for the special case of $p = 1$, the Minkowski metric gives the City Block metric, and for the special case of $p = 2$, the Minkowski metric gives the Euclidean distance.

**Examples**        X = [1 2; 1 3; 2 2; 3 1]

X =
        1       2
        1       3
        2       2
        3       1

Y = pdist(X, 'mahal')
Y =
     2.3452      2.0000      2.3452      1.2247      2.4495      1.2247

Y = pdist(X)
Y =
     1.0000      1.0000      2.2361      1.4142      2.8284      1.4142

squareform(Y)

ans =
          0      1.0000      1.0000      2.2361
     1.0000           0      1.4142      2.8284
     1.0000      1.4142           0      1.4142
     2.2361      2.8284      1.4142           0

**See Also**        cluster, clusterdata, cophenet, dendrogram, inconsistent, linkage,
squareform

# perms

**Purpose**        All permutations.

**Syntax**         P = perms(v)

**Description**    P = perms(v) where v is a row vector of length n, creates a matrix whose rows consist of all possible permutations of the n elements of v. The matrix P contains n! rows and n columns.

perms is only practical when n is less than 8 or 9.

**Example**
```
perms([2 4 6])

ans =

        6        4        2
        4        6        2
        6        2        4
        2        6        4
        4        2        6
        2        4        6
```

**Purpose**        Poisson cumulative distribution function (cdf).

**Syntax**         P = poisscdf(X, LAMBDA)

**Description**    poisscdf(X, LAMBDA) computes the Poisson cdf at each of the values in X using the corresponding parameters in LAMBDA. Vector or matrix inputs for X and LAMBDA must be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other input. The parameters in LAMBDA must be positive.

The Poisson cdf is

$$p = F(x|\lambda) = e^{-\lambda} \sum_{i=0}^{floor(x)} \frac{\lambda^i}{i!}$$

**Examples**      For example, consider a Quality Assurance department that performs random tests of individual hard disks. Their policy is to shut down the manufacturing process if an inspector finds more than four bad sectors on a disk. What is the probability of shutting down the process if the mean number of bad sectors ($\lambda$) is two?

    probability = 1 - poisscdf(4, 2)

    probability =

        0.0527

About 5% of the time, a normally functioning manufacturing process will produce more than four flaws on a hard disk.

Suppose the average number of flaws ($\lambda$) increases to four. What is the probability of finding fewer than five flaws on a hard drive?

    probability = poisscdf(4, 4)

    probability =

        0.6288

This means that this faulty manufacturing process continues to operate after this first inspection almost 63% of the time.

# poisscdf

**See Also**    cdf, poissfit, poissinv, poisspdf, poissrnd, poisstat

**Purpose**        Parameter estimates and confidence intervals for Poisson data.

**Syntax**         lambdahat = poissfit(X)
                   [lambdahat,lambdaci] = poissfit(X)
                   [lambdahat,lambdaci] = poissfit(X,alpha)

**Description**    poissfit(X) returns the maximum likelihood estimate (MLE) of the
                   parameter of the Poisson distribution, $\lambda$, given the data X.

                   [lambdahat,lambdaci] = poissfit(X) also gives 95% confidence intervals in
                   lamdaci.

                   [lambdahat,lambdaci] = poissfit(X,alpha) gives 100(1-alpha)%
                   confidence intervals. For example alpha = 0.001 yields 99.9% confidence
                   intervals.

                   The sample average is the MLE of $\lambda$.

                   $$\hat{\lambda} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

**Example**        r = poissrnd(5,10,2);
                   [l,lci] = poissfit(r)

                   l =
                        7.4000      6.3000

                   lci =
                        5.8000      4.8000
                        9.1000      7.9000

**See Also**       betafit, binofit, expfit, gamfit, poisscdf, poissfit, poissinv, poisspdf,
                   poissrnd, poisstat, unifit, weibfit

# poissinv

**Purpose**     Inverse of the Poisson cumulative distribution function (cdf).

**Syntax**      X = poissinv(P, LAMBDA)

**Description**   poissinv(P, LAMBDA) returns the smallest value X such that the Poisson cdf evaluated at X equals or exceeds P.

**Examples**    If the average number of defects (λ) is two, what is the 95th percentile of the number of defects?

    poissinv(0.95, 2)

    ans =

        5

What is the median number of defects?

    median_defects = poissinv(0.50, 2)

    median_defects =

        2

**See Also**    icdf, poisscdf, poissfit, poisspdf, poissrnd, poisstat

**Purpose**        Poisson probability density function (pdf).

**Syntax**         Y = poisspdf(X, LAMBDA)

**Description**    poisspdf(X, LAMBDA) computes the Poisson pdf at each of the values in X using the corresponding parameters in LAMBDA. Vector or matrix inputs for X and LAMBDA must be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other input. The parameters in LAMBDA must all be positive.

The Poisson pdf is

$$y = f(x|\lambda) = \frac{\lambda^x}{x!}e^{-\lambda}I_{(0,\,1,\,\ldots)}(x)$$

where $x$ can be any nonnegative integer. The density function is zero unless $x$ is an integer.

**Examples**       A computer hard disk manufacturer has observed that flaws occur randomly in the manufacturing process at the average rate of two flaws in a 4 Gb hard disk and has found this rate to be acceptable. What is the probability that a disk will be manufactured with no defects?

In this problem, $\lambda = 2$ and $x = 0$.

    p = poisspdf(0, 2)

    p =
        0.1353

**See Also**       pdf, poisscdf, poissfit, poissinv, poissrnd, poisstat

# poissrnd

| | |
|---|---|
| **Purpose** | Random numbers from the Poisson distribution. |
| **Syntax** | R = poissrnd(LAMBDA)<br>R = poissrnd(LAMBDA, m)<br>R = poissrnd(LAMBDA, m, n) |
| **Description** | R = poissrnd(LAMBDA) generates Poisson random numbers with mean LAMBDA. The size of R is the size of LAMBDA.<br><br>R = poissrnd(LAMBDA, m) generates Poisson random numbers with mean LAMBDA, where m is a 1-by-2 vector that contains the row and column dimensions of R.<br><br>R = poissrnd(LAMBDA, m, n) generates Poisson random numbers with mean LAMBDA, where scalars m and n are the row and column dimensions of R. |
| **Examples** | Generate a random sample of 10 pseudo-observations from a Poisson distribution with $\lambda = 2$. |

```
lambda = 2;

random_sample1 = poissrnd(lambda, 1, 10)
random_sample1 =

    1    0    1    2    1    3    4    2    0    0

random_sample2 = poissrnd(lambda, [1 10])
random_sample2 =

    1    1    1    5    0    3    2    2    3    4

random_sample3 = poissrnd(lambda(ones(1, 10)))
random_sample3 =

    3    2    1    1    0    0    4    0    2    0
```

| | |
|---|---|
| **See Also** | poisscdf, poissfit, poissinv, poisspdf, poisstat |

**Purpose**         Mean and variance for the Poisson distribution.

**Syntax**          M = poisstat(LAMBDA)
                    [M,V] = poisstat(LAMBDA)

**Description**     M = poisstat(LAMBDA) returns the mean of the Poisson distribution with
                    parameter LAMBDA. The size of M is the size of LAMBDA.

                    [M,V] = poisstat(LAMBDA) also returns the variance V of the Poisson
                    distribution.

                    For the Poisson distribution with parameter $\lambda$, both the mean and variance are
                    equal to $\lambda$.

**Examples**        Find the mean and variance for the Poisson distribution with $\lambda = 2$.

```
[m,v] = poisstat([1 2; 3 4])

m =
     1     2
     3     4

v =
     1     2
     3     4
```

**See Also**        poisscdf, poissfit, poissinv, poisspdf, poissrnd

# polyconf

**Purpose**        Polynomial evaluation and confidence interval estimation.

**Syntax**         [Y, DELTA] = polyconf(p, X, S)
                   [Y, DELTA] = polyconf(p, X, S, alpha)

**Description**    [Y, DELTA] = polyconf(p, X, S) uses the optional output S generated by
                   polyfit to give 95% confidence intervals Y ± DELTA. This assumes the errors in
                   the data input to polyfit are independent normal with constant variance.

                   [Y, DELTA] = polyconf(p, X, S, alpha) gives $100(1-alpha)$% confidence
                   intervals. For example, alpha = 0.1 yields 90% intervals.

                   If p is a vector whose elements are the coefficients of a polynomial in
                   descending powers, such as those output from polyfit, then polyconf(p, X) is
                   the value of the polynomial evaluated at X. If X is a matrix or vector, the
                   polynomial is evaluated at each of the elements.

**Examples**       This example gives predictions and 90% confidence intervals for computing
                   time for LU factorizations of square matrices with 100 to 200 columns.

```
n = [100 100:20:200];
for i = n
A = rand(i,i);
tic
B = lu(A);
   t(ceil((i-80)/20)) = toc;
end

[p,S] = polyfit(n(2:7),t,3);
[time,delta_t] = polyconf(p,n(2:7),S,0.1)

time =

    0.0829    0.1476    0.2277    0.3375    0.4912    0.7032

delta_t =

    0.0064    0.0057    0.0055    0.0055    0.0057    0.0064
```

**Purpose**     Polynomial curve fitting.

**Syntax**      [p, S] = polyfit(x, y, n)

**Description**  p = polyfit(x, y, n) finds the coefficients of a polynomial p(x) of degree n
that fits the data, p(x(i)) to y(i), in a least-squares sense. The result p is a
row vector of length n+1 containing the polynomial coefficients in descending
powers.

$$p(x) = p_1 x^n + p_2 x^{n-1} + \ldots + p_n x + p_{n+1}$$

[p, S] = polyfit(x, y, n) returns polynomial coefficients p and matrix S for
use with polyval to produce error estimates on predictions. If the errors in the
data, y, are independent normal with constant variance, polyval will produce
error bounds which contain at least 50% of the predictions.

You may omit S if you are not going to pass it to polyval or polyconf for
calculating error estimates.

The polyfit function is part of the standard MATLAB language.

**Example**     [p, S] = polyfit(1:10, [1:10] + normrnd(0, 1, 1, 10), 1)

p =

    1.0300      0.4561

S =

  -19.6214    -2.8031
        0     -1.4639
    8.0000          0
    2.3180          0

**See Also**    polyval, polytool, polyconf

# polytool

| | |
|---|---|
| **Purpose** | Interactive plot for prediction of fitted polynomials. |
| **Syntax** | polytool (x, y)<br>polytool (x, y, n)<br>polytool (x, y, n, alpha) |
| **Description** | polytool (x, y) fits a line to the column vectors x and y and displays an interactive plot of the result. This plot is graphic user interface for exploring the effects of changing the polynomial degree of the fit. The plot shows the fitted curve and 95% global confidence intervals on a new predicted value for the curve. Text with current predicted value of *y* and its uncertainty appears to the left of the *y*-axis. |

polytool (x, y, n) initially fits a polynomial of order n.

polytool (x, y, n, alpha) plots $100(1-\text{alpha})\%$ confidence intervals on the predicted values.

polytool fits by least-squares using the regression model

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \ldots + \beta_n x_i^n + \varepsilon_i$$

$$\varepsilon_i \sim N(0, \sigma^2) \quad \forall i$$

$$Cov(\varepsilon_i, \varepsilon_j) = 0 \quad \forall i, j$$

Evaluate the function by typing a value in the *x*-axis edit box or by dragging the vertical reference line on the plot. The shape of the pointer changes from an arrow to a cross hair when you are over the vertical line to indicate that the line can be dragged. The predicted value of *y* will update as you drag the reference line.

The argument n controls the degree of the polynomial fit. To change the degree of the polynomial, choose from the pop-up menu at the top of the figure. To change the type of confidence intervals, use the **Bounds** menu. To change from least squares to a robust fitting method, use the **Method** menu.

When you are done, press the **Close** button.

**Purpose**          Polynomial evaluation.

**Syntax**          Y = polyval(p, X)
                    [Y, DELTA] = polyval(p, X, S)

**Description**     Y = polyval(p, X) returns the predicted value of a polynomial given its
                    coefficients, p, at the values in X.

                    [Y, DELTA] = polyval(p, X, S) uses the optional output S generated by
                    polyfit to generate error estimates, Y ± DELTA. If the errors in the data input
                    to polyfit are independent normal with constant variance, Y ± DELTA contains
                    at least 50% of the predictions.

                    If p is a vector whose elements are the coefficients of a polynomial in
                    descending powers, then polyval(p, X) is the value of the polynomial
                    evaluated at X. If X is a matrix or vector, the polynomial is evaluated at each of
                    the elements.

                    The polyval function is part of the standard MATLAB language.

**Examples**        Simulate the function $y = x$, adding normal random errors with a standard
                    deviation of 0.1. Then use polyfit to estimate the polynomial coefficients. Note
                    that predicted Y values are within DELTA of the integer X in every case.

```
[p, S] = polyfit(1:10, (1:10) + normrnd(0, 0.1, 1, 10), 1);
X = magic(3);
[Y, D] = polyval(p, X, S)

Y =
    8.0696    1.0486    6.0636
    3.0546    5.0606    7.0666
    4.0576    9.0726    2.0516

D =
    0.0889    0.0951    0.0861
    0.0889    0.0861    0.0870
    0.0870    0.0916    0.0916
```

**See Also**        polyfit, polytool, polyconf

# prctile

**Purpose**          Percentiles of a sample.

**Syntax**           Y = prctile(X, p)

**Description**      Y = prctile(X, p) calculates a value that is greater than p percent of the values in X. The values of p must lie in the interval [0 100].

For vectors, prctile(X, p) is the pth percentile of the elements in X. For instance, if p = 50 then Y is the median of X.

For matrix X and scalar p, prctile(X, p) is a row vector containing the pth percentile of each column. If p is a vector, the $i$th row of Y is p(i) of X.

**Examples**         x = (1:5)'*(1:5)

```
x =
     1     2     3     4     5
     2     4     6     8    10
     3     6     9    12    15
     4     8    12    16    20
     5    10    15    20    25

y = prctile(x, [25 50 75])

y =
    1.7500    3.5000    5.2500    7.0000    8.7500
    3.0000    6.0000    9.0000   12.0000   15.0000
    4.2500    8.5000   12.7500   17.0000   21.2500
```

| | |
|---|---|
| **Purpose** | Principal Components Analysis (PCA). |

**Syntax**

```
PC = princomp(X)
[PC, SCORE, latent, tsquare] = princomp(X)
```

**Description**    [PC, SCORE, latent, tsquare] = princomp(X) takes a data matrix X and returns the principal components in PC, the so-called Z-scores in SCORE, the eigenvalues of the covariance matrix of X in latent, and Hotelling's $T^2$ statistic for each data point in tsquare.

The Z-scores are the data formed by transforming the original data into the space of the principal components. The values of the vector, latent, are the variance of the columns of SCORE. Hotelling's $T^2$ is a measure of the multivariate distance of each observation from the center of the data set.

**Example**    Compute principal components for the ingredients data in the Hald dataset, and the variance accounted for by each component.

```
load hald;
[pc, score, latent, tsquare] = princomp(ingredients);
pc, latent

pc =
    0.0678   -0.6460    0.5673   -0.5062
    0.6785   -0.0200   -0.5440   -0.4933
   -0.0290    0.7553    0.4036   -0.5156
   -0.7309   -0.1085   -0.4684   -0.4844

latent =

  517.7969
   67.4964
   12.4054
    0.2372
```

**Reference**    Jackson, J. E., *A User's Guide to Principal Components,* John Wiley and Sons, Inc. 1991. pp. 1–25.

**See Also**    barttest, pcacov, pcares

# qqplot

| | |
|---|---|
| **Purpose** | Quantile-quantile plot of two samples. |
| **Syntax** | qqplot(X)<br>qqplot(X, Y)<br>qqplot(X, Y, pvec)<br>h = qqplot(...) |
| **Description** | qqplot(X) displays a quantile-quantile plot of the sample quantiles of X versus theoretical quantiles from a normal distribution. If the distribution of X is normal, the plot will be close to linear. |
| | qqplot(X, Y) displays a quantile-quantile plot of two samples. If the samples do come from the same distribution, the plot will be linear. |
| | For matrix X and Y, qqplot displays a separate line for each pair of columns. The plotted quantiles are the quantiles of the smaller dataset. |
| | The plot has the sample data displayed with the plot symbol '+'. Superimposed on the plot is a line joining the first and third quartiles of each distribution (this is a robust linear fit of the order statistics of the two samples). This line is extrapolated out to the ends of the sample to help evaluate the linearity of the data. |
| | Use qqplot(X, Y, pvec) to specify the quantiles in the vector pvec. |
| | h = qqplot(X, Y, pvec) returns handles to the lines in h. |
| **Examples** | Generate two normal samples with different means and standard deviations. Then make a quantile-quantile plot of the two samples. |

```
x = normrnd(0, 1, 100, 1);
y = normrnd(0.5, 2, 50, 1);
qqplot(x, y);
```
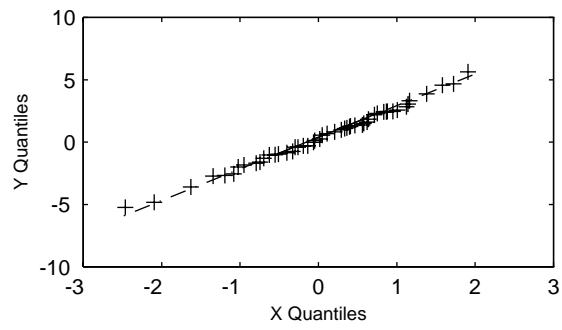
**See Also**　　　　normplot

# random

| | |
|---|---|
| **Purpose** | Random numbers from a specified distribution. |
| **Syntax** | y = random('*name*', A1, A2, A3, m, n) |

**Description**    y = random('*name*', A1, A2, A3, m, n) returns a matrix of random numbers, where '*name*' is a string containing the name of the distribution, and A1, A2, and A3 are matrices of distribution parameters. Depending on the distribution some of the parameters may not be necessary.

Vector or matrix inputs must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

The last two parameters, d and e, are the size of the matrix y. If the distribution parameters are matrices, then these parameters are optional, but they must match the size of the other matrix arguments (see second example).

random is a utility routine allowing you to access all the random number generators in the Statistics Toolbox using the name of the distribution as a parameter. See "Overview of the Distributions" on page 1-12 for the list of available distributions.

**Examples**
```
rn = random('Normal', 0, 1, 2, 4)

rn =
    1.1650      0.0751     -0.6965      0.0591
    0.6268      0.3516      1.6961      1.7971

rp = random('Poisson', 1:6, 1, 6)

rp =
    0       0       1       2       5       7
```

**See Also**    betarnd, binornd, cdf, chi2rnd, exprnd, frnd, gamrnd, geornd, hygernd, icdf, lognrnd, nbinrnd, ncfrnd, nctrnd, ncx2rnd, normrnd, pdf, poissrnd, raylrnd, trnd, unidrnd, unifrnd, weibrnd

| **Purpose** | Interactive random number generation using histograms for display. |
|---|---|

**Syntax**       randtool
                r = randtool('output')

**Description**   The randtool command sets up a graphic user interface for exploring the
                effects of changing parameters and sample size on the histogram of random
                samples from the supported probability distributions.

                The M-file calls itself recursively using the action and flag parameters. For
                general use call randtool without parameters.

                To output the current set of random numbers, press the **Output** button. The
                results are stored in the variable ans. Alternatively, use the following
                command.

                r = randtool('output') places the sample of random numbers in the
                vector r.

                To sample repetitively from the same distribution, press the **Resample** button.

                To change the distribution function, choose from the pop-up menu of functions
                at the top of the figure.

                To change the parameter settings, move the sliders or type a value in the edit
                box under the name of the parameter. To change the limits of a parameter, type
                a value in the edit box at the top or bottom of the parameter slider.

                To change the sample size, type a number in the **Sample Size** edit box.

                When you are done, press the **Close** button.

                For an extensive discussion, see "The randtool Demo" on page 1-169.

**See Also**     disttool

# range

**Purpose**
Sample range.

**Syntax**
y = range(X)

**Description**
range(X) returns the difference between the maximum and the minimum of a sample. For vectors, range(x) is the range of the elements. For matrices, range(X) is a row vector containing the range of each column of X.

The range is an easily calculated estimate of the spread of a sample. Outliers have an undue influence on this statistic, which makes it an unreliable estimator.

**Example**
The range of a large sample of standard normal random numbers is approximately six. This is the motivation for the process capability indices $C_p$ and $C_{pk}$ in statistical quality control applications.

```
rv = normrnd(0, 1, 1000, 5);
near6 = range(rv)

near6 =

    6.1451    6.4986    6.2909    5.8894    7.0002
```

**See Also**
std, iqr, mad

**Purpose**     Wilcoxon rank sum test that two populations are identical.

**Syntax**      p = ranksum(x, y, alpha)
                [p, h] = ranksum(x, y, alpha)
                [p, h, stats] = ranksum(x, y, alpha)

**Description**  p = ranksum(x, y, alpha) returns the significance probability that the
                populations generating two independent samples, x and y, are identical. x and
                y are both vectors, but can have different lengths. alpha is the desired level of
                significance and must be a scalar between zero and one.

                [p, h] = ranksum(x, y, alpha) also returns the result of the hypothesis test, h.
                h is zero if the populations of x and y are not significantly different. h is one if
                the two populations are significantly different.

                p is the probability of observing a result equally or more extreme than the one
                using the data (x and y) if the null hypothesis is true. If p is near zero, this casts
                doubt on this hypothesis.

                [p, h, stats] = ranksum(x, y, alpha) also returns a structure containing the
                field stats.ranksum whose value is equal to the rank sum statistic. For large
                samples, it also contains stats.zval that is the value of the normal (Z) statistic
                used to compute p.

**Example**     This example tests the hypothesis of equality of means for two samples
                generated with poissrnd.

                    x = poissrnd(5, 10, 1);
                    y = poissrnd(2, 20, 1);
                    [p, h] = ranksum(x, y, 0.05)

                    p =
                        0.0027

                    h =
                         1

**See Also**    signrank, signtest, ttest2

# raylcdf

**Purpose**    Rayleigh cumulative distribution function (cdf).

**Syntax**    P = raylcdf(X, B)

**Description**    P = raylcdf(X, B) computes the Rayleigh cdf at each of the values in X using the corresponding parameters in B. Vector or matrix inputs for X and B must have the same size, which is also the size of P. A scalar input for X or B is expanded to a constant matrix with the same dimensions as the other input.

The Rayleigh cdf is

$$y = F(x|b) = \int_0^x \frac{t}{b^2} e^{\left(\frac{-t^2}{2b^2}\right)} dt$$

**Example**
```
x = 0:0.1:3;
p = raylcdf(x, 1);
plot(x, p)
```
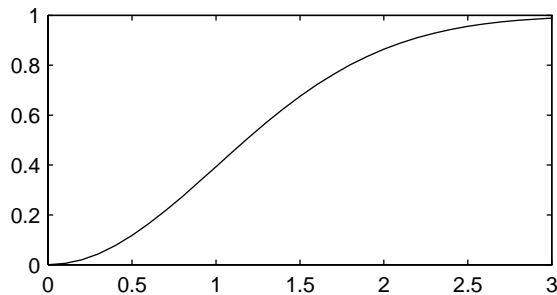


**Reference**    Evans, M., N. Hastings, and B. Peacock, *Statistical Distributions, Second Edition,* Wiley 1993. pp. 134–136.

**See Also**    cdf, raylinv, raylpdf, raylrnd, raylstat

**Purpose**　　　　Inverse of the Rayleigh cumulative distribution function.

**Syntax**　　　　X = raylinv(P, B)

**Description**　　X = raylinv(P, B) returns the inverse of the Rayleigh cumulative distribution function with parameter B at the corresponding probabilities in P. Vector or matrix inputs for P and B must have the same size, which is also the size of X. A scalar input for P or B is expanded to a constant matrix with the same dimensions as the other input.

**Example**　　　　x = raylinv(0.9, 1)

　　　　　　　　　x =
　　　　　　　　　　2.1460

**See Also**　　　icdf, raylcdf, raylpdf, raylrnd, raylstat

# raylpdf

**Purpose**       Rayleigh probability density function.

**Syntax**        Y = raylpdf(X, B)

**Description**   Y = raylpdf(X, B) computes the Rayleigh pdf at each of the values in X using the corresponding parameters in B. Vector or matrix inputs for X and B must have the same size, which is also the size of Y. A scalar input for X or B is expanded to a constant matrix with the same dimensions as the other input.

The Rayleigh pdf is

$$y = f(x|b) = \frac{x}{b^2} e^{\left(\frac{-x^2}{2b^2}\right)}$$

**Example**       x = 0:0.1:3;
                  p = raylpdf(x, 1);
                  plot(x, p)
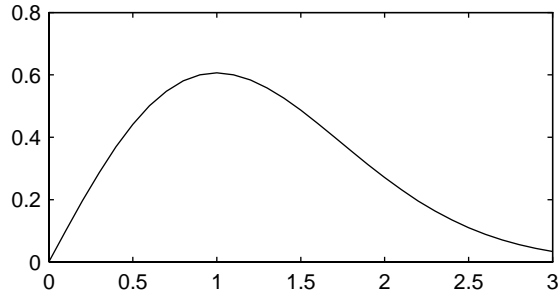


**See Also**      pdf, raylcdf, raylinv, raylrnd, raylstat

**Purpose**      Random matrices from the Rayleigh distribution.

**Syntax**       R = raylrnd(B)
                 R = raylrnd(B, m)
                 R = raylrnd(B, m, n)

**Description**  R = raylrnd(B) returns a matrix of random numbers chosen from the
                 Rayleigh distribution with parameter B. The size of R is the size of B.

                 R = raylrnd(B, m) returns a matrix of random numbers chosen from the
                 Rayleigh distribution with parameter B, where m is a 1-by-2 vector that
                 contains the row and column dimensions of R.

                 R = raylrnd(B, m, n) returns a matrix of random numbers chosen from the
                 Rayleigh distribution with parameter B, where scalars m and n are the row and
                 column dimensions of R.

**Example**          r = raylrnd(1:5)

                     r =
                        1.7986    0.8795    3.3473    8.9159    3.5182

**See Also**     random, raylcdf, raylinv, raylpdf, raylstat

# raylstat

**Purpose**  Mean and variance for the Rayleigh distribution.

**Syntax**
M = raylstat(B)
[M,V] = raylstat(B)

**Description**  [M,V] = raylstat(B) returns the mean and variance of the Rayleigh distribution with parameter B.

The mean of the Rayleigh distribution with parameter $b$ is $b\sqrt{\pi/2}$ and the variance is

$$\frac{4-\pi}{2}b^2$$

**Example**
[mn,v] = raylstat(1)

mn =
    1.2533

v =
    0.4292

**See Also**  raylcdf, raylinv, raylpdf, raylrnd

**Purpose**          Residual case order plot.

**Syntax**           rcoplot(r, rint)

**Description**      rcoplot(r, rint) displays an errorbar plot of the confidence intervals on the
residuals from a regression. The residuals appear in the plot in case order.
Inputs r and rint are outputs from the regress function.

**Example**
```
X = [ones(10, 1)  (1:10)'];
y = X * [10;1] + normrnd(0, 0.1, 10, 1);
[b, bint, r, rint] = regress(y, X, 0.05);
rcoplot(r, rint);
```
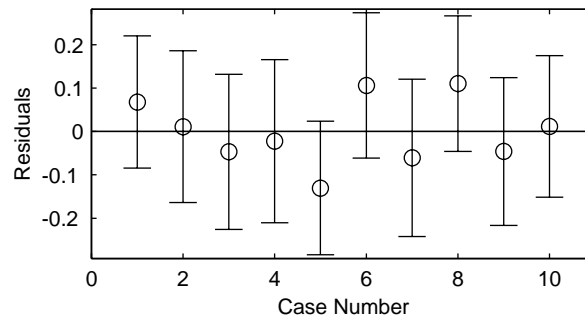


The figure shows a plot of the residuals with error bars showing 95% confidence
intervals on the residuals. All the error bars pass through the zero line,
indicating that there are no outliers in the data.

**See Also**        regress

# refcurve

**Purpose**          Add a polynomial curve to the current plot.

**Syntax**           h = refcurve(p)

**Description**      refcurve adds a graph of the polynomial p to the current axes. The function for a polynomial of degree *n* is:

$$y = p_1 x^n + p_2 x^{(n-1)} + \dots + p_n x + p_{n+1}$$

Note that $p_1$ goes with the highest order term.

h = refcurve(p) returns the handle to the curve.

**Example**          Plot data for the height of a rocket against time, and add a reference curve showing the theoretical height (assuming no air friction). The initial velocity of the rocket is 100 m/sec.

```
h = [85 162 230 289 339 381 413 437 452 458 456 440 400 356];
plot(h,'+')
refcurve([-4.9 100 0])
```
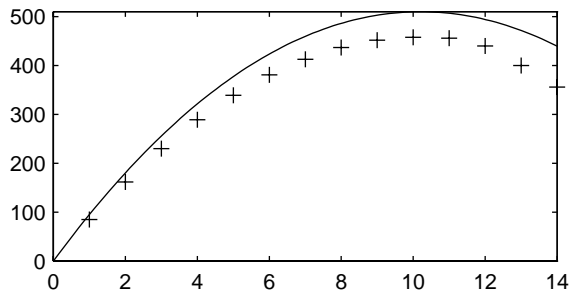


**See Also**         polyfit, polyval, refline

# refline

**Purpose**      Add a reference line to the current axes.

**Syntax**
```
refline(slope, intercept)
refline(slope)
h = refline(slope, intercept)
refline
```

**Description**   `refline(slope, intercept)` adds a reference line with the given `slope` and `intercept` to the current axes.

`refline(slope)`, where `slope` is a two-element vector, adds the line

$$y = slope(2) + slope(1)*x$$

to the figure.

`h = refline(slope, intercept)` returns the handle to the line.

`refline` with no input arguments superimposes the least squares line on each line object in the current figure (except LineStyles '-','--','.-'). This behavior is equivalent to `lsline`.

**Example**
```
y = [3.2 2.6 3.1 3.4 2.4 2.9 3.0 3.3 3.2 2.1 2.6]';
plot(y, '+')
refline(0, 3)
```
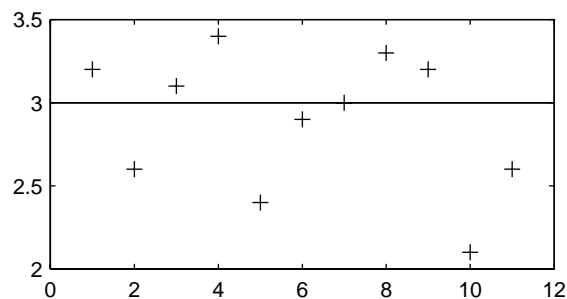


**See Also**      `lsline, polyfit, polyval, refcurve`

# regress

**Purpose**        Multiple linear regression.

**Syntax**
```
b = regress(y, X)
[b, bint, r, rint, stats] = regress(y, X)
[b, bint, r, rint, stats] = regress(y, X, alpha)
```

**Description**    `b = regress(y, X)` returns the least squares fit of y on X by solving the linear model

$$y = X\beta + \varepsilon$$
$$\varepsilon \sim N(0, \sigma^2 I)$$

for β, where:

- *y* is an *n*-by-1 vector of observations
- *X* is an *n*-by-*p* matrix of regressors
- β is a *p*-by-1 vector of parameters
- ε is an *n*-by-1 vector of random disturbances

`[b, bint, r, rint, stats] = regress(y, X)` returns an estimate of β in b, a 95% confidence interval for β in the *p*-by-2 vector `bint`. The residuals are returned in r and a 95% confidence interval for each residual is returned in the *n*-by-2 vector `rint`. The vector `stats` contains the $R^2$ statistic along with the *F* and *p* values for the regression.

`[b, bint, r, rint, stats] = regress(y, X, alpha)` gives 100(1-alpha)% confidence intervals for `bint` and `rint`. For example, `alpha = 0.2` gives 80% confidence intervals.

**Examples**       Suppose the true model is

$$y = 10 + x + \varepsilon$$
$$\varepsilon \sim N(0, 0.01 I)$$

where *I* is the identity matrix.

```
X = [ones(10, 1) (1:10)']
```

```
X =
     1     1
     1     2
     1     3
     1     4
     1     5
     1     6
     1     7
     1     8
     1     9
     1    10

y = X * [10; 1] + normrnd(0, 0. 1, 10, 1)

y =
    11. 1165
    12. 0627
    13. 0075
    14. 0352
    14. 9303
    16. 1696
    17. 0059
    18. 1797
    19. 0264
    20. 0872

[b, bint] = regress(y, X, 0. 05)

b =
    10. 0456
     1. 0030

bint =
     9. 9165    10. 1747
     0. 9822     1. 0238
```

Compare b to [10 1]'. Note that bint includes the true model values.

**Reference**   Chatterjee, S. and A. S. Hadi. *Influential Observations, High Leverage Points, and Outliers in Linear Regression.* Statistical Science, 1986. pp. 379–416.

# regstats

| | |
|---|---|
| **Purpose** | Regression diagnostics graphical user interface. |
| **Syntax** | regstats(responses, DATA) |
| | regstats(responses, DATA, '*model*') |

**Description**  regstats(responses, DATA) generates regression diagnostics for a linear additive model with a constant term. The dependent variable is the vector responses. Values of the independent variables are in the matrix DATA.

The function creates a figure with a group of check boxes that save diagnostic statistics to the base workspace using variable names you can specify.

regstats(responses, data, '*model*') controls the order of the regression model, where '*model*' can be one of these strings:

- 'interaction' – includes constant, linear, and cross product terms
- 'quadratic' – includes interactions and squared terms
- 'purequadratic' – includes constant, linear, and squared terms

The literature suggests many diagnostic statistics for evaluating multiple linear regression. regstats provides these diagnostics:

- Q from QR decomposition
- R from QR decomposition
- Regression coefficients
- Covariance of regression coefficients
- Fitted values of the response data
- Residuals
- Mean squared error
- Leverage
- "Hat" matrix
- Delete-1 variance
- Delete-1 coefficients
- Standardized residuals
- Studentized residuals
- Change in regression coefficients

- Change in fitted values
- Scaled change in fitted values
- Change in covariance
- Cook's distance

For more detail press the **Help** button in the regstats window. This provides formulae and interpretations for each of these regression diagnostics.

**Algorithm**  The usual regression model is $y = X\beta + \varepsilon$, where:

- $y$ is an $n$-by-1 vector of responses
- $X$ is an $n$-by-$p$ matrix of predictors
- $\beta$ is an $p$-by-1 vector of parameters
- $\varepsilon$ is an $n$-by-1 vector of random disturbances

Let $X = Q*R$ where $Q$ and $R$ come from a QR Decomposition of X. $Q$ is orthogonal and $R$ is triangular. Both of these matrices are useful for calculating many regression diagnostics (Goodall 1993).

The standard textbook equation for the least squares estimator of $\beta$ is

$$\hat{\beta} = b = (X'X)^{-1}X'y$$

However, this definition has poor numeric properties. Particularly dubious is the computation of $(X'X)^{-1}$, which is both expensive and imprecise.

Numerically stable MATLAB code for $\beta$ is

```
b = R\(Q' *y);
```

**Reference**  Goodall, C. R. (1993). *Computation using the QR decomposition*. Handbook in Statistics, Volume 9. Statistical Computing (C. R. Rao, ed.).   Amsterdam, NL Elsevier/North-Holland.

**See Also**  leverage, stepwise, regress

# ridge

**Purpose**        Parameter estimates for ridge regression.

**Syntax**         b = ridge(y, X, k)

**Description**    b = ridge(y, X, k) returns the ridge regression coefficients b for the linear
                   model $y = X\beta + \varepsilon$, where:

- $X$ is an $n$-by-$p$ matrix
- $y$ is the $n$-by-1 vector of observations
- $k$ is a scalar constant (the ridge parameter)

The ridge estimator of $\beta$ is $b = (X'X + kI)^{-1}X'y$.

When k = 0, b is the least squares estimator. For increasing k, the bias of b
increases, but the variance of b falls. For poorly conditioned X, the drop in the
variance more than compensates for the bias.

**Example**        This example shows how the coefficients change as the value of k increases,
                   using data from the hald dataset.

```
load hald;
b = zeros(4, 100);
kvec = 0.01:0.01:1;
count = 0;

for k = 0.01:0.01:1
count = count + 1;
b(:, count) = ridge(heat, ingredients, k);
end

plot(kvec', b'), xlabel('k'), ylabel('b', 'FontName', 'Symbol')
```
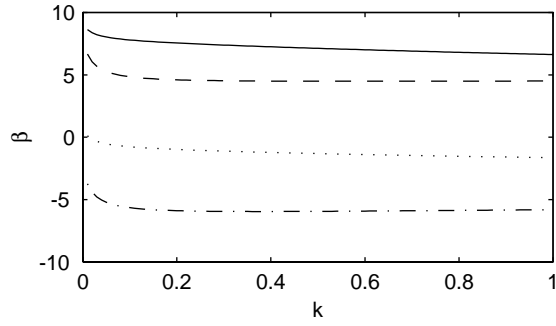
**See Also**       regress, stepwise

# robustdemo

| | |
|---|---|
| **Purpose** | Demo of robust regression. |
| **Syntax** | robustdemo<br>robustdemo(X, Y) |
| **Description** | rsmdemo demonstrates robust regression and ordinary least squares regression on a sample dataset. The function creates a figure window containing a scatter plot of sample data vectors X and Y, along with two fitted lines calculated using least squares and the robust bisquare method. The bottom of the figure shows the equations of the lines and the estimated error standard deviations for each fit. If you use the left mouse button to select an point and move it to a new location, both fits will update. If you hold down the right mouse button over any point, the point will be labeled with the leverage of that point on the least squares fit, and the weight of that point in the robust fit.<br><br>rsmdemo(X, Y) performs the same demonstration using the X and Y values that you specify. |
| **Example** | See "The robustdemo Demo" on page 1-172. |
| **See Also** | robustfit, leverage |

**Purpose**       Robust regression.

**Syntax**        b = robustfit(X, Y)
                  [b, stats] = robustfit(X, Y)
                  [b, stats] = robustfit(X, Y, '*wfun*', tune, '*const*')

**Description**   b = robustfit(X, Y) uses robust regression to fit Y as a function of the
                  columns of X, and returns the vector b of coefficient estimates. The robustfit
                  function uses an iteratively reweighted least squares algorithm, with the
                  weights at each iteration calculated by applying the bisquare function to the
                  residuals from the previous iteration. This algorithm gives lower weight to
                  points that do not fit well. The results are less sensitive to outliers in the data
                  as compared with ordinary least squares regression.

                  [b, stats] = robustfit(X, Y) also returns a stats structure with the
                  following fields:

- stats.ols_s – sigma estimate (rmse) from least squares fit
- stats.robust_s – robust estimate of sigma
- stats.mad_s – estimate of sigma computed using the median absolute
  deviation of the residuals from their median; used for scaling residuals
  during the iterative fitting
- stats.s – final estimate of sigma, the larger of robust_s and a weighted
  average of ols_s and robust_s
- stats.se – standard error of coefficient estimates
- stats.t – ratio of b to stats.se
- stats.p – p-values for stats.t
- stats.coeffcorr – estimated correlation of coefficient estimates
- stats.w – vector of weights for robust fit
- stats.h – vector of leverage values for least squares fit
- stats.dfe – degrees of freedom for error
- stats.R – R factor in QR decomposition of X matrix

The robustfit function estimates the variance-covariance matrix of the
coefficient estimates as $V = inv(X'*X)*stats.s^2$. The standard errors and
correlations are derived from V.

[b, stats] = robustfit(X, Y, '*wfun*', tune, '*const*') specifies a weight function, a tuning constant, and the presence or absence of a constant term. The weight function '*wfun*' can be any of the names listed in the following table.

| Weight function | Meaning | Tuning constant |
|---|---|---|
| 'andrews' | w = (abs(r)<pi) .* sin(r) ./ r | 1.339 |
| 'bisquare' | w = (abs(r)<1) .* (1 - r.^2).^2 | 4.685 |
| 'cauchy' | w = 1 ./ (1 + r.^2) | 2.385 |
| 'fair' | w = 1 ./ (1 + abs(r)) | 1.400 |
| 'huber' | w = 1 ./ max(1, abs(r)) | 1.345 |
| 'logistic' | w = tanh(r) ./ r | 1.205 |
| 'talwar' | w = 1 * (abs(r)<1) | 2.795 |
| 'welsch' | w = exp(-(r.^2)) | 2.985 |

The value r in the weight function expression is equal to

```
resid/(tune*s*sqrt(1-h))
```

where resid is the vector of residuals from the previous iteration, tune is the tuning constant, h is the vector of leverage values from a least squares fit, and s is an estimate of the standard deviation of the error term.

```
s = MAD/0.6745
```

The quantity MAD is the median absolute deviation of the residuals from their median. The constant 0.6745 makes the estimate unbiased for the normal distribution. If there are $p$ columns in the X matrix (including the constant term, if any), the smallest $p$-1 absolute deviations are excluded when computing their median.

In addition to the function names listed above, '*wfun*' can be 'ols' to perform unweighted ordinary least squares.

The argument tune overrides the default tuning constant from the table. A smaller tuning constant tends to downweight large residuals more severely,

and a larger tuning constant downweights large residuals less severely. The default tuning constants, shown in the table, yield coefficient estimates that are approximately 95% as efficient as least squares estimates, when the response has a normal distribution with no outliers. The value of 'const' can be 'on' (the default) to add a constant term or 'off' to omit it. If you want a constant term, you should set 'const' to 'on' rather than adding a column of ones to your X matrix.

As an alternative to specifying one of the named weight functions shown above, you can write your own weight function that takes a vector of scaled residuals as input and produces a vector of weights as output. You can specify 'wfun' using @ (for example, @myfun) or as an inline function.

**Example**      Let's see how a single erroneous point affects least squares and robust fits. First we generate a simple dataset following the equation y = 10- 2*x plus some random noise. Then we change one y value to simulate an outlier that could be an erroneous measurement.

```
x = (1:10)';
y = 10 - 2*x + randn(10,1);
y(10) = 0;
```

We use both ordinary least squares and robust fitting to estimate the equations of a straight line fit.

```
bls = regress(y,[ones(10,1) x])

bls =

    8.6305
   -1.4721

brob = robustfit(x,y)

brob =

   10.5089
   -1.9844
```

A scatter plot with both fitted lines shows that the robust fit (solid line) fits most of the data points well but ignores the outlier. The least squares fit (dotted line) is pulled toward the outlier.

```
scatter(x, y)
hold on
plot(x, bls(1)+bls(2)*x, 'g:')
plot(x, brob(1)+brob(2)*x, 'r-')
```
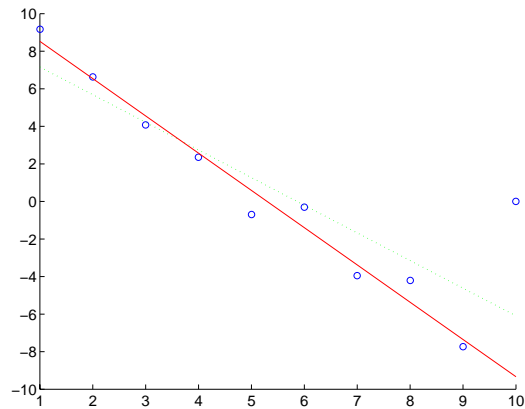


**See Also**     regress, robustdemo

**References**     DuMouchel, W.H., and F.L. O'Brien (1989), "Integrating a robust option into a multiple regression computing environment," *Computer Science and Statistics*: *Proceedings of the 21st Symposium on the Interface*, Alexandria, VA: American Statistical Association.

Holland, P.W., and R.E. Welsch (1977), "Robust regression using iteratively reweighted least-squares," *Communications in Statistics: Theory and Methods*, *A6*, 813-827.

Huber, P.J. (1981), *Robust Statistics*, New York: Wiley.

Street, J.O., R.J. Carroll, and D. Ruppert (1988), "A note on computing robust regression estimates via iteratively reweighted least squares," *The American Statistician*, *42*, 152-154

**Purpose**         D-optimal design of experiments – row exchange algorithm.

**Syntax**          settings = rowexch(nfactors, nruns)
                    [settings, X] = rowexch(nfactors, nruns)
                    [settings, X] = rowexch(nfactors, nruns, 'model')

**Description**     settings = rowexch(nfactors, nruns) generates the factor settings matrix,
                    settings, for a D-Optimal design using a linear additive model with a constant
                    term. settings has nruns rows and nfactors columns.

                    [settings, X] = rowexch(nfactors, nruns) also generates the associated
                    design matrix X.

                    [settings, X] = rowexch(nfactors, nruns, 'model') produces a design for
                    fitting a specified regression model.  The input, 'model', can be one of these
                    strings:

                    • 'interaction' – includes constant, linear, and cross product terms.
                    • 'quadratic' – interactions plus squared terms.
                    • 'purequadratic' – includes constant, linear and squared terms.

**Example**         This example illustrates that the D-optimal design for three factors in eight
                    runs, using an interactions model, is a two level full-factorial design.

```
s = rowexch(3, 8, 'interaction')

s =
    -1    -1     1
     1    -1    -1
     1    -1     1
    -1    -1    -1
    -1     1     1
     1     1     1
    -1     1    -1
     1     1    -1
```

**See Also**        cordexch, daugment, dcovary, fullfact, ff2n, hadamard

# rsmdemo

| | |
|---|---|
| **Purpose** | Demo of design of experiments and surface fitting. |
| **Syntax** | rsmdemo |
| **Description** | rsmdemo creates a GUI that simulates a chemical reaction. To start, you have a budget of 13 test reactions. Try to find out how changes in each reactant affect the reaction rate. Determine the reactant settings that maximize the reaction rate. Estimate the run-to-run variability of the reaction. Now run a designed experiment using the model pop-up. Compare your previous results with the output from response surface modeling or nonlinear modeling of the reaction. The GUI has the following elements: |

- A **Run** button to perform one reactor run at the current settings
- An **Export** button to export the *x* and *y* data to the base workspace
- Three sliders with associated data entry boxes to control the partial pressures of the chemical reactants: Hydrogen, n-Pentane, and Isopentane
- A text box to report the reaction rate
- A text box to keep track of the number of test reactions you have left

| | |
|---|---|
| **Example** | See "The rsmdemo Demo" on page 1-170. |
| **See Also** | rstool, nlintool, cordexch |

**Purpose**          Interactive fitting and visualization of a response surface.

**Syntax**           rstool(x, y)
                     rstool(x, y, '*model*')
                     rstool(x, y, '*model*', alpha, 'xname', 'yname')

**Description**      rstool(x, y) displays an interactive prediction plot with 95% global confidence intervals. This plot results from a multiple regression of ($x,y$) data using a linear additive model.

rstool(x, y, '*model*') allows control over the initial regression model, where 'model' can be one of the following strings:

- 'interaction' – includes constant, linear, and cross product terms
- 'quadratic' – includes interactions and squared terms
- 'purequadratic' – includes constant, linear and squared terms

rstool(x, y, 'model', alpha) plots 100(1-alpha)% global confidence interval for predictions as two red curves. For example, alpha = 0.01 gives 99% confidence intervals.

rstool displays a "vector" of plots, one for each column of the matrix of inputs x. The response variable, y, is a column vector that matches the number of rows in x.

rstool(x, y, '*model*', alpha, 'xname', 'yname') labels the graph using the string matrix 'xname' for the labels to the *x*-axes and the string, 'yname', to label the *y*-axis common to all the plots.

Drag the dotted white reference line and watch the predicted values update simultaneously. Alternatively, you can get a specific prediction by typing the value of *x* into an editable text field. Use the pop-up menu labeled **Model** to interactively change the model. Use the pop-up menu labeled **Export** to move specified variables to the base workspace.

**Example**          See "Quadratic Response Surface Models" on page 1-86.

**See Also**         nlintool

# schart

| | |
|---|---|
| **Purpose** | Chart of standard deviation for Statistical Process Control. |

**Syntax**

schart(DATA, conf)
schart(DATA, conf, specs)
schart(DATA, conf, specs)
[outliers, h] = schart(DATA, conf, specs)

**Description**

schart(data) displays an S chart of the grouped responses in DATA. The rows of DATA contain replicate observations taken at a given time. The rows must be in time order. The graph contains the sample standard deviation *s* for each group, a center line at the average *s* value, and upper and lower control limits. The limits are placed at a three-sigma distance on either side of the center line, where sigma is an estimate of the standard deviation of *s*. If the process is in control, fewer than 3 out of 1000 observations would be expected to fall outside the control limits by random chance. So, if you observe points outside the limits, you can take this as evidence that the process is not in control.

schart(DATA, conf) allows control of the confidence level of the upper and lower plotted control limits. The default conf = 0.9973 produces three-sigma limits.

```
norminv(1 - (1-.9973)/2)
ans =
            3
```

To get *k*-sigma limits, use the expression 1-2*(1-normcdf(k)). For example, the correct conf value for 2-sigma limits is 0.9545, as shown below.

```
k = 2;
1-2*(1-normcdf(k))
ans =
      0.9545
```

schart(DATA, conf, specs) plots the specification limits in the two element vector specs.

[outliers, h] = schart(data, conf, specs) returns outliers, a vector of indices to the rows where the mean of DATA is out of control, and h, a vector of handles to the plotted lines.

**Example**      This example plots an S chart of measurements on newly machined parts, taken at one hour intervals for 36 hours. Each row of the runout matrix contains the measurements for 4 parts chosen at random. The values indicate, in thousandths of an inch, the amount the part radius differs from the target radius.

```
load parts
schart(runout)
```
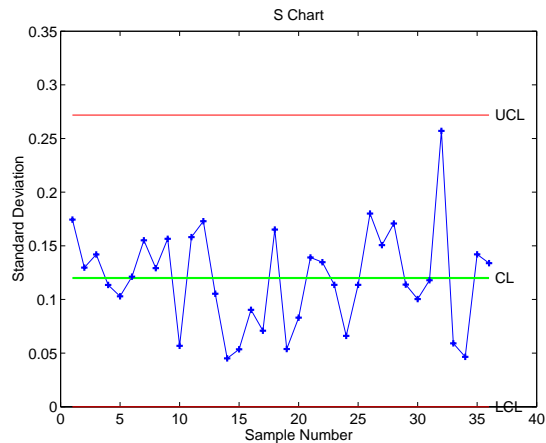


All points are within the control limits, so the variability within subgroups is consistent with what would be expected by random chance. There is no evidence that the process is out of control.

**Reference**     Montgomery, D., *Introduction to Statistical Quality Control,* John Wiley and Sons 1991. p. 235.

**See Also**      capaplot, ewmaplot, histfit, xbarplot

# signrank

**Purpose**      Wilcoxon signed rank test of equality of medians.

**Syntax**       p = signrank(x, y, alpha)
                 [p, h] = signrank(x, y, alpha)
                 [p, h, stats] = signrank(x, y, alpha)

**Description**  p = signrank(x, y, alpha) returns the significance probability that the
                 medians of two matched samples, x and y, are equal. x and y must be vectors
                 of equal length. y may also be a scalar; in this case, signrank computes the
                 probability that the median of x is different from the constant y. alpha is the
                 desired level of significance, and must be a scalar between zero and one.

                 [p, h] = signrank(x, y, alpha) also returns the result of the hypothesis
                 test, h. h is zero if the difference in medians of x and y is not significantly
                 different from zero. h is one if the two medians are significantly different.

                 p is the probability of observing a result equally or more extreme than the one
                 using the data (x and y) if the null hypothesis is true. p is calculated using the
                 rank values for the differences between corresponding elements in x and y. If p
                 is near zero, this casts doubt on this hypothesis.

                 [p, h, stats] = signrank(x, y, alpha) also returns a structure stats
                 containing the field stats.signedrank whose value is the signed rank
                 statistic. For large samples, it also contains stats.zval, the value of the
                 normal (Z) statistic used to compute p.

**Example**      This example tests the hypothesis of equality of means for two samples
                 generated with normrnd. The samples have the same theoretical mean but
                 different standard deviations.

                     x = normrnd(0, 1, 20, 1);
                     y = normrnd(0, 2, 20, 1);
                     [p, h] = signrank(x, y, 0.05)

                     p =
                         0.2959

                     h =
                          0

**See Also**     ranksum, signtest, ttest

# signtest

**Purpose**          Sign test for paired samples.

**Syntax**           p = signtest(x, y, alpha)
                     [p, h] = signtest(x, y, alpha)
                     [p, h, stats] = signtest(x, y, alpha)

**Description**      p = signtest(x, y, alpha) returns the significance probability that the
                     medians of two matched samples, x and y, are equal. x and y must be vectors
                     of equal length. y may also be a scalar; in this case, signtest computes the
                     probability that the median of x is different from the constant y. alpha is the
                     desired level of significance and must be a scalar between zero and one.

                     [p, h] = signtest(x, y, alpha) also returns the result of the hypothesis test,
                     h. h is 0 if the difference in medians of x and y is not significantly different from
                     zero. h is 1 if the two medians are significantly different.

                     p is the probability of observing a result equally or more extreme than the one
                     using the data (x and y) if the null hypothesis is true. p is calculated using the
                     signs (plus or minus) of the differences between corresponding elements in x
                     and y. If p is near zero, this casts doubt on this hypothesis.

                     [p, h, stats] = signtest(x, y, alpha) also returns a structure stats
                     containing the field stats.sign whose value is the sign statistic. For large
                     samples, it also contains stats.zval, the value of the normal (Z) statistic used
                     to compute p.

**Example**          This example tests the hypothesis of equality of medians for two samples
                     generated with normrnd. The samples have the same theoretical median but
                     different standard deviations. (For the normal distribution, the mean and
                     median are the same.)

```
x = normrnd(0, 1, 20, 1);
y = normrnd(0, 2, 20, 1);
[p, h] = signtest(x, y, 0.05)

p =
    0.2632

h =
     0
```

**See Also**        ranksum, signrank, ttest

# skewness

**Purpose**          Sample skewness.

**Syntax**           y = skewness(X)
                     y = skewness(X, flag)

**Description**      y = skewness(X) returns the sample skewness of X. For vectors, skewness(x)
                     is the skewness of the elements of x. For matrices, skewness(X) is a row vector
                     containing the sample skewness of each column.

                     Skewness is a measure of the asymmetry of the data around the sample mean.
                     If skewness is negative, the data are spread out more to the left of the mean
                     than to the right. If skewness is positive, the data are spread out more to the
                     right. The skewness of the normal distribution (or any perfectly symmetric
                     distribution) is zero.

                     The skewness of a distribution is defined as

                     $$y = \frac{E(x-\mu)^3}{\sigma^3}$$

                     where $\mu$ is the mean of $x$, $\sigma$ is the standard deviation of $x$, and $E(t)$ represents
                     the expected value of the quantity $t$.

                     y = skewness(X, flag) specifies whether to correct for bias ($flag$ = 0) or not
                     ($flag$ = 1, the default). When X represents a sample from a population, the
                     skewness of X is biased; that is, it will tend to differ from the population
                     skewness by a systematic amount that depends on the size of the sample. You
                     can set $flag$ = 0 to correct for this systematic bias.

**Example**          X = randn([5 4])

                     X =
                         1.1650     1.6961    -1.4462    -0.3600
                         0.6268     0.0591    -0.7012    -0.1356
                         0.0751     1.7971     1.2460    -1.3493
                         0.3516     0.2641    -0.6390    -1.2704
                        -0.6965     0.8717     0.5774     0.9846

```
y = skewness(X)

y =
   -0.2933     0.0482     0.2735     0.4641
```

**See Also**     kurtosis, mean, moment, std, var

# squareform

**Purpose**            Reformat the output of pdist into a square matrix.

**Syntax**             S = squareform(Y)

**Description**        S = squareform(Y) reformats the distance information returned by pdist
                       from a vector into a square matrix. In this format, $S(i,j)$ denotes the distance
                       between the $i$ and $j$ observations in the original data.

**See Also**           pdist

**Purpose**       Standard deviation of a sample.

**Syntax**        y = std(X)

**Description**   y = std(X) computes the sample standard deviation of the data in X. For vectors, std(x) is the standard deviation of the elements in x. For matrices, std(X) is a row vector containing the standard deviation of each column of X.

std normalizes by $n$-1 where $n$ is the sequence length. For normally distributed data, the square of the standard deviation is the minimum variance unbiased estimator of $\sigma^2$ (the second parameter).

The standard deviation is

$$s = \left( \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2 \right)^{\frac{1}{2}}$$

where the sample average is $\bar{x} = \frac{1}{n} \sum x_i$.

The std function is part of the standard MATLAB language.

**Examples**     In each column, the expected value of y is one.

```
x = normrnd(0, 1, 100, 6);
y = std(x)

y =
    0.9536    1.0628    1.0860    0.9927    0.9605    1.0254

y = std(-1:2:1)

y =
    1.4142
```

**See Also**     cov, var

# stepwise

**Purpose**       Interactive environment for stepwise regression.

**Syntax**        stepwise(X, y)
                  stepwise(X, y, inmodel)
                  stepwise(X, y, inmodel, alpha)

**Description**   stepwise(X, y) fits a regression model of y on the columns of X. It displays
                  three figure windows for interactively controlling the stepwise addition and
                  removal of model terms.

                  stepwise(X, y, inmodel) allows control of the terms in the original regression
                  model. The values of vector, inmodel, are the indices of the columns of the
                  matrix X to include in the initial model.

                  stepwise(X, y, inmodel, alpha) allows control of the length confidence
                  intervals on the fitted coefficients. alpha is the significance for testing each
                  term in the model. By default, alpha = 1 - (1 - 0.025)$^{(1/p)}$ where $p$ is the number
                  of columns in X. This translates to plotted 95% simultaneous confidence
                  intervals (Bonferroni) for all the coefficients.

                  The least squares coefficient is plotted with a green filled circle. A coefficient is
                  not significantly different from zero if its confidence interval crosses the white
                  zero line. Significant model terms are plotted using solid lines. Terms not
                  significantly different from zero are plotted with dotted lines.

                  Click on the confidence interval lines to toggle the state of the model
                  coefficients. If the confidence interval line is green, the term is in the model. If
                  the confidence interval line is red, the term is not in the model.

                  Use the **Export** menu to move variables to the base workspace.

**Example**       See "Stepwise Regression" on page 1-88.

**Reference**     Draper, N. and H. Smith, *Applied Regression Analysis, Second Edition*, John
                  Wiley and Sons, Inc. 1981 pp. 307–312.

**See Also**      regstats, regress, rstool

**Purpose**          Interactive contour plot.

**Syntax**           surfht(Z)
                     surfht(x, y, Z)

**Description**      surfht(Z) is an interactive contour plot of the matrix Z treating the values in
                     Z as height above the plane. The *x*-values are the column indices of Z while the
                     *y*-values are the row indices of Z.

                     surfht(x, y, Z) where x and y are vectors specify the *x* and *y*-axes on the
                     contour plot. The length of x must match the number of columns in Z, and the
                     length of y must match the number of rows in Z.

                     There are vertical and horizontal reference lines on the plot whose intersection
                     defines the current *x*-value and *y*-value. You can drag these dotted white
                     reference lines and watch the interpolated *z*-value (at the top of the plot)
                     update simultaneously. Alternatively, you can get a specific interpolated
                     *z*-value by typing the *x*-value and *y*-value into editable text fields on the *x*-axis
                     and *y*-axis respectively.

# tabulate

**Purpose**    Frequency table.

**Syntax**    table = tabulate(x)
              tabulate(x)

**Description**    table = tabulate(x) takes a vector of positive integers, x, and returns a
                  matrix, table.

The first column of table contains the values of x. The second contains the
number of instances of this value. The last column contains the percentage of
each value.

tabulate with no output arguments displays a formatted table in the
command window.

**Example**

    tabulate([1 2 4 4 3 4])

| Value | Count | Percent |
|-------|-------|---------|
| 1     | 1     | 16.67%  |
| 2     | 1     | 16.67%  |
| 3     | 1     | 16.67%  |
| 4     | 3     | 50.00%  |

**See Also**    pareto

**Purpose**        Read tabular data from the file system.

**Syntax**         [data, varnames, casenames] = tblread
                   [data, varnames, casenames] = tblread('filename')
                   [data, varnames, casenames] = tblread('filename', '*delimiter*')

**Description**    [data, varnames, casenames] = tblread displays the **File Open** dialog box for
                   interactive selection of the tabular data file. The file format has variable names
                   in the first row, case names in the first column and data starting in the (2,2)
                   position.

                   [data, varnames, casenames] = tblread(filename) allows command line
                   specification of the name of a file in the current directory, or the complete
                   pathname of any file.

                   [data, varnames, casenames] = tblread(filename, '*delimiter*') allows
                   specification of the field '*delimiter*' in the file. Accepted values are 'tab',
                   'space', or 'comma'.

                   tblread returns the data read in three values.

| Return Value | Description |
|---|---|
| data | Numeric matrix with a value for each variable-case pair. |
| varnames | String matrix containing the variable names in the first row. |
| casenames | String matrix containing the names of each case in the first column. |

# tblread

**Example**

```
[data, varnames, casenames] = tblread('sat.dat')

data =

    470    530
    520    480

varnames =

Male
Female

casenames =

Verbal
Quantitative
```

**See Also**   caseread, tblwrite, tdfread

**Purpose**        Writes tabular data to the file system.

**Syntax**         tblwrite(data,'varnames','casenames')
                   tblwrite(data,'varnames','casenames','filename')

**Description**    tblwrite(data,'varnames','casenames') displays the **File Open** dialog box
                   for interactive specification of the tabular data output file. The file format has
                   variable names in the first row, case names in the first column and data
                   starting in the (2,2) position.

                   'varnames' is a string matrix containing the variable names. 'casenames' is
                   a string matrix containing the names of each case in the first column. data is
                   a numeric matrix with a value for each variable-case pair.

                   tblwrite(data,'varnames','casenames','filename') allows command line
                   specification of a file in the current directory, or the complete pathname of any
                   file in the string 'filename'.

**Example**        Continuing the example from tblread:

                   tblwrite(data, varnames, casenames, 'sattest.dat')
                   type sattest.dat

                   |              | Male | Female |
                   |--------------|------|--------|
                   | Verbal       | 470  | 530    |
                   | Quantitative | 520  | 480    |

**See Also**       casewrite, tblread

# tcdf

**Purpose**    Student's t cumulative distribution function (cdf).

**Syntax**    P = tcdf(X, V)

**Description**    P = tcdf(X, V) computes Student's t cdf at each of the values in X using the corresponding degrees of freedom in V. Vector or matrix inputs for X and V must be the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in V must be positive integers.

The t cdf is

$$p = F(x|v) = \int_{-\infty}^{x} \frac{\Gamma\left(\frac{v+1}{2}\right)}{\Gamma\left(\frac{v}{2}\right)} \frac{1}{\sqrt{v\pi}} \frac{1}{\left(1+\frac{t^2}{v}\right)^{\frac{v+1}{2}}} dt$$

The result, $p$, is the probability that a single observation from the t distribution with v degrees of freedom will fall in the interval $(-\infty\ x]$.

**Examples**    Suppose 10 samples of Guinness beer have a mean alcohol content of 5.5% by volume and the standard deviation of these samples is 0.5%. What is the probability that the true alcohol content of Guinness beer is less than 5%?

```
t = (5.0 - 5.5) / 0.5;
probability = tcdf(t, 10 - 1)

probability =

    0.1717
```

**See Also**    cdf, tinv, tpdf, trnd, tstat

**Purpose**      Read file containing tab-delimited numeric and text values.

**Syntax**       tdfread
                 tdfread('filename')
                 tdfread('filename','*delimiter*')

**Description**  tdfread displays the **File Open** dialog box for interactive selection of the data file. The file should consist of columns of values, separated by tabs, and with column names in the first line of the file. Each column is read from the file and assigned to a variable with the specified name. If all values for a column are numeric, the variable is converted to numbers; otherwise the variable is a string matrix. After all values are imported, tdfread displays information about the imported values using the format of the whos command.

tdfread('filename') allows command line specification of the name of a file in the current directory, or the complete pathname of any file.

tdfread('filename','*delimiter*') indicates that the character specified by '*delimiter*' separates columns in the file. Accepted values are:

- ' ' or 'space'
- '\t' or 'tab'
- ',' or 'comma'
- ';' or 'semi'
- '|' or 'bar'

The default delimiter is 'tab'.

**Example**      type sat2.dat

                 Test, Gender, Score
                 Verbal, Mail, 470
                 Verbal, Female, 530
                 Quantitative, Male, 520
                 Quantitative, Female, 480
                 tdfread('sat2.dat',',')

# tdfread

```
Name          Size          Bytes  Class

Gender        4x6              48   char array
Score         4x1              32   double array
Test          4x12             96   char array

Grand total is 76 elements using 176 bytes
```

**See Also**          tblread

**Purpose**        Inverse of the Student's t cumulative distribution function (cdf).

**Syntax**         X = tinv(P, V)

**Description**    X = tinv(P, V) computes the inverse of Student's t cdf with parameter V for
the corresponding probabilities in P. Vector or matrix inputs for P and V must
be the same size. A scalar input is expanded to a constant matrix with the same
dimensions as the other inputs. The degrees of freedom in V must be positive
integers, and the values in P must lie on the interval [0 1].

The t inverse function in terms of the t cdf is

$$x = F^{-1}(p|\nu) = \{x : F(x|\nu) = p\}$$

where

$$p = F(x|\nu) = \int_{-\infty}^{x} \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \frac{1}{\sqrt{\nu\pi}} \frac{1}{\left(1 + \frac{t^2}{\nu}\right)^{\frac{\nu+1}{2}}} dt$$

The result, *x*, is the solution of the cdf integral with parameter $\nu$, where you
supply the desired probability *p*.

**Examples**      What is the 99th percentile of the t distribution for one to six degrees of
freedom?

```
percentile = tinv(0.99, 1:6)

percentile =

    31.8205    6.9646    4.5407    3.7469    3.3649    3.1427
```

**See Also**      icdf, tcdf, tpdf, trnd, tstat

# tpdf

**Purpose**  Student's t probability density function (pdf).

**Syntax**  Y = tpdf(X, V)

**Description**  Y = tpdf(X, V) computes Student's t pdf at each of the values in X using the corresponding parameters in V. Vector or matrix inputs for X and V must have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The degrees of freedom in V must be positive integers.

Student's t pdf is

$$y = f(x|\nu) = \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \frac{1}{\sqrt{\nu\pi}} \frac{1}{\left(1 + \frac{x^2}{\nu}\right)^{\frac{\nu+1}{2}}}$$

**Examples**  The mode of the t distribution is at $x = 0$. This example shows that the value of the function at the mode is an increasing function of the degrees of freedom.

    tpdf(0, 1:6)

    ans =

        0.3183    0.3536    0.3676    0.3750    0.3796    0.3827

The t distribution converges to the standard normal distribution as the degrees of freedom approaches infinity. How good is the approximation for $\nu = 30$?

    difference = tpdf(-2.5:2.5, 30) - normpdf(-2.5:2.5)

    difference =

        0.0035   -0.0006   -0.0042   -0.0042   -0.0006    0.0035

**See Also**  pdf, tcdf, tinv, trnd, tstat

**Purpose**             Mean of a sample of data excluding extreme values.

**Syntax**               m = trimmean(X, percent)

**Description**     m = trimmean(X, percent) calculates the mean of a sample X excluding the highest and lowest percent/2 of the observations. The trimmed mean is a robust estimate of the location of a sample. If there are outliers in the data, the trimmed mean is a more representative estimate of the center of the body of the data. If the data is all from the same probability distribution, then the trimmed mean is less efficient than the sample average as an estimator of the location of the data.

**Examples**      This example shows a Monte Carlo simulation of the efficiency of the 10% trimmed mean relative to the sample average for normal data.

```
x = normrnd(0, 1, 100, 100);
m = mean(x);
trim = trimmean(x, 10);
sm = std(m);
strim = std(trim);
efficiency = (sm/strim).^2

efficiency =

    0.9702
```

**See Also**       mean, median, geomean, harmmean

# trnd

| | |
|---|---|
| **Purpose** | Random numbers from Student's t distribution. |

**Syntax**

```
R = trnd(V)
R = trnd(V, m)
R = trnd(V, m, n)
```

**Description**   R = trnd(V) generates random numbers from Student's t distribution with V degrees of freedom. The size of R is the size of V.

R = trnd(V, m) generates random numbers from Student's t distribution with V degrees of freedom, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = trnd(V, m, n) generates random numbers from Student's t distribution with V degrees of freedom, where scalars m and n are the row and column dimensions of R.

**Examples**

```
noisy = trnd(ones(1, 6))

noisy =

    19.7250    0.3488    0.2843    0.4034    0.4816   -2.4190

numbers = trnd(1:6, [1 6])

numbers =

    -1.9500   -0.9611   -0.9038    0.0754    0.9820    1.0115

numbers = trnd(3, 2, 6)

numbers =

    -0.3177   -0.0812   -0.6627    0.1905   -1.5585   -0.0433
     0.2536    0.5502    0.8646    0.8060   -0.5216    0.0891
```

**See Also**   tcdf, tinv, tpdf, tstat

**Purpose**      Mean and variance for the Student's t distribution.

**Syntax**       [M, V] = tstat(NU)

**Description**  [M, V] = tstat(NU) returns the mean and variance for Student's t distribution with parameters specified by NU. M and V are the same size as NU.

The mean of the Student's t distribution with parameter $\nu$ is zero for values of $\nu$ greater than 1. If $\nu$ is one, the mean does not exist. The variance for values of $\nu$ greater than 2 is $\nu/(\nu-2)$.

**Examples**     Find the mean and variance for 1 to 30 degrees of freedom.

```
[m, v] = tstat(reshape(1: 30, 6, 5))

m =
    NaN      0      0      0      0
      0      0      0      0      0
      0      0      0      0      0
      0      0      0      0      0
      0      0      0      0      0
      0      0      0      0      0

v =
       NaN    1. 4000    1. 1818    1. 1176    1. 0870
       NaN    1. 3333    1. 1667    1. 1111    1. 0833
    3. 0000    1. 2857    1. 1538    1. 1053    1. 0800
    2. 0000    1. 2500    1. 1429    1. 1000    1. 0769
    1. 6667    1. 2222    1. 1333    1. 0952    1. 0741
    1. 5000    1. 2000    1. 1250    1. 0909    1. 0714
```

Note that the variance does not exist for one and two degrees of freedom.

**See Also**     tcdf, tinv, tpdf, trnd

# ttest

**Purpose**    Hypothesis testing for a single sample mean.

**Syntax**

h = ttest(x, m)
h = ttest(x, m, alpha)
[h, sig, ci] = ttest(x, m, alpha, tail)

**Description**    h = ttest(x, m) performs a t-test at significance level 0.05 to determine whether a sample from a normal distribution (in x) could have mean m when the standard deviation is unknown.

h = ttest(x, m, alpha) gives control of the significance level, alpha. For example if alpha = 0.01, and the result, h, is 1 you can reject the null hypothesis at the significance level 0.01. If h is 0, you cannot reject the null hypothesis at the alpha level of significance.

[h, sig, ci] = ttest(x, m, alpha, tail) allows specification of one- or two-tailed tests. tail is a flag that specifies one of three alternative hypotheses:

- tail = 0 specifies the alternative $\bar{x} \neq m$ (default)
- tail = 1 specifies the alternative $\bar{x} > m$
- tail = -1 specifies the alternative $\bar{x} < m$

Output sig is the p-value associated with the T-statistic

$$T = \frac{\bar{x} - m}{s/\sqrt{n}}$$

where $s$ is the sample standard deviation and $n$ is the number of observations in the sample. sig is the probability that the observed value of T could be as large or larger *by chance* under the null hypothesis that the mean of $x$ is equal to $m$.

ci is a 1-alpha confidence interval for the true mean.

**Example**    This example generates 100 normal random numbers with theoretical mean zero and standard deviation one. The observed mean and standard deviation are different from their theoretical values, of course. We test the hypothesis that there is no true difference.

Normal random number generator test.

```
x = normrnd(0, 1, 1, 100);
[h, sig, ci] = ttest(x, 0)

h =
     0

sig =
    0.4474

ci =
   -0.1165    0.2620
```

The result h = 0 means that we cannot reject the null hypothesis. The significance level is 0.4474, which means that by chance we would have observed values of T more extreme than the one in this example in 45 of 100 similar experiments. A 95% confidence interval on the mean is [-0.1165 0.2620], which includes the theoretical (and hypothesized) mean of zero.

# ttest2

**Purpose**
Hypothesis testing for the difference in means of two samples.

**Syntax**
[h, significance, ci] = ttest2(x, y)
[h, significance, ci] = ttest2(x, y, alpha)
[h, significance, ci] = ttest2(x, y, alpha, tail)

**Description**
h = ttest2(x, y) performs a t-test to determine whether two samples from a normal distribution (in x and y) could have the same mean when the standard deviations are unknown but assumed equal.

The result, h, is 1 if you can reject the null hypothesis at the 0.05 significance level alpha and 0 otherwise.

The significance is the p-value associated with the T-statistic

$$T = \frac{\bar{x} - \bar{y}}{s\sqrt{\frac{1}{n} + \frac{1}{m}}}$$

where *s* is the pooled sample standard deviation and *n* and *m* are the numbers of observations in the x and y samples. significance is the probability that the observed value of T could be as large or larger *by chance* under the null hypothesis that the mean of *x* is equal to the mean of *y*.

ci is a 95% confidence interval for the true difference in means.

[h, significance, ci] = ttest2(x, y, alpha) gives control of the significance level alpha. For example if alpha = 0.01, and the result, h, is 1, you can reject the null hypothesis at the significance level 0.01. ci in this case is a 100(1-alpha)% confidence interval for the true difference in means.

ttest2(x, y, alpha, tail) allows specification of one- or two-tailed tests, where tail is a flag that specifies one of three alternative hypotheses:

- tail = 0 specifies the alternative $\mu_x \neq \mu_y$ (default)
- tail = 1 specifies the alternative $\mu_x > \mu_y$
- tail = -1 specifies the alternative $\mu_x < \mu_y$

**Examples**

This example generates 100 normal random numbers with theoretical mean 0 and standard deviation 1. We then generate 100 more normal random numbers with theoretical mean 1/2 and standard deviation 1. The observed means and standard deviations are different from their theoretical values, of course. We test the hypothesis that there is no true difference between the two means. Notice that the true difference is only one half of the standard deviation of the individual observations, so we are trying to detect a signal that is only one half the size of the inherent noise in the process.

```
x = normrnd(0, 1, 100, 1);
y = normrnd(0.5, 1, 100, 1);

[h, significance, ci] = ttest2(x, y)

h =
    1

significance =

    0.0017

ci =
    -0.7352    -0.1720
```

The result h = 1 means that we can reject the null hypothesis. The significance is 0.0017, which means that by chance we would have observed values of t more extreme than the one in this example in only 17 of 10,000 similar experiments! A 95% confidence interval on the mean is [-0.7352 -0.1720], which includes the theoretical (and hypothesized) difference of -0.5.

# unidcdf

| | |
|---|---|
| **Purpose** | Discrete uniform cumulative distribution (cdf) function. |
| **Syntax** | P = unidcdf(X, N) |
| **Description** | P = unidcdf(X, N) computes the discrete uniform cdf at each of the values in X using the corresponding parameters in N. Vector or matrix inputs for X and N must have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The maximum observable values in N must be positive integers. |

The discrete uniform cdf is

$$p = F(x|N) = \frac{floor(x)}{N} I_{(1, \dots, N)}(x)$$

The result, $p$, is the probability that a single observation from the discrete uniform distribution with maximum $N$ will be a positive integer less than or equal to $x$. The values $x$ do not need to be integers.

| | |
|---|---|
| **Examples** | What is the probability of drawing a number 20 or less from a hat with the numbers from 1 to 50 inside? |

```
probability = unidcdf(20, 50)

probability =

    0.4000
```

| | |
|---|---|
| **See Also** | cdf, unidinv, unidpdf, unidrnd, unidstat |

**Purpose**       Inverse of the discrete uniform cumulative distribution function.

**Syntax**        X = unidinv(P,N)

**Description**   X = unidinv(P,N) returns the smallest positive integer X such that the
                  discrete uniform cdf evaluated at X is equal to or exceeds P. You can think of P
                  as the probability of drawing a number as large as X out of a hat with the
                  numbers 1 through N inside.

                  Vector or matrix inputs for N and P must have the same size, which is also the
                  size of X. A scalar input for N or P is expanded to a constant matrix with the
                  same dimensions as the other input. The values in P must lie on the interval
                  [0 1] and the values in N must be positive integers.

**Examples**          x = unidinv(0.7, 20)

                      x =
                          14

                      y = unidinv(0.7 + eps, 20)

                      y =
                          15

                  A small change in the first parameter produces a large jump in output. The cdf
                  and its inverse are both step functions. The example shows what happens at a
                  step.

**See Also**     icdf, unidcdf, unidpdf, unidrnd, unidstat

# unidpdf

**Purpose**     Discrete uniform probability density function (pdf).

**Syntax**      Y = unidpdf(X, N)

**Description** unidpdf(X, N) computes the discrete uniform pdf at each of the values in X using the corresponding parameters in N. Vector or matrix inputs for X and N must have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs. The parameters in N must be positive integers.

The discrete uniform pdf is

$$y = f(x|N) = \frac{1}{N} I_{(1, \ldots, N)}(x)$$

You can think of $y$ as the probability of observing any one number between 1 and $n$.

**Examples**    For fixed n, the uniform discrete pdf is a constant.

    y = unidpdf(1:6, 10)

    y =
        0.1000     0.1000     0.1000     0.1000     0.1000     0.1000

Now fix x, and vary n.

    likelihood = unidpdf(5, 4:9)

    likelihood =

             0     0.2000     0.1667     0.1429     0.1250     0.1111

**See Also**    pdf, unidcdf, unidinv, unidrnd, unidstat

**Purpose**        Random numbers from the discrete uniform distribution.

**Syntax**         R = unidrnd(N)
                   R = unidrnd(N, mm)
                   R = unidrnd(N, mm, nn)

**Description**    The discrete uniform distribution arises from experiments equivalent to
                   drawing a number from one to N out of a hat.

                   R = unidrnd(N) generates discrete uniform random numbers with
                   maximum N. The parameters in N must be positive integers. The size of R is the
                   size of N.

                   R = unidrnd(N, mm) generates discrete uniform random numbers with
                   maximum N, where mm is a 1-by-2 vector that contains the row and column
                   dimensions of R.

                   R = unidrnd(N, mm, nn) generates discrete uniform random numbers with
                   maximum N, where scalars mm and nn are the row and column dimensions of R.

**Examples**       In the Massachusetts lottery, a player chooses a four digit number. Generate
                   random numbers for Monday through Saturday.

                   numbers = unidrnd(10000, 1, 6) - 1

                   numbers =

                           2189          470         6788         6792         9346

**See Also**       unidcdf, unidinv, unidpdf, unidstat

# unidstat

| | |
|---|---|
| **Purpose** | Mean and variance for the discrete uniform distribution. |
| **Syntax** | [M, V] = unidstat(N) |
| **Description** | [M, V] = unidstat(N) returns the mean and variance for the discrete uniform distribution with parameter N. |
| | The mean of the discrete uniform distribution with parameter $N$ is $(N+1)/2$. The variance is $(N^2-1)/12$. |

**Examples**

```
[m, v] = unidstat(1:6)

m =
    1.0000    1.5000    2.0000    2.5000    3.0000    3.5000

v =
         0    0.2500    0.6667    1.2500    2.0000    2.9167
```

**See Also**    unidcdf, unidinv, unidpdf, unidrnd

**Purpose**    Continuous uniform cumulative distribution function (cdf).

**Syntax**    P = unifcdf(X, A, B)

**Description**    P = unifcdf(X, A, B) computes the uniform cdf at each of the values in X using the corresponding parameters in A and B (the minimum and maximum values, respectively). Vector or matrix inputs for X, A, and B must all have the same size. A scalar input is expanded to a constant matrix with the same dimensions as the other inputs.

The uniform cdf is

$$p = F(x|a, b) = \frac{x - a}{b - a} I_{[a, b]}(x)$$

The standard uniform distribution has A = 0 and B = 1.

**Examples**    What is the probability that an observation from a standard uniform distribution will be less than 0.75?

    probability = unifcdf(0.75)

    probability =

        0.7500

What is the probability that an observation from a uniform distribution with a = -1 and b = 1 will be less than 0.75?

    probability = unifcdf(0.75, -1, 1)

    probability =

        0.8750

**See Also**    cdf, unifinv, unifit, unifpdf, unifrnd, unifstat

# unifinv

**Purpose**        Inverse continuous uniform cumulative distribution function (cdf).

**Syntax**         X = unifinv(P, A, B)

**Description**    X = unifinv(P, A, B) computes the inverse of the uniform cdf with parameters
                   A and B (the minimum and maximum values, respectively) at the corresponding
                   probabilities in P. Vector or matrix inputs for P, A, and B must all have the same
                   size. A scalar input is expanded to a constant matrix with the same dimensions
                   as the other inputs.

                   The inverse of the uniform cdf is

                   $$x = F^{-1}(p|a, b) = a + p(a - b)I_{[0, 1]}(p)$$

                   The standard uniform distribution has A = 0 and B = 1.

**Examples**       What is the median of the standard uniform distribution?

                       median_value = unifinv(0.5)

                       median_value =

                           0.5000

                   What is the 99th percentile of the uniform distribution between -1 and 1?

                       percentile = unifinv(0.99, -1, 1)

                       percentile =

                           0.9800

**See Also**       icdf, unifcdf, unifit, unifpdf, unifrnd, unifstat

**Purpose**        Parameter estimates for uniformly distributed data.

**Syntax**         [ahat, bhat] = unifit(X)
                   [ahat, bhat, ACI, BCI] = unifit(X)
                   [ahat, bhat, ACI, BCI] = unifit(X, alpha)

**Description**    [ahat, bhat] = unifit(X) returns the maximum likelihood estimates (MLEs)
                   of the parameters of the uniform distribution given the data in X.

                   [ahat, bhat, ACI, BCI] = unifit(X) also returns 95% confidence intervals,
                   ACI and BCI, which are matrices with two rows. The first row contains the
                   lower bound of the interval for each column of the matrix X. The second row
                   contains the upper bound of the interval.

                   [ahat, bhat, ACI, BCI] = unifit(X, alpha) allows control of the confidence
                   level alpha. For example, if alpha = 0.01 then ACI and BCI are 99% confidence
                   intervals.

**Example**        r = unifrnd(10, 12, 100, 2);
                   [ahat, bhat, aci, bci] = unifit(r)

                   ahat =

                       10.0154    10.0060

                   bhat =

                       11.9989    11.9743

                   aci =

                        9.9551     9.9461
                       10.0154    10.0060

                   bci =

                       11.9989    11.9743
                       12.0592    12.0341

**See Also**       betafit, binofit, expfit, gamfit, normfit, poissfit, unifcdf, unifinv,
                   unifpdf, unifrnd, unifstat, weibfit

# unifpdf

**Purpose**        Continuous uniform probability density function (pdf).

**Syntax**         Y = unifpdf(X, A, B)

**Description**    Y = unifpdf(X, A, B) computes the continuous uniform pdf at each of the
                   values in X using the corresponding parameters in A and B. Vector or matrix
                   inputs for X, A, and B must all have the same size. A scalar input is expanded
                   to a constant matrix with the same dimensions as the other inputs. The
                   parameters in B must be greater than those in A.

                   The continuous uniform distribution pdf is

$$y = f(x|a, b) = \frac{1}{b-a}I_{[a, b]}(x)$$

                   The standard uniform distribution has A = 0 and B = 1.

**Examples**       For fixed a and b, the uniform pdf is constant.

```
x = 0.1:0.1:0.6;
y = unifpdf(x)

y =
      1     1     1     1     1     1
```

                   What if x is not between a and b?

```
y = unifpdf(-1, 0, 1)

y =
      0
```

**See Also**       pdf, unifcdf, unifinv, unifrnd, unifstat

**Purpose**    Random numbers from the continuous uniform distribution.

**Syntax**    R = unifrnd(A, B)
R = unifrnd(A, B, m)
R = unifrnd(A, B, m, n)

**Description**    R = unifrnd(A, B) generates uniform random numbers with parameters A and B. Vector or matrix inputs for A and B must have the same size, which is also the size of R. A scalar input for A or B is expanded to a constant matrix with the same dimensions as the other input.

R = unifrnd(A, B, m) generates uniform random numbers with parameters A and B, where m is a 1-by-2 vector that contains the row and column dimensions of R.

R = unifrnd(A, B, m, n) generates uniform random numbers with parameters A and B, where scalars m and n are the row and column dimensions of R.

**Examples**    random = unifrnd(0, 1:6)

random =

   0.2190    0.0941    2.0366    2.7172    4.6735    2.3010

random = unifrnd(0, 1:6, [1 6])

random =

   0.5194    1.6619    0.1037    0.2138    2.6485    4.0269

random = unifrnd(0, 1, 2, 3)

random =

   0.0077    0.0668    0.6868
   0.3834    0.4175    0.5890

**See Also**    unifcdf, unifinv, unifpdf, unifstat

# unifstat

**Purpose**         Mean and variance for the continuous uniform distribution.

**Syntax**          [M, V] = unifstat(A, B)

**Description**     [M, V] = unifstat(A, B) returns the mean and variance for the continuous
                    uniform distribution with parameters specified by A and B. Vector or matrix
                    inputs for A and B must have the same size, which is also the size of M and V. A
                    scalar input for A or B is expanded to a constant matrix with the same
                    dimensions as the other input.

                    The mean of the continuous uniform distribution with parameters *a* and *b* is
                    $(a + b)/2$, and the variance is $(b - a)^2/12$.

**Examples**        a = 1:6;
                    b = 2.*a;
                    [m, v] = unifstat(a, b)

                    m =
                        1.5000      3.0000      4.5000      6.0000      7.5000      9.0000

                    v =
                        0.0833      0.3333      0.7500      1.3333      2.0833      3.0000

**See Also**        unifcdf, unifinv, unifpdf, unifrnd

**Purpose**     Variance of a sample.

**Syntax**
y = var(X)
y = var(X, 1)
y = var(X, w)

**Description**     y = var(X) computes the variance of the data in X. For vectors, var(x) is the variance of the elements in x. For matrices, var(X) is a row vector containing the variance of each column of X.

y = var(x) normalizes by $n$-1 where $n$ is the sequence length. For normally distributed data, this makes var(x) the minimum variance unbiased estimator MVUE of $\sigma^2$ (the second parameter).

y = var(x, 1) normalizes by $n$ and yields the second moment of the sample data about its mean (moment of inertia).

y = var(X, w) computes the variance using the vector of positive weights w. The number of elements in w must equal the number of rows in the matrix X. For vector x, w and x must match in length.

var supports both common definitions of variance. Let *SS* be the sum of the squared deviations of the elements of a vector x from their mean. Then, var(x) = $SS/(n\text{-}1)$ is the MVUE, and var(x, 1) = $SS/n$ is the maximum likelihood estimator (MLE) of $\sigma^2$.

# var

**Examples**
```
x = [-1 1];
w = [1 3];
v1 = var(x)

v1 =
     2

v2 = var(x, 1)

v2 =
     1

v3 = var(x, w)

v3 =
    0.7500
```

**See Also**        cov, std

**Purpose**       Weibull cumulative distribution function (cdf).

**Syntax**        P = weibcdf(X, A, B)

**Description**   P = weibcdf(X, A, B) computes the Weibull cdf at each of the values in X using
the corresponding parameters in A and B. Vector or matrix inputs for X, A, and
B must all have the same size. A scalar input is expanded to a constant matrix
with the same dimensions as the other inputs. The parameters in A and B must
be positive.

The Weibull cdf is

$$p = F(x|a, b) = \int_0^x abt^{b-1} e^{-at^b} dt = 1 - e^{-ax^b} I_{(0, \infty)}(x)$$

**Examples**      What is the probability that a value from a Weibull distribution with
parameters a = 0.15 and b = 0.24 is less than 500?

    probability = weibcdf(500, 0.15, 0.24)

    probability =

        0.4865

How sensitive is this result to small changes in the parameters?

    [A, B] = meshgrid(0.1:0.05:0.2, 0.2:0.05:0.3);
    probability = weibcdf(500, A, B)

    probability =

        0.2929    0.4054    0.5000
        0.3768    0.5080    0.6116
        0.4754    0.6201    0.7248

**See Also**      cdf, weibfit, weibinv, weiblike, weibpdf, weibplot, weibrnd, weibstat

# weibfit

**Purpose**    Parameter estimates and confidence intervals for Weibull data.

**Syntax**
```
phat = weibfit(x)
[phat, pci] = weibfit(x)
[phat, pci] = weibfit(x, alpha)
```

**Description**    phat = weibfit(x) returns the maximum likelihood estimates, phat, of the parameters of the Weibull distribution given the values in vector x, which must be positive. phat is a two-element row vector: phat(1) estimates the Weibull parameter *a*, and phat(2) estimates the Weibull parameter *b* in the pdf

$$y = f(x|a, b) = abx^{b-1}e^{-ax^b}I_{(0, \infty)}(x)$$

[phat, pci] = weibfit(x) also returns 95% confidence intervals in the two-row matrix pci. The first row contains the lower bound of the confidence interval, and the second row contains the upper bound. The columns of pci correspond to the columns of phat.

[phat, pci] = weibfit(x, alpha) allows control over the confidence interval returned, 100(1-alpha)%.

**Example**
```
r = weibrnd(0.5, 0.8, 100, 1);
[phat, pci] = weibfit(r)

phat =

    0.4746    0.7832

pci =

    0.3851    0.6367
    0.5641    0.9298
```

**See Also**    betafit, binofit, expfit, gamfit, normfit, poissfit, unifit, weibcdf, weibinv, weiblike, weibpdf, weibplot, weibrnd, weibstat

**Purpose**        Inverse of the Weibull cumulative distribution function.

**Syntax**         X = weibinv(P, A, B)

**Description**    X = weibinv(P, A, B) computes the inverse of the Weibull cdf with parameters
                   A and B for the corresponding probabilities in P. Vector or matrix inputs for P,
                   A, and B must all have the same size. A scalar input is expanded to a constant
                   matrix with the same dimensions as the other inputs. The parameters in A and
                   B must be positive.

                   The inverse of the Weibull cdf is

$$x = F^{-1}(p|a, b) = \left[\frac{1}{a}\ln\left(\frac{1}{1-p}\right)\right]^{\frac{1}{b}} I_{[0, 1]}(p)$$

**Examples**       A batch of light bulbs have lifetimes (in hours) distributed Weibull with
                   parameters a = 0.15 and b = 0.24. What is the median lifetime of the bulbs?

                       life = weibinv(0.5, 0.15, 0.24)

                       life =

                          588.4721

                   What is the 90th percentile?

                       life = weibinv(0.9, 0.15, 0.24)

                       life =

                          8.7536e+04

**See Also**       icdf, weibcdf, weibfit, weiblike, weibpdf, weibplot, weibrnd, weibstat

# weiblike

**Purpose**    Weibull negative log-likelihood function.

**Syntax**

logL = weiblike(params, data)
[logL, avar] = weiblike(params, data)

**Description**    logL = weiblike(params, data) returns the Weibull log-likelihood with parameters params(1) = $a$ and params(2) = $b$ given the data $x_i$.

[logL, avar] = weiblike(params, data) also returns avar, which is the asymptotic variance-covariance matrix of the parameter estimates if the values in params are the maximum likelihood estimates. avar is the inverse of Fisher's information matrix. The diagonal elements of avar are the asymptotic variances of their respective parameters.

The Weibull negative log-likelihood is

$$-\log L = -\log \prod_{i=1}^{n} f(a, b|x_i) = -\sum_{i=1}^{n} \log f(a, b|x_i)$$

weiblike is a utility function for maximum likelihood estimation.

**Example**    This example continues the example from weibfit.

```
r = weibrnd(0.5, 0.8, 100, 1);
[logL, info] = weiblike([0.4746 0.7832], r)

logL =

   203.8216

info =

     0.0021     0.0022
     0.0022     0.0056
```

**Reference**    Patel, J. K., C. H. Kapadia, and D. B. Owen, *Handbook of Statistical Distributions,* Marcel-Dekker, 1976.

**See Also**    betalike, gamlike, mle, weibcdf, weibfit, weibinv, weibpdf, weibplot, weibrnd, weibstat

**Purpose**        Weibull probability density function (pdf).

**Syntax**         Y = weibpdf(X, A, B)

**Description**    Y = weibpdf(X, A, B) computes the Weibull pdf at each of the values in X using
                   the corresponding parameters in A and B. Vector or matrix inputs for X, A, and
                   B must all have the same size. A scalar input is expanded to a constant matrix
                   with the same dimensions as the other input. The parameters in A and B must
                   all be positive.

                   The Weibull pdf is

$$y = f(x|a, b) = abx^{b-1}e^{-ax^b}I_{(0, \infty)}(x)$$

                   Some references refer to the Weibull distribution with a single parameter. This
                   corresponds to weibpdf with A = 1.

**Examples**       The exponential distribution is a special case of the Weibull distribution.

```
lambda = 1:6;
y = weibpdf(0.1:0.1:0.6, lambda, 1)

y =

    0.9048    1.3406    1.2197    0.8076    0.4104    0.1639

y1 = exppdf(0.1:0.1:0.6, 1./lambda)

y1 =

    0.9048    1.3406    1.2197    0.8076    0.4104    0.1639
```

**Reference**      Devroye, L., *Non-Uniform Random Variate Generation*. Springer-Verlag. New
                   York, 1986.

**See Also**       pdf, weibcdf, weibfit, weibinv, weiblike, weibplot, weibrnd, weibstat

# weibplot

**Purpose**        Weibull probability plot.

**Syntax**        weibplot(X)
h = weibplot(X)

**Description**        weibplot(X) displays a Weibull probability plot of the data in X. If X is a matrix, weibplot displays a plot for each column.

h = weibplot(X) returns handles to the plotted lines.

The purpose of a Weibull probability plot is to graphically assess whether the data in X could come from a Weibull distribution. If the data are Weibull the plot will be linear. Other distribution types may introduce curvature in the plot.

**Example**        r = weibrnd(1.2, 1.5, 50, 1);
weibplot(r)
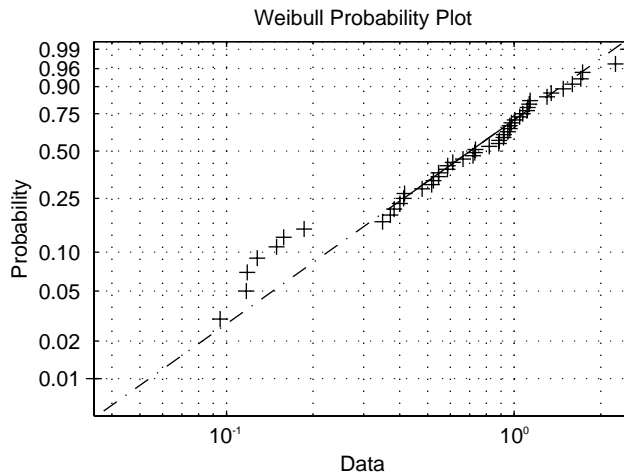


**See Also**        normplot, weibcdf, weibfit, weibinv, weiblike, weibpdf, weibrnd, weibstat

**Purpose**        Random numbers from the Weibull distribution.

**Syntax**         R = weibrnd(A, B)
                   R = weibrnd(A, B, m)
                   R = weibrnd(A, B, m, n)

**Description**    R = weibrnd(A, B) generates Weibull random numbers with parameters A
                   and B. Vector or matrix inputs for A and B must have the same size, which is
                   also the size of R. A scalar input for A or B is expanded to a constant matrix with
                   the same dimensions as the other input.

                   R = weibrnd(A, B, m) generates Weibull random numbers with parameters A
                   and B, where m is a 1-by-2 vector that contains the row and column dimensions
                   of R.

                   R = weibrnd(A, B, m, n) generates Weibull random numbers with parameters
                   A and B, where scalars m and n are the row and column dimensions of R.

                   Devroye refers to the Weibull distribution with a single parameter; this is
                   weibrnd with A = 1.

**Examples**       n1 = weibrnd(0.5:0.5:2, 0.5:0.5:2)

                   n1 =
                       0.0093      1.5189      0.8308      0.7541

                   n2 = weibrnd(1/2, 1/2, [1 6])

                   n2 =
                       29.7822     0.9359      2.1477     12.6402      0.0050      0.0121

**Reference**      Devroye, L., *Non-Uniform Random Variate Generation*. Springer-Verlag. New
                   York, 1986.

**See Also**       weibcdf, weibfit, weibinv, weiblike, weibpdf, weibplot, weibstat

# weibstat

| | |
|---|---|
| **Purpose** | Mean and variance for the Weibull distribution. |
| **Syntax** | [M, V] = weibstat(A, B) |

**Description**  [M, V] = weibstat(A, B) returns the mean and variance for the Weibull distribution with parameters specified by A and B. Vector or matrix inputs for A and B must have the same size, which is also the size of M and V. A scalar input for A or B is expanded to a constant matrix with the same dimensions as the other input.

The mean of the Weibull distribution with parameters $a$ and $b$ is

$$a^{-\frac{1}{b}}\Gamma(1 + b^{-1})$$

and the variance is

$$a^{-\frac{2}{b}}\left[\Gamma(1 + 2b^{-1}) - \Gamma^2(1 + b^{-1})\right]$$

**Examples**

```
[m, v] = weibstat(1: 4, 1: 4)

m =
    1.0000     0.6267     0.6192     0.6409

v =
    1.0000     0.1073     0.0506     0.0323

weibstat(0.5, 0.7)

ans =

    3.4073
```

**See Also**   weibcdf, weibfit, weibinv, weiblike, weibpdf, weibplot, weibrnd

| | |
|---|---|
| **Purpose** | Transform a factor settings matrix to a design matrix. |
| **Syntax** | D = x2fx(X) |
| | D = x2fx(X, '*model*') |
| **Description** | D = x2fx(X) transforms a matrix of system inputs, X, to a design matrix for a linear additive model with a constant term. |

D = x2fx(X, '*model*') allows control of the order of the regression model. '*model*' can be one of these strings:

- 'interaction' – includes constant, linear, and cross product terms
- 'quadratic' – includes interactions and squared terms
- 'purequadratic' – includes constant, linear, and squared terms

Alternatively *model* can be a matrix of terms. In this case, each row of model represents one term. The value in a column is the exponent to which the same column in X for that term should be raised. This allows for models with polynomial terms of arbitrary order.

x2fx is a utility function for rstool, regstats, and cordexch.

**Example**

```
x = [1 2 3;4 5 6]';  model = 'quadratic';
D = x2fx(x,model)

D =

     1     1     4     4     1    16
     1     2     5    10     4    25
     1     3     6    18     9    36
```

Let $x_1$ be the first column of x and $x_2$ be the second. Then the first column of D is the constant term, the second column is $x_1$, the third column is $x_2$, the fourth column is $x_1 x_2$, the fifth column is $x_1^2$, and the last columns is $x_2^2$.

**See Also**  rstool, cordexch, rowexch, regstats

# xbarplot

**Purpose**
X-bar chart for Statistical Process Control.

**Syntax**
xbarplot(DATA)
xbarplot(DATA, conf)
xbarplot(DATA, conf, specs, '*sigmaest*')
[outlier, h] = xbarplot(...)

**Description**
xbarplot(DATA) displays an x-bar chart of the grouped responses in DATA. The rows of DATA contain replicate observations taken at a given time, and must be in time order. The graph contains the sample mean $\bar{x}$ for each group, a center line at the average $\bar{x}$ value, and upper and lower control limits. The limits are placed at a three-sigma distance on either side of the center line, where sigma is an estimate of the standard deviation of $\bar{x}$. If the process is in control, fewer than 3 out of 1000 observations would be expected to fall outside the control limits by random chance. So if you observe points outside the limits, you can take this as evidence that the process is not in control.

xbarplot(DATA, conf) allows control of the confidence level of the upper and lower plotted confidence limits. The default conf = 0.9973 produces three-sigma limits.

    norminv(1 - (1-.9973)/2)

    ans =
             3

To get *k*-sigma limits, use the expression 1-2*(1-normcdf(k)). For example, the correct conf value for 2-sigma limits is 0.9545, as shown below.

    k = 2;
    1-2*(1-normcdf(k))

    ans =
          0.9545

xbarplot(DATA, conf, specs) plots the specification limits in the two element vector specs.

xbarplot(DATA, conf, specs, '*sigmaest*') specifies how xbarplot should estimate the standard deviation. Acceptable values are:

- 's' – use the average of the group standard deviations (default)
- 'v' – use the square root of a pooled variance estimate
- 'r' – use the average range with each group; requires 25 or fewer observations per group

[outlier, h] = xbarplot(DATA, conf, specs) returns outlier, a vector of indices to the rows where the mean of DATA is out of control, and h, a vector of handles to the plotted lines.

**Example**    Plot an x-bar chart of measurements on newly machined parts, taken at one hour intervals for 36 hours. Each row of the runout matrix contains the measurements for four parts chosen at random. The values indicate, in thousandths of an inch, the amount the part radius differs from the target radius.

```
load parts
xbarplot(runout, 0.999, [-0.5 0.5])
```
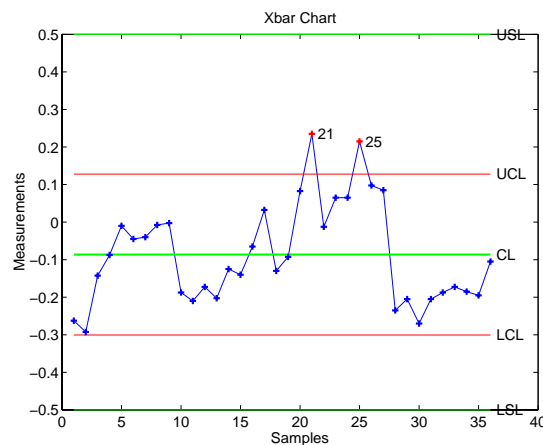


The points in groups 21 and 25 are out of control, so the mean in those groups was higher than would be expected by random chance alone. There is evidence that the process was not in control when those measurements were collected.

# xbarplot

**See Also**   capaplot, histfit, ewmaplot, schart

**Purpose**        Standardized Z score.

**Syntax**         Z = zscore(D)

**Description**    Z = zscore(D) returns the deviation of each column of D from its mean, normalized by its standard deviation. This is known as the Z score of D.

For column vector V, the Z score is Z = (V-mean(V))./std(V).

# ztest

**Purpose**    Hypothesis testing for the mean of one sample with known variance.

**Syntax**    h = ztest(x, m, sigma)
h = ztest(x, m, sigma, alpha)
[h, sig, ci, zval] = ztest(x, m, sigma, alpha, tail)

**Description**    h = ztest(x, m, sigma) performs a Z test at significance level 0.05 to determine whether a sample x from a normal distribution with standard deviation sigma could have mean m.

h = ztest(x, m, sigma, alpha) gives control of the significance level alpha. For example, if alpha = 0.01 and the result is h = 1, you can reject the null hypothesis at the significance level 0.01. If h = 0, you cannot reject the null hypothesis at the alpha level of significance.

[h, sig, ci] = ztest(x, m, sigma, alpha, tail) allows specification of one- or two-tailed tests, where tail is a flag that specifies one of three alternative hypotheses:

- tail = 0 specifies the alternative $\bar{x} \neq m$ (default)
- tail = 1 specifies the alternative $\bar{x} > m$
- tail = -1 specifies the alternative $\bar{x} < m$

zval is the value of the Z statistic

$$z = \frac{\bar{x} - m}{\sigma / \sqrt{n}}$$

where $n$ is the number of observations in the sample.

sig is the probability that the observed value of Z could be as large or larger *by chance* under the null hypothesis that the mean of *x* is equal to *m*.

ci is a 1-alpha confidence interval for the true mean.

**Example**    This example generates 100 normal random numbers with theoretical mean zero and standard deviation one. The observed mean and standard deviation are different from their theoretical values, of course. We test the hypothesis that there is no true difference.

```
x = normrnd(0, 1, 100, 1);
m = mean(x)
m =
    0.0727

[h, sig, ci] = ztest(x, 0, 1)

h =
    0

sig =
    0.4669

ci =
    -0.1232    0.2687
```

The result, h = 0, means that we cannot reject the null hypothesis. The significance level is 0.4669, which means that by chance we would have observed values of Z more extreme than the one in this example in 47 of 100 similar experiments. A 95% confidence interval on the mean is [-0.1232 0.2687], which includes the theoretical (and hypothesized) mean of zero.

# ztest

# Index

## X

## Z